



## On $(\alpha, \psi)$ - $K$ -Contractions in the Extended $b$ -Metric Space

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**Abstract.** In this paper, we introduce a notion of  $(\alpha, \psi)$ - $K$ -contraction in the setting of extended  $b$ -metric spaces and investigate the existence of a fixed point. The presented results generalize and unify a number of well-known fixed point theorem mainly in two distinct aspects; in the sense of the contraction conditions and in the frame of abstract spaces.

### 1. Introduction and Preliminaries

In 1993, Czerwik [16] suggested a successful and proper generalization of the metric space notion by introducing the concepts of  $b$ -metric space. In this paper, the author examine the basic topological properties of this new space and investigate the existence and uniqueness of certain mappings in framework of  $b$ -metric space. Following this famous result in the setting of  $b$ -metric space, a number of authors have reported several interesting results in this direction (see e.g. [2, 6–8],[11]–[14] and related references therein). Very recently, Kamran *et al.* [18] extend the  $b$ -metric space and successfully prove the analog of Banach mapping principle in this new space.

In this paper, we shall define a general contraction condition by the help of some auxiliary functions and investigate the existence and uniqueness of a fixed point for such mappings.

Throughout the manuscript, we denote  $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$  where  $\mathbb{N}$  is the positive integers. Further,  $\mathbb{R}$  represent the real numbers and  $\mathbb{R}_0^+ := [0, \infty)$ .

We, first, recall the notion of  $b$ -metric.

**Definition 1.1 (Czerwik [16]).** Let  $X$  be a nonempty set and  $d : X \times X \rightarrow [0, \infty)$  be a function satisfying the following conditions:

- (b1)  $d(x, y) = 0$  if and only if  $x = y$ .
- (b2)  $d(x, y) = d(y, x)$  for all  $x, y \in X$ .
- (b3)  $d(x, y) \leq s[d(x, z) + d(z, y)]$  for all  $x, y, z \in X$ , where  $s \geq 1$ .

The function  $d$  is called a  $b$ -metric and the space  $(X, d)$  is called a  $b$ -metric space, in short,  $bMS$ .

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The immediate examples of  $b$ -metric are the following (see also [2, 6–8],[11]-[14].)

**Example 1.2.** Let  $X = \mathbb{R}^2$ . Then, the functional  $d : X \times X \rightarrow [0, \infty)$  defined by:

$$d((x_1, y_1), (x_2, y_2)) := \begin{cases} |x_1 - x_2| + |y_1 - y_2|, & ((x_1, y_1), (x_2, y_2)) \in [0, 1] \times [0, 1] \\ |x_1 - x_2|^2 + |y_1 - y_2|^2, & ((x_1, y_1), (x_2, y_2)) \in (1, \infty) \times (1, \infty) \\ 0, & \text{otherwise.} \end{cases}$$

It is a  $b$ -metric on  $X$  with coefficient  $s = 2$ .

**Example 1.3.** The space  $L^p[0, 1]$  (where  $0 < p < 1$ ) of all real functions  $x(t), t \in [0, 1]$  such that  $\int_0^1 |x(t)|^p dt < \infty$ , together with the functional

$$d(x, y) := \left( \int_0^1 |x(t) - y(t)|^p dt \right)^{1/p}, \text{ for each } x, y \in L^p[0, 1],$$

is a  $b$ -metric space. Notice that  $s = 2^{1/p}$ .

**Example 1.4.** Let  $X = \{a, b, c\}$  and  $d : X \times X \rightarrow \mathbb{R}_+$  such that  $d(a, b) = d(b, a) = d(a, c) = d(c, a) = b, d(b, c) = d(c, b) = \alpha \geq c, d(a, a) = d(b, b) = d(c, c) = a$ . Then

$$d(x, y) \leq \frac{\alpha}{2} [d(x, z) + d(z, y)], \text{ for } x, y, z \in X.$$

Then  $(X, d)$  is a  $b$ -metric space. If  $\alpha > c$  the ordinary triangle inequality does not hold and  $(X, d)$  is not a metric space.

