# Iterative Approximation of Solution of Split Variational Inclusion Problem 

Jeremiah Nkwegu Ezeora ${ }^{\text {a }}$, Chinedu Izuchukwu ${ }^{\text {b }}$<br>${ }^{a}$ Department of Mathematics and Statistics, University of Port Harcourt, Nigeria.<br>${ }^{b}$ School of Mathematics, Statistics and Computer Science, University of KwaZulu-Natal, Durban, South Africa.


#### Abstract

Following recent important results of Moudafi [Journal of Optimization Theory and Applications 150(2011), 275-283] and other related results on variational problems, we introduce a new iterative algorithm for approximating a solution of monotone variational inclusion problem involving multi-valued mapping. The sequence of the algorithm is proved to converge strongly in the setting of Hilbert spaces. As application, we solved split convex optimization problems.


## 1. Introduction

Let $H$ be a real Hilbert space and $C$ be a nonempty, closed and convex subset of $H$. A mapping $S: C \rightarrow C$ is said to be
(i) nonexpansive if

$$
\|S x-S y\| \leq\|x-y\| \forall x, y \in C
$$

(ii) $\mu$-strictly pseudocontractive in the sense of Browder and Petryshyn [12] if for $0 \leq \mu<1$,

$$
\|S x-S y\|^{2} \leq\|x-y\|^{2}+\mu\|(I-S) x-(I-S) y\|^{2} \forall x, y \in C .
$$

A point $x \in C$ is called a fixed point of $S$ if $S x=x$. The set of fixed points of $S$ is denoted by $F(S)$, and it is generally known that if $F(S) \neq \emptyset$, then $F(S)$ is closed and convex. For more information on strictly pseudocontrative mappings, see $[1,12,32,43]$ and references therein.
A mapping $M: H \rightarrow H$ is said to be
(i) monotone, if

$$
\langle M x-M y, x-y\rangle \geq 0, \quad \forall x, y \in H
$$

(ii) $\alpha$-inverse strongly monotone, if there exists a constant $\alpha>0$ such that

$$
\langle M x-M y, x-y\rangle \geq \alpha\|M x-M y\|^{2}, \quad \forall x, y \in H
$$

[^0](iii) firmly nonexpansive, if
$$
\langle M x-M y, x-y\rangle \geq\|M x-M y\|^{2}, \quad \forall x, y \in H
$$
(iv) Lipschitz, if there exists a constant $L>0$ such that
$$
\|M x-M y\| \leq L\|x-y\|, \forall x, y \in H
$$

Remark 1.1. [9] It is well known that $M$ is $\alpha$-inverse strongly monotone if and only if it is $\frac{1}{\alpha}$-Lipschitz continuous. If $M$ is a multivalued mapping, i.e. $M: H \rightarrow 2^{H}$, then $M$ is called monotone if

$$
\langle x-y, u-v\rangle \geq 0 \forall x, y \in H, u \in M(x), v \in M(y)
$$

and $M$ is maximal monotone if the graph $G(M)$ of $M$ defined by

$$
G(M)=:\{(x, y) \in H \times H: y \in M(x)\}
$$

is not properly contained in the graph of any other monotone mapping. It is generally known that $M$ is maximal if and only if for $(x, u) \in H \times H,\langle x-y, u-v\rangle \geq 0$ for all $(y, v) \in G(M)$ implies $u \in M(x)$.
The resolvent operator $J_{\lambda}^{M}$ associated with a mapping $M$ and $\lambda$ is the mapping $J_{\lambda}^{M}: H \rightarrow 2^{H}$ defined by

$$
\begin{equation*}
J_{\lambda}^{M}(x)=(I+\lambda M)^{-1} x, \quad x \in H, \lambda>0 \tag{1}
\end{equation*}
$$

It is known that if the mapping $M$ is monotone, then $J_{\lambda}^{M}$ is single valued and firmly nonexpansive (see [11]). A mapping $f: C \rightarrow C$ is said to be averaged nonexpansive if $\forall x, y \in C, f=(1-\beta) I+\beta S$ holds for a nonexpansive operator $S: C \rightarrow C$ and $\beta \in(0,1)$. The term "averaged mapping" was coined by Biallon et al [8]. Recall that a mapping $f$ is firmly nonexpansive if and only if $f$ can be expressed as $f=\frac{1}{2}(I+S)$, where $S$ is nonexpansive (see [34]). Thus, we make the following remark which can be easily verified.
Remark 1.2. In a Hilbert space, $f$ is firmly nonexpansive if and only if it is averaged with $\beta=\frac{1}{2}$.
The metric projection $P_{C}$ is a map defined on $H$ onto $C$ which assigns to each $x \in H$, the unique point in $C$, denoted by $P_{C} x$ such that

$$
\left\|x-P_{C} x\right\|=\inf \{\|x-y\|: y \in C\}
$$

It is well known that $P_{C} x$ is characterized by the inequality $\left\langle x-P_{C} x, z-P_{C} x\right\rangle \leq 0, \forall z \in C$ and $P_{C}$ is a firmly nonexpansive mapping. Thus, $P_{C}$ is nonexpansive. For more information on metric projections, see [19, 24].
Recall that the normal cone of $C$ at the point $z \in H$ is defined as

$$
N_{C} z:=\{d \in H:\langle d, y-z\rangle \leq 0, \forall y \in C\} \text { if } z \in C \text { and } \emptyset \text {, otherwise. }
$$

In 1994, Censor and Elfving [17] introduced the following Split Feasibility Problem (SFP): Find a point

$$
\begin{equation*}
x \in C \text { such that } A x \in Q \tag{2}
\end{equation*}
$$

where $C$ and $Q$ are nonempty closed and convex subsets of $\mathbb{R}^{n}$ and $\mathbb{R}^{m}$ respectively, and $A$ is an $m \times n$ real matrix. The SFP is known to have wide applications in many fields such as phase retrieval, medical image reconstruction, signal processing, radiation therapy treatment planning, among others (for example, see [13, 16-18] and the references therein).
Byrne [14] applied the forward-backward method, a type of projected gradient method, thus, presenting the so-called CQ-iterative procedure for approximating a solution of (2), which he defined as

$$
\begin{equation*}
x_{n+1}=P_{C}\left(I-\gamma A^{*}\left(I-P_{Q}\right) A\right) x_{n}, n \in \mathbb{N}, \tag{3}
\end{equation*}
$$

where $\gamma \in\left(0, \frac{2}{\lambda}\right)$ with $\lambda$ being the spectral radius of the operator $A^{*} A$. Byrne [14] proved that the sequence generated by Algorithm 3 converges weakly to a solution of (2).

In 2010, Censor et al. [20] introduced a new class of problem called the Split Variational Inequality Problem (SVIP) by combining the Variational Inequality Problem (VIP) and the SFP. They defined the SVIP as follows: Find $x^{*} \in C$ such that

$$
\begin{equation*}
\left\langle f\left(x^{*}\right), x-x^{*}\right\rangle \geq 0 \forall x \in C, \tag{4}
\end{equation*}
$$

and such that $y^{*}=A x^{*} \in Q$ solves

$$
\begin{equation*}
\left\langle g\left(y^{*}\right), y-y^{*}\right\rangle \geq 0 \forall y \in Q \tag{5}
\end{equation*}
$$

where $C$ and $Q$ are nonempty, closed and convex subsets of real Hilbert spaces $H_{1}$ and $H_{2}$ respectively, $A: H_{1} \rightarrow H_{2}$ is a bounded linear operator, $f: H_{1} \rightarrow H_{1}$ and $g: H_{2} \rightarrow H_{2}$ are two given operators. If (4) and (5) are considered separately, we have that (4) is a VIP with its solution set VIP (C, f) and (5) is a VIP with its solution set $\operatorname{VIP}(Q, g)$. To solve the SVIP (4)-(5), Censor et al. proposed the following algorithm and obtained a weak convergence result. For $x_{1} \in H_{1}$, the sequence $\left\{x_{n}\right\}$ is generated by

$$
\begin{equation*}
x_{n+1}=P_{C}(I-\lambda f)\left(x_{n}+\gamma A^{*}\left(P_{Q}(I-\lambda g)-I\right) A x_{n}\right), n \geq 1 \tag{6}
\end{equation*}
$$

where $\gamma \in\left(0, \frac{1}{L}\right)$ with $L$ being the spectral radius of the operator $A^{*} A$.
Based on the work of Censor et al. [20], Moudafi [34] recently introduced and studied a new type of split problem called Split Monotone Variational Inclusion Problem (SMVIP), which is to find