**Remark 1.5.** It is clear that for  $s = 1$ , the  $b$ -metric becomes a usual metric.

In what follows, we recollect the notion of extend the  $b$ -metric space that is defined by Kamran et al. [18]

**Definition 1.6.** [18] Let  $X$  be a non empty set and  $\theta : X \times X \rightarrow [1, \infty)$ . A function  $d_\theta : X \times X \rightarrow [0, \infty)$  is called an extended  $b$ -metric if for all  $x, y, z \in X$  is satisfies

( $d_\theta 1$ )  $d_\theta(x, y) = 0$  if and only if  $x = y$ ;

( $d_\theta 2$ )  $d_\theta(x, y) = d_\theta(y, x)$ ;

( $d_\theta 3$ )  $d_\theta(x, z) \leq \theta(x, z) [d_\theta(x, y) + d_\theta(y, z)]$ .

The pair  $(X, d_\theta)$  is called an extended  $b$ -metric space, in short extended- $bMS$ .

**Remark 1.7.** If  $\theta(x, y) = s$ , for  $s \geq 1$  then we obtain the definition of  $bMS$ .

**Example 1.8.** Let  $X = \{a, b, c\} \cup \mathbb{R}_0^+$  and  $d : X \times X \rightarrow [0, \infty)$  be defined by

Case 1. if  $x, y \in \mathbb{R}_0^+$  then  $d_\theta(x, y) = |x - y|^2$ ,

Case 2. if  $x \in \{a, b, c\}$  and  $y \in \mathbb{R}_0^+$  then  $d_\theta(x, y) = 1 = d_\theta(y, x)$  and  $d_\theta(x, x) = 0$ ,

Case 3. if  $x, y \in \{a, b, c\}$

$$d_\theta(a, b) = 1, \quad d_\theta(a, c) = \frac{1}{2} \quad \text{and} \quad d_\theta(b, c) = 2,$$

with  $d_\theta(x, x) = 0$  and  $d_\theta(x, y) = d_\theta(y, x)$ .

Notice that  $d$  is not a metric since  $d_\theta(b, c) > d_\theta(b, a) + d_\theta(a, c)$ . However, it is easy to see that  $d$  is a extended  $b$ -metric space. Indeed, for the following  $\theta : X \times X \rightarrow [1, \infty)$ , we conclude the desired result.

$$\theta(x, y) = \begin{cases} 2 & \text{if } x, y \in \mathbb{R}_0^+, \\ \frac{4}{3} & \text{if } x, y \in \{a, b, c\}, \\ 1 & \text{if } (x, y) \text{ or } (y, x) \in \{a, b, c\} \times \mathbb{R}_0^+. \end{cases} \tag{1}$$

**Example 1.9.** Let  $X = \{x, y, z\}$  and  $\theta : X \times X \rightarrow [1, \infty)$ ,  $\theta(x, y) = |x| + |y| + 2$ . Define  $d_\theta : X \times X \rightarrow [0, \infty)$  as

$$d_\theta(x, y) = d_\theta(y, x) = 5, d_\theta(x, z) = d_\theta(z, x) = 3, d_\theta(y, z) = d_\theta(z, y) = 1,$$

$$d_\theta(x, x) = d_\theta(y, y) = d_\theta(z, z) = 0.$$

Obviously,  $(d_\theta 1)$  and  $(d_\theta 2)$  hold. For  $(d_\theta 3)$ , we have

$$5 = d_\theta(x, y) \leq \theta(x, y)(d_\theta(x, z) + d_\theta(z, y)) = (|x| + |y| + 2) \cdot 4,$$

$$3 = d_\theta(x, z) \leq \theta(x, z)(d_\theta(x, y) + d_\theta(y, z)) = (|x| + |z| + 2) \cdot 6,$$

$$1 = d_\theta(y, z) \leq \theta(y, z)(d_\theta(y, x) + d_\theta(x, z)) = (|y| + |z| + 2) \cdot 8,$$