$$
\begin{equation*}
x^{*} \in H_{1} \text { such that } 0 \in f\left(x^{*}\right)+M_{1}\left(x^{*}\right), \tag{7}
\end{equation*}
$$

and such that $y^{*}=A x^{*} \in H_{2}$ solves

$$
\begin{equation*}
0 \in g\left(y^{*}\right)+M_{2}\left(y^{*}\right) \tag{8}
\end{equation*}
$$

where $M_{1}: H_{1} \rightarrow 2^{H_{1}}$ and $M_{2}: H_{2} \rightarrow 2^{H_{2}}$ are multivalued mappings, $A: H_{1} \rightarrow H_{2}$ is a bounded linear operator, $f: H_{1} \rightarrow H_{1}$ and $g: H_{2} \rightarrow H_{2}$ are single valued operators. We also note that if (7) and (8) are considered separately, we have that (7) is a Monotone Variational Inclusion Problem (MVIP) with its solution set $\left(M_{1}+f\right)^{-1}(0)$ and (8) is a MVIP with its solution set $\left(M_{2}+g\right)^{-1}(0)$. In [34], Moudafi proved that $x^{*} \in\left(M_{1}+f\right)^{-1}(0)$ if and only if $x^{*}=J_{\lambda}^{M_{1}}(I-\lambda f)\left(x^{*}\right), \forall \lambda>0$. It was also shown in [34] that, if $f$ is an $\alpha$-inverse strongly monotone mapping and $M$ is a maximal monotone mapping, then $J_{\lambda}^{M_{1}}(I-\lambda f)$ is averaged with $0<\lambda<2 \alpha$. Thus, $J_{\lambda}^{M_{1}}(I-\lambda f)$ is a nonexpansive mapping with $0<\lambda<2 \alpha$. In addition, $\left(M_{1}+f\right)^{-1}(0)$ is closed and convex.
To solve the SMVIP (7)-(8), Moudafi [34] proposed the following iterative algorithm and obtained weak convergence results: For $x_{1} \in H_{1}$, the sequence $\left\{x_{n}\right\}$ is generated by

$$
\begin{equation*}
x_{n+1}=J_{\lambda}^{M_{1}}(I-\lambda f)\left(x_{n}+\gamma A^{*}\left(J_{\lambda}^{M_{2}}(I-\lambda g)-I\right) A x_{n}\right), n \in \mathbb{N} \tag{9}
\end{equation*}
$$

where $\gamma \in\left(0, \frac{1}{L}\right)$ with $L$ being the spectral radius of the operator $A^{*} A$.
Remark 1.3. [34] As observed by Moudafi, setting $M_{1}=N_{C}$ and $M_{2}=N_{Q}$ in SMVIP (7)-(8), where $N_{C}$ and $N_{Q}$ are the normal cones of C and Q respectively, we recover the SVIP (4)-(5). Thus, the SMVIP can be viewed as an important generalization of the SVIP, SFP and other related problems (see also [33]).

Moreover, MVIP is generally known to be very useful in the study of wide classes of problems. It has been an important tools for solving problems arising from mechanics, optimization, nonlinear programming, economics, finance, applied sciences, among others (see for example [2-4,21,33] and the references therein). Very recently, Tian and Jiang [39] proposed a class of SVIP which is to find $x^{*} \in C$ such that

$$
\begin{equation*}
\left\langle f\left(x^{*}\right), x-x^{*}\right\rangle \geq 0 \forall x \in C, \text { and such that } A x^{*} \in F(S), \tag{10}
\end{equation*}
$$

where $C$ is a nonempty, closed and convex subset of $H_{1}, A: H_{1} \rightarrow H_{2}$ is a bounded linear operator, $f: C \rightarrow H_{1}$ is a single valued operator and $S: H_{2} \rightarrow H_{2}$ is a nonlinear mapping. To approximate solutions of (10), Tian and Jiang [39] proposed the following iterative algorithm by combining Algorithm (6) with the