In conclusion, for any  $x, y, z \in X$ ,

$$d_\theta(x, z) \leq \theta(x, z) [d_\theta(x, y) + d_\theta(y, z)].$$

Hence,  $(X, d_\theta)$  is an extended  $b$ -metric space. Notice also that

$$5 = d_\theta(x, y) > 4 = d_\theta(x, z) + d_\theta(z, y),$$

thus the standard triangle inequality does not hold in this case and  $(X, d)$  is not a metric space.

In what follows that we recollect some basic concepts, for instance, convergence, notion of the Cauchy sequence, and completeness in a extended- $b$ MS. For more details, see e.g. [18].

**Definition 1.10.** [18] Let  $(X, d_\theta)$  be an extended- $b$ MS.

- (i) A sequence  $x_n$  in  $X$  is said to converge to  $x \in X$ , if for every  $\epsilon > 0$  there exists  $N = N(\epsilon) \in \mathbb{N}$  such that  $d_\theta(x_n, x) < \epsilon$ , for all  $n \geq N$ . In this case, we write  $\lim_{n \rightarrow \infty} x_n = x$ .
- (ii) A sequence  $x_n$  in  $X$  is said to be Cauchy if for every  $\epsilon > 0$  there exists  $N = N(\epsilon) \in \mathbb{N}$  such that  $d_\theta(x_m, x_n) < \epsilon$ , for all  $m, n \geq N$ .

**Definition 1.11.** An extended- $b$ metric space  $(X, d_\theta)$  is complete if every Cauchy sequence in  $X$  is convergent.

**Lemma 1.12.** Let  $(X, d_\theta)$  be an complete extended- $b$ MS. If  $d_\theta$  is continuous, then every convergent sequence has a unique limit.

**Theorem 1.13.** [18] Let  $(X, d_\theta)$  be an extended- $b$ MS such that  $d_\theta$  is a continuous functional. Let  $T : X \rightarrow X$  satisfy:

$$d_\theta(Tx, Ty) \leq kd_\theta(x, y) \tag{2}$$

for all  $x, y \in X$ , where  $k \in [0, 1)$  be such that for each  $x_0 \in X$ ,  $\lim_{n, m \rightarrow \infty} \theta(x_n, x_m) < \frac{1}{k}$ , here  $x_n = T^n x_0$ ,  $n = 1, 2, \dots$ . Then  $T$  has precisely one fixed point  $u$ . Moreover for each  $y \in X$ ,  $T^n y \rightarrow u$ .

For our purposes, we need to recall the following definition of  $\alpha$ -orbital admissible mappings given by Popescu [29]

**Definition 1.14.** Let  $T : X \rightarrow X$  and  $\alpha : X \times X \rightarrow [0, \infty)$ . We say that  $T$  is an  $\alpha$ -orbital admissible if for all  $x, y \in X$  we have

$$\alpha(x, Tx) \geq 1 \Rightarrow \alpha(Tx, T^2x) \geq 1. \tag{3}$$

**Remark 1.15.** Each  $\alpha$ -admissible mapping is an  $\alpha$ -orbital admissible mapping.(see [29]).

Let  $\Phi$  be the family of functions  $\psi : [0, \infty) \rightarrow [0, \infty)$  satisfying the following conditions:

- $(\Phi_1)$   $\phi$  is nondecreasing;
- $(\Phi_2)$   $\phi(t) < t$ .

2. Main results

We start with the definition of  $(\alpha, \psi)$ -K-contraction.