Korpelevich's extra-gradient method (see [27]) and Byrne's CQ algorithm: For arbitrary $x_{1} \in C$, define the sequence $\left\{x_{n}\right\},\left\{y_{n}\right\}$ and $\left\{t_{n}\right\}$ by

$$
\left\{\begin{array}{l}
y_{n}=P_{C}\left(x_{n}-\gamma_{n} A^{*}(I-S) A x_{n}\right)  \tag{11}\\
t_{n}=P_{C}\left(y_{n}-\lambda_{n} f\left(y_{n}\right)\right) \\
x_{n+1}=P_{C}\left(y_{n}-\lambda_{n} f\left(t_{n}\right)\right)
\end{array}\right.
$$

for each $n \in \mathbb{N}$, where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right)$ and $\left\{\lambda_{n}\right\} \subset[a, b]$ for some $c, d \in\left(0, \frac{1}{k}\right), S: H_{2} \rightarrow H_{2}$ is a nonexpansive mapping and $f: C \rightarrow H_{1}$ is a monotone and $k$-Lipschitz continuous mapping. They proved that the sequence generated by Algorithm (11) converges weakly to a solution of (10). Furthermore, Tian and Jian [39] showed that Algorithm (11) can be used to solve the SVIP of Censor et al. [20] by setting $S=P_{Q}(I-\lambda g)$ in Algorithm (11), since $P_{Q}(I-\lambda g)$ is a nonexpansive mapping for $\lambda \in(0,2 \alpha)$. For more results on VIPs and MVIPs, see $[5-7,15,19,23,26,29,30,35]$ and the references therein.
Motivated by the works of Moudafi [34], Tian and Jiang [39], and in view of Remark 1.3, we propose an extension of the class of SVIP studied by Tian and Jiang [39] to the following class of SMVIP: Find

$$
\begin{equation*}
x^{*} \in H_{1} \text { such that } 0 \in f\left(x^{*}\right)+M\left(x^{*}\right) \text {, and such that } A x^{*} \in F(S), \tag{12}
\end{equation*}
$$

where $M: H_{1} \rightarrow 2^{H_{1}}$ is a multivalued mapping, $A: H_{1} \rightarrow H_{2}$ is a bounded linear operator, $f: H_{1} \rightarrow H_{1}$ is a single valued operator and $S: H_{2} \rightarrow H_{2}$ is a nonlinear mapping. Furthermore, we propose an iterative algorithm and using the algorithm, we state and prove some strong convergence results for the approximation of solutions of (12) and (7)-(8). Finally, we applied our results to study split convex minimization problems. Our results extend and improve the results of Censor et al. [20], Moudafi [34], Tian and Jiang [39], and a host of other important results.

## 2. Preliminaries

We state some useful results which will be needed in the proof of our main theorem.
Lemma 2.1. [22] Let $H$ be a Hilbert space, then for all $x, y \in H$ and $\alpha \in(0,1)$, the following hold:
(i) $2\langle x, y\rangle=\|x\|^{2}+\|y\|^{2}-\|x-y\|^{2}=\|x+y\|^{2}-\|x\|^{2}-\|y\|^{2}$,
(ii) $\|\alpha x+(1-\alpha) y\|^{2}=\alpha\|x\|^{2}+(1-\alpha)\|y\|^{2}-\alpha(1-\alpha)\|x-y\|^{2}$.

Lemma 2.2. [40] Let $H$ be a Hilbert space and $T: H \rightarrow H$ be a nonlinear mapping, then the following hold.
(i) $f$ is nonexpansive if and only if the complement $I-f$ is $\frac{1}{2}$-ism.
(ii) $f$ is $v$-ism and $\gamma>0$, then $\gamma f$ is $\frac{v}{\gamma}$-ism.
(iii) $f$ is averaged if and only if the complement $I-f$ is $v$-ism for some $v>\frac{1}{2}$. Indeed, for $\beta \in(0,1), f$ is $\beta$-averaged if and only if $I-f$ is $\frac{1}{2 \beta}$-ism.
(iv) If $f_{1}$ is $\beta_{1}$-averaged and $f_{2}$ is $\beta_{2}$-averaged, where $\beta_{1}, \beta_{2} \in(0,1)$, then the composite $f_{1} f_{2}$ is $\beta$-averaged, where $\beta=\beta_{1}+\beta_{2}-\beta_{1} \beta_{2}$.
(v) If $f_{1}$ and $f_{2}$ are averaged and have a common fixed point, then $F\left(f_{1} f_{2}\right)=F\left(f_{1}\right) \cap F\left(f_{2}\right)$.