**Definition 2.1.** Let  $(X, d)$  be an extended b-metric space  $\alpha : X \times X \rightarrow [0, \infty)$  and  $\theta : X \times X \rightarrow [1, \infty)$ . A mapping  $T : X \rightarrow X$  is called  $(\alpha, \psi)$ -K-contraction if it satisfies

$$\alpha(x, y)d_\theta(Tx, Ty) \leq \phi(K(x, y)), \text{ for all } x, y \in X, \tag{4}$$

where  $\phi \in \Phi$  and

$$K(x, y) = \max\{d_\theta(x, y), d_\theta(x, Tx), d_\theta(y, Ty), \frac{d_\theta(x, Tx)d_\theta(y, Ty)}{d_\theta(x, y)}, \frac{d_\theta(x, Ty) + d_\theta(y, Tx)}{2 \max\{\theta(y, Tx), \theta(x, Ty)\}}\}. \tag{5}$$

The following is the first main result of this paper.

**Theorem 2.2.** Let  $(X, d)$  be a complete extended b-metric space and  $T : X \rightarrow X$  be a  $(\alpha, \psi)$ -K-contraction mapping. Suppose that for each  $x_0 \in X$  and for each  $t > 0$ ,

$$\limsup_{n,m \rightarrow \infty} \frac{\phi^{n+1}(t)}{\phi^n(t)} \theta(x_n, x_m) < 1$$

where  $x_n = T^n x_0, n \in \mathbb{N}$ . Suppose also that

- (i)  $T$  is  $\alpha$ -orbital admissible,
- (ii) there exists  $x_0 \in X$  such that  $\alpha(x_0, Tx_0) \geq 1$
- (iii)  $T$  is continuous.

Then the mappings  $T$  posses a fixed point  $u$ , that is,  $Tu = u$ .

*Proof.* By assumption, for a given  $x_0 \in X$ , we have a constructive sequence  $\{x_n\}$  that is defined by  $x_n = T^n x_0$  for each  $n \in \mathbb{N}$ . If for some  $n_0$ , we have  $x_{n_0} = x_{n_0+1} = Tx_{n_0}$ , then  $x_{n_0}$  is a fixed point of  $T$ . From now on, we assume that  $x_n \neq x_{n+1}$  for all  $n \geq 0$ . Since  $T$  is  $\alpha$ -admissible, we have

$$\alpha(x_0, x_1) = \alpha(x_0, Tx_0) \geq 1 \Rightarrow \alpha(Tx_0, Tx_1) = \alpha(x_1, x_2) \geq 1.$$

Recursively, we find that

$$\alpha(x_n, x_{n+1}) \geq 1, \text{ for all } n = 0, 1, \dots \tag{6}$$

On account of (6) and (4), we have

$$d_\theta(x_n, x_{n+1}) = d_\theta(Tx_{n-1}, Tx_n) \leq \phi(M(x_{n-1}, x_n)),$$

where

$$\begin{aligned} K(x_{n-1}, x_n) &= \max\{d_\theta(x_{n-1}, x_n), d_\theta(x_{n-1}, Tx_{n-1}), d_\theta(x_n, Tx_n), \\ &\quad \frac{d_\theta(x_{n-1}, Tx_{n-1})d_\theta(x_n, Tx_n)}{d_\theta(x_{n-1}, x_n)}, \frac{d_\theta(x_n, Tx_{n-1}) + d_\theta(x_{n-1}, Tx_n)}{2 \max\{\theta(y, Tx), \theta(x, Ty)\}}\} \\ &= \max\{d_\theta(x_{n-1}, x_n), d_\theta(x_{n-1}, x_n), d_\theta(x_n, x_{n+1}), \\ &\quad \frac{d_\theta(x_{n-1}, x_n)d_\theta(x_n, x_{n+1})}{d_\theta(x_{n-1}, x_n)}, \frac{d_\theta(x_{n-1}, x_{n+1})}{2 \max\{\theta(x_n, x_n), \theta(x_{n-1}, x_{n+1})\}}\} \\ &\leq \max\left\{d_\theta(x_{n-1}, x_n), d_\theta(x_n, x_{n+1}), \frac{d_\theta(x_n, x_{n+1}) + d_\theta(x_{n-1}, x_n)}{2}\right\} \\ &= \max\{d_\theta(x_{n-1}, x_n), d_\theta(x_n, x_{n+1})\}. \end{aligned}$$