Lemma 2.3. [37] Let $H_{1}$ and $H_{2}$ be real Hilbert spaces. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator with $A \neq 0$, and $S: H_{2} \rightarrow H_{2}$ be a nonexpansive mapping. Then $A^{*}(I-S) A$ is $\frac{1}{2\|A\|^{2}}$-ism.

Lemma 2.4. [39] Let $H_{1}$ and $H_{2}$ be real Hilbert spaces. Let $C$ be a nonempty, closed and convex subset of $H_{1}$. Let $S: H_{2} \rightarrow H_{2}$ be a nonexpansive mapping and let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator. Suppose that $C \cap A^{-1} F(T) \neq \emptyset$. Let $\gamma>0$ and $x^{*} \in H_{1}$. Then the following are equivalent.
(i) $x^{*}=P_{C}\left(I-\gamma A^{*}(I-S) A\right) x^{*}$;
(ii) $0 \in A^{*}(I-S) A x^{*}+N_{C} x^{*}$;
(iii) $x^{*} \in C \cap A^{-1} F(S)$.

Lemma 2.5. [41] Let $H$ be a real Hilbert space and $S: H \rightarrow H$ be a nonexpansive mapping with $F(S) \neq \emptyset$. If $\left\{x_{n}\right\}$ is a sequence in $H$ converging weakly to $x^{*}$ and if $\left\{(I-S) x_{n}\right\}$ converges strongly to $y$, then $(I-S) x^{*}=y$.
Lemma 2.6. [28] Let $M: H \rightarrow 2^{H}$ be a maximal monotone mapping and $f: H \rightarrow H$ be a Lipschitz continuous mapping. Then, the mapping $(M+f): H \rightarrow 2^{H}$ is maximal monotone.

Lemma 2.7. [42] Let $\left\{a_{n}\right\}$ be a sequence of nonnegative real numbers such that

$$
a_{n+1} \leq\left(1-\gamma_{n}\right) a_{n}+\gamma_{n} \delta_{n}, \quad n \geq 0
$$

where $\left\{\gamma_{n}\right\}$ is a sequence in $(0,1)$ and $\left\{\delta_{n}\right\}$ is a sequence in $\mathbb{R}$ such that
(i) $\sum_{n=0}^{\infty} \gamma_{n}=\infty$,
(ii) $\lim \sup \delta_{n} \leq 0$ or $\sum_{n=0}^{\infty}\left|\delta_{n} \gamma_{n}\right|<\infty$.

Then $\lim _{n \rightarrow \infty}^{n \rightarrow \infty} a_{n}=0$.
Lemma 2.8. [43] Let $H$ be a real Hilbert space and $S: H \rightarrow H$ be $\mu$-strictly pseudocontractive mapping with $\mu \in[0,1)$. Let $T_{\gamma}:=\gamma I+(1-\gamma) S$, where $\gamma \in[\mu, 1)$, then
(i) $F(T)=F\left(T_{\gamma}\right)$,
(ii) $T_{\gamma}$ is a nonexpansive mapping.

Lemma 2.9. [31] Let $\left\{\Gamma_{n}\right\}$ be a sequence of real numbers that does not decrease at infinity, in the sense that there exists a subsequence $\left\{\Gamma_{n_{j}}\right\}_{j \geq 0}$ of $\left\{\Gamma_{n}\right\}$ such that

$$
\Gamma_{n_{j}}<\Gamma_{n_{j}+1} \forall j \geq 0
$$

Also consider the sequence of integers $\{\tau(n)\}_{n \geq n_{0}}$ defined by

$$
\tau(n)=\max \left\{k \leq n \mid \Gamma_{k}<\Gamma_{k+1}\right\} .
$$

Then $\left\{\Gamma_{n}\right\}_{n \geq n_{0}}$ is a nondecreasing sequence such that $\tau(n) \rightarrow \infty$, as $n \rightarrow 0$, and for all $n \geq n_{0}$, the following two estimates hold:

$$
\Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}, \quad \Gamma_{n} \leq \Gamma_{\tau(n)+1} .
$$

## 3. Main Results

Proposition 3.1. Let $H$ be a real Hilbert space. Let $M: H \rightarrow 2^{H}$ be a maximal monotone mapping and $f: H \rightarrow H$ be an $\alpha$-inverse strongly monotone mapping. Let $z=J_{\lambda}^{M}(I-\lambda f) x$, then

$$
\|y-z\|^{2}+\|x-z\|^{2} \leq\|y-x\|^{2}, \forall x \in H, y \in F\left(J_{\lambda}^{M}(I-\lambda f)\right), \text { and } \lambda \in(0,2 \alpha)
$$