If for some  $n$ , we have  $K(x_{n-1}, x_n) = \max\{d_\theta(x_{n-1}, x_n), d_\theta(x_n, x_{n+1}) = d_\theta(x_n, x_{n+1})\}$ , then

$$0 < d_\theta(x_n, x_{n+1}) \leq \phi(d_\theta(x_n, x_{n+1})) < d_\theta(x_n, x_{n+1}),$$

a contradiction. Accordingly, we conclude, for all  $n \geq 1$ , that

$$K(x_{n-1}, x_n) = \max\{d_\theta(x_{n-1}, x_n), d_\theta(x_n, x_{n+1}) = d_\theta(x_{n-1}, x_n)\}.$$

We deduce that

$$0 < d_\theta(x_n, x_{n+1}) \leq \phi(d_\theta(x_{n-1}, x_n)) < d_\theta(x_{n-1}, x_n), \quad \forall n \geq 1. \tag{7}$$

We deduce

$$0 < d_\theta(x_n, x_{n+1}) \leq \phi^n(d_\theta(x_0, x_1)), \quad \forall n \geq 0. \tag{8}$$

Therefore, there exists  $L \geq 0$  such that

$$\lim_{n \rightarrow \infty} d_\theta(x_n, x_{n+1}) = L.$$

Letting  $n \rightarrow \infty$  in (7), we get

$$L \leq \phi(L),$$

which holds unless  $l = 0$ . Thus

$$\lim_{n \rightarrow \infty} d_\theta(x_n, x_{n+1}) = 0. \tag{9}$$

We claim that  $\{x_n\}$  is a Cauchy sequence. By using the modified triangle inequality (b3) together with (7) and (8), we find that

$$\begin{aligned} d_\theta(x_n, x_{n+k}) &\leq \theta(x_n, x_{n+k})[d_\theta(x_n, x_{n+1}) + d_\theta(x_{n+1}, x_{n+k})] \\ &\leq \theta(x_n, x_{n+k})d_\theta(x_n, x_{n+1}) + \theta(x_n, x_{n+k})\theta(x_{n+1}, x_{n+k})d_\theta(x_{n+1}, x_{n+2}) \\ &\quad + \dots + \theta(x_n, x_{n+k})\theta(x_{n+1}, x_{n+k})\dots\theta(x_{n+k-1}, x_{n+k})d_\theta(x_{n+k-1}, x_{n+k}) \\ &\leq \theta(x_n, x_{n+k})\phi^n(d_\theta(x_0, x_1)) + \theta(x_n, x_{n+k})\theta(x_{n+1}, x_{n+k})\phi^{n+1}(d_\theta(x_0, x_1)) \\ &\quad + \dots + \theta(x_n, x_{n+k})\theta(x_{n+1}, x_{n+k})\dots\theta(x_{n+k-1}, x_{n+k})\phi^{n+k-1}(d_\theta(x_0, x_1)) \\ &\leq \theta(x_1, x_{n+k})\theta(x_2, x_{n+k})\dots\theta(x_n, x_{n+k})\phi^n(d_\theta(x_0, x_1)) \\ &\quad + \theta(x_1, x_{n+k})\theta(x_2, x_{n+k})\dots\theta(x_n, x_{n+k})\theta(x_{n+1}, x_{n+k})\phi^{n+1}(d_\theta(x_0, x_1)) \\ &\quad + \dots + \dots \\ &\quad + \theta(x_1, x_{n+k})\theta(x_2, x_{n+k})\dots\theta(x_{n+k-1}, x_{n+k})\phi^{n+k-1}(d_\theta(x_0, x_1)) \\ &= \sum_{j=n}^{n+k-1} \phi^j(d_\theta(x_0, x_1)) \prod_{i=1}^j \theta(x_i, x_{n+k}). \end{aligned}$$

We deduce that

$$d_\theta(x_n, x_{n+k}) \leq S_{n+k-1} - S_n, \tag{10}$$

for the series

$$\sum_{j=1}^{\infty} \phi^j(d_\theta(x_0, x_1)) \prod_{i=1}^j \theta(x_i, x_{n+k}).$$

Put  $a_n = \phi^n(d_\theta(x_0, x_1)) \prod_{i=1}^n \theta(x_i, x_{n+k})$ . We have

$$\frac{a_{n+1}}{a_n} = \frac{\phi^{n+1}(d_\theta(x_0, x_1))}{\phi^j(d_\theta(x_0, x_1))} \theta(x_{n+1}, x_{n+k}).$$

In view of the assumption,

$$\limsup_{n \rightarrow \infty} \frac{\phi^{n+1}(t)}{\phi^j(t)} \theta(x_{n+1}, x_{n+k}) < 1,$$

the above series converges by ratio test. Consequently, in view of (10), we get

$$\lim_{n, m \rightarrow \infty} d_\theta(x_n, x_{n+k}) = 0, \tag{11}$$

that is,  $\{x_n\}$  is a Cauchy sequence. Since  $(X, d)$  is a complete extended  $b$ -metric space, there exists  $z \in X$  such that

$$\lim_{n \rightarrow \infty} d_\theta(x_n, z) = 0. \tag{12}$$

Since the mapping  $T$  and the extended  $b$ -metric are continuous, we derive that

$$\lim_{n \rightarrow \infty} d_\theta(Tx_n, Tz) = 0 = \lim_{n \rightarrow \infty} d_\theta(x_{n+1}, Tz) = d_\theta(z, Tz). \tag{13}$$

Hence, we conclude that  $Tz = z$ .  $\square$

In what follows, we refine the definition of  $(\alpha, \psi)$ - $K$ -contraction as  $(\alpha, \psi)$ - $M$ -contraction to remove the heavy condition, continuity, on the given self-mapping.

**Definition 2.3.** Let  $(X, d)$  be an extended  $b$ -metric space  $\alpha : X \times X \rightarrow [0, \infty)$  and  $\theta : X \times X \rightarrow [1, \infty)$ . A mapping  $T : X \rightarrow X$  is called  $(\alpha, \psi)$ - $M$ -contraction if it satisfies

$$\alpha(x, y)d_\theta(Tx, Ty) \leq \phi(M(x, y)), \text{ for all } x, y \in X, \tag{14}$$

where  $\phi \in \Phi$  and

$$M(x, y) = \max\left\{d_\theta(x, y), \frac{d_\theta(x, Tx) + d_\theta(y, Ty)}{2}, \frac{d_\theta(x, Ty) + d_\theta(y, Tx)}{2 \max\{\theta(y, Tx), \theta(x, Ty)\}}\right\}. \tag{15}$$

This is the second main result in which the continuity of the mapping is removed.

**Theorem 2.4.** Let  $(X, d)$  be a complete extended  $b$ -metric space and  $T : X \rightarrow X$  be a  $(\alpha, \psi)$ - $M$ -contraction mapping. Suppose that for each  $x_0 \in X$  and for each  $t > 0$ ,

$$\limsup_{n, m \rightarrow \infty} \frac{\phi^{n+1}(t)}{\phi^n(t)} \theta(x_n, x_m) < 1$$

where  $x_n = T^n x_0, n \in \mathbb{N}$ . Suppose also that

- (i)  $T$  is  $\alpha$ -orbital admissible,
- (ii) there exists  $x_0 \in X$  such that  $\alpha(x_0, Tx_0) \geq 1$
- (iii) if  $\{x_n\}$  is a sequence in  $X$  such that  $\alpha(x_n, x_{n+1}) \geq 1$  for all  $n$  and  $x_n \rightarrow x \in X$  as  $n \rightarrow \infty$ , then there exists a subsequence  $\{x_{n(k)}\}$  of  $\{x_n\}$  such that  $\alpha(x_{n(k)}, x) \geq 1$  for all  $k$ .

Then the mappings  $T$  posses a fixed point  $u$ , that is,  $Tu = u$ .

*Proof.* Following the proof of Theorem 2.2, we know that the sequence  $\{x_n\}$  defined by  $x_{n+1} = Tx_n$  for all  $n \geq 0$ , converges for some  $u \in X$ . From (6) and condition (iii), there exists a subsequence  $\{x_{n(k)}\}$  of  $\{x_n\}$  such that  $\alpha(x_{n(k)}, u) \geq 1$  for all  $k$ . Applying (14), for all  $k$ , we get that

$$d_\theta(x_{n(k)+1}, Tu) = d_\theta(Tx_{n(k)}, Tu) \leq \alpha(x_{n(k)}, u)d_\theta(Tx_{n(k)}, Tu) \leq \phi(M(x_{n(k)}, u)). \tag{16}$$

On the other hand, we have

$$M(x_{n(k)}, u) = \max \left\{ d_\theta(x_{n(k)}, u), \frac{d_\theta(x_{n(k)}, x_{n(k)+1}) + d_\theta(u, Tu)}{2}, \frac{d_\theta(x_{n(k)}, Tu) + d_\theta(u, x_{n(k)+1})}{2 \max\{\theta(y, Tx), \theta(x, Ty)\}} \right\}.$$

Letting  $k \rightarrow \infty$  in the above equality, we get that

$$\lim_{k \rightarrow \infty} M(x_{n(k)}, u) = \frac{d_\theta(u, Tu)}{2}. \tag{17}$$

Suppose that  $d_\theta(u, Tu) > 0$ . From (17), for  $k$  large enough, we have  $M(x_{n(k)}, u) > 0$ , which implies that  $\phi(M(x_{n(k)}, u)) < M(x_{n(k)}, u)$ . Thus, from (16), we have

$$d_\theta(x_{n(k)+1}, Tu) < M(x_{n(k)}, u).$$

Letting  $k \rightarrow \infty$  in the above inequality, using (17), we obtain that

$$d_\theta(u, Tu) \leq \frac{d_\theta(u, Tu)}{2},$$

which is a contradiction. Thus we have  $d_\theta(u, Tu) = 0$ , that is,  $u = Tu$ .  $\square$

For the uniqueness of a fixed point of a  $(\alpha, \psi)$ - $K$ -contractive mapping (respectively,  $(\alpha, \psi)$ - $M$ -contractive mapping), we shall suggest the following hypothesis.

(U) For all  $x, y \in \text{Fix}(T)$ , either  $\alpha(x, y) \geq 1$  or  $\alpha(y, x) \geq 1$ .

Here,  $\text{Fix}(T)$  denotes the set of fixed points of  $T$ .

**Theorem 2.5.** Adding condition (U) to hypotheses of Theorem 2.2 (respectively, Theorem 2.4), we obtain uniqueness of the fixed point of  $T$ .

*Proof.* Suppose, on the contrary, that  $u$  and  $v$  are two distinct fixed points of  $T$ . Then we have  $K(u, v) = d(u, v)$  (respectively,  $M(u, v) = d(u, v)$ ). On account of the hypothesis of (U), we employ the contraction condition (14)

$$\begin{aligned} \phi(d(u, v)) &= \phi(d(Tu, Tv)) \\ &\leq \alpha(u, v)\phi(d(Tu, Tv)) \\ &\leq \phi(K(u, v)) \\ &< \phi(d(u, v)), \end{aligned}$$

which is a contradiction. Hence, we conclude that the obtained fixed points are unique in Theorem 2.2 and Theorem 2.4.  $\square$

**Definition 2.6.** Let  $(X, d)$  be an extended  $b$ -metric space  $\alpha : X \times X \rightarrow [0, \infty)$  and  $\theta : X \times X \rightarrow [1, \infty)$ . A mapping  $T : X \rightarrow X$  is called  $\alpha$ -contraction if it satisfies

$$\alpha(x, y)d_\theta(Tx, Ty) \leq \phi(d_\theta(x, y)), \text{ for all } x, y \in X, \tag{18}$$

where  $\phi \in \Phi$ .

**Corollary 2.7.** Let  $(X, d)$  be a complete extended  $b$ -metric space and  $T : X \rightarrow X$  be a  $\alpha$ -contraction mapping. Suppose that for each  $x_0 \in X$  and for each  $t > 0$ ,

$$\limsup_{n,m \rightarrow \infty} \frac{\phi^{n+1}(t)}{\phi^n(t)} \theta(x_n, x_m) < 1$$

where  $x_n = T^n x_0, n \in \mathbb{N}$ . Suppose also that

- (i)  $T$  is  $\alpha$ -orbital admissible,
- (ii) there exists  $x_0 \in X$  such that  $\alpha(x_0, Tx_0) \geq 1$
- (iii)  $T$  is continuous.

or

(iii)\* if  $\{x_n\}$  is a sequence in  $X$  such that  $\alpha(x_n, x_{n+1}) \geq 1$  for all  $n$  and  $x_n \rightarrow x \in X$  as  $n \rightarrow \infty$ , then there exists a subsequence  $\{x_{n(k)}\}$  of  $\{x_n\}$  such that  $\alpha(x_{n(k)}, x) \geq 1$  for all  $k$ .

Then the mappings  $T$  posses a fixed point  $u$ , that is,  $Tu = u$ . If, additionally, we assume the condition (U), then  $u$  is the unique fixed point of  $T$ .

**Definition 2.8.** Let  $(X, d)$  be an extended  $b$ -metric space  $\alpha : X \times X \rightarrow [0, \infty)$  and  $\theta : X \times X \rightarrow [1, \infty)$ . A mapping  $T : X \rightarrow X$  is called  $\alpha$ -Jaggi-type contraction if it satisfies

$$\alpha(x, y)d_\theta(Tx, Ty) \leq \phi\left(\frac{d_\theta(x, Tx)d_\theta(y, Ty)}{d_\theta(x, y)}\right), \text{ for all } x, y \in X, \tag{19}$$

where  $\phi \in \Phi$ .

**Corollary 2.9.** Let  $(X, d)$  be a complete extended  $b$ -metric space and  $T : X \rightarrow X$  be a  $\alpha$ -Jaggi-type contraction mapping. Suppose that for each  $x_0 \in X$  and for each  $t > 0$ ,

$$\limsup_{n,m \rightarrow \infty} \frac{\phi^{n+1}(t)}{\phi^n(t)} \theta(x_n, x_m) < 1$$

where  $x_n = T^n x_0, n \in \mathbb{N}$ . Suppose also that

- (i)  $T$  is  $\alpha$ -orbital admissible,
- (ii) there exists  $x_0 \in X$  such that  $\alpha(x_0, Tx_0) \geq 1$
- (iii)  $T$  is continuous.

Then the mappings  $T$  posses a fixed point  $u$ , that is,  $Tu = u$ . If, additionally, we assume the condition (U), then  $u$  is the unique fixed point of  $T$ .

### 3. Conclusion

One can easily drive several consequences from the presented main results in this paper in different aspects. For example, letting  $\theta(x, y) = s \geq 1$  yields the corresponding fixed point results in the context of  $b$ -metric space. Moreover, the standard versions of the given results are follows when we take  $\theta(x, y) = 1$ . As in Corollary 2.7 and Corollary 2.9, we can derive more results by replacing  $K(x, y)$  with a proper one. On the other hand, as in [19], by assign  $\alpha(x, y)$  in a proper way, we can conclude results in the frame of "partially ordered spaces" and for "cyclic contraction."

### Competing interests

The authors declare that they have no competing interests.



## Authors contributions

All authors contributed equally and significantly in writing this article. All authors read and approved the final manuscript.

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