Proof. Let $\lambda \in(0,2 \alpha)$, since $J_{\lambda}^{M}(I-\lambda f)$ is averaged, then it follows from Remark 1.2 that $J_{\lambda}^{M}(I-\lambda f)$ is a firmly nonexpansive mapping. Thus, for any $x \in H$ and $y \in F\left(J_{\lambda}^{M}(I-\lambda f)\right)$, we have from Lemma 2.1 that

$$
\begin{aligned}
\|z-y\|^{2} & =\left\|J_{\lambda}^{M}(I-\lambda f) x-y\right\|^{2} \\
& \leq\langle z-y, x-y\rangle \\
& =\frac{1}{2}\left[\|z-y\|^{2}+\|x-y\|^{2}-\|z-x\|^{2}\right]
\end{aligned}
$$

which implies

$$
\|y-z\|^{2}+\|x-z\|^{2} \leq\|y-x\|^{2}
$$

Theorem 3.2. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $M: H_{1} \rightarrow 2^{H_{1}}$ be multivalued maximal monotone mapping and $f: H_{1} \rightarrow H_{1}$ be an $\alpha$-inverse strongly monotone mapping. Let $S: H_{2} \rightarrow H_{2}$ be $\mu$-strictly pseudocontractive mapping. Assume that $\Gamma=\left\{z \in(M+f)^{-1}(0): A z \in F(S)\right\} \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in H_{1}$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{13}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}\left(I-T_{\gamma}\right) A u_{n}\right) \\
x_{n+1}=J_{\lambda}^{M}(I-\lambda f) y_{n}, n \geq 1
\end{array}\right.
$$

where $T_{\gamma}:=\gamma I+(1-\gamma) S$ with $\gamma \in[\mu, 1),\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), \lambda \in(0,2 \alpha)$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Gamma$.

Proof. From Lemma 2.8, Lemma 2.2 (ii), (iii), (iv) and Lemma 2.3, we obtain that $P_{C}\left(I-\gamma_{n} A^{*}\left(I-T_{\gamma}\right) A\right)$ is $\frac{1+\gamma_{n}\|A\|^{2}}{2}$-averaged. That is, $P_{C}\left(I-\gamma_{n} A^{*}\left(I-T_{\gamma}\right) A\right)=\left(1-\alpha_{n}\right) I+\alpha_{n} T_{n}$, where $\alpha_{n}=\frac{1+\gamma_{n}\|A\|^{2}}{2}$ and $T_{n}$ is a nonexpansive mapping for each $n \geq 1$. Thus, we can rewrite $y_{n}$ as

$$
\begin{equation*}
y_{n}=\left(1-\alpha_{n}\right) u_{n}+\alpha_{n} T_{n} u_{n} . \tag{14}
\end{equation*}
$$

Let $p \in \Gamma$, then from (13), (14) and Lemma 2.1, we have

$$
\begin{align*}
&\left\|x_{n+1}-p\right\|^{2}=\left\|J_{\lambda}^{M}(I-\lambda f) y_{n}-p\right\|^{2} \\
& \leq\left\|y_{n}-p\right\|^{2} \\
&=\left\|\left(1-\alpha_{n}\right)\left(u_{n}-p\right)+\alpha_{n}\left(T_{n} u_{n}-p\right)\right\|^{2} \\
&=\left(1-\alpha_{n}\right)\left\|u_{n}-p\right\|^{2}+\alpha_{n}\left\|T_{n} u_{n}-p\right\|^{2} \\
&-\alpha_{n}\left(1-\alpha_{n}\right)\left\|u_{n}-T_{n} u_{n}\right\|^{2} \\
& \leq\left\|u_{n}-p\right\|^{2}-\alpha_{n}\left(1-\alpha_{n}\right)\left\|u_{n}-T_{n} u_{n}\right\|^{2}  \tag{15}\\
& \leq\left\|\left(1-\beta_{n}\right)\left(x_{n}-p\right)+\beta_{n}(u-p)\right\|^{2} \\
& \leq\left(1-\beta_{n}\right)\left\|x_{n}-p\right\|^{2}+\beta_{n}\|u-p\|^{2} \\
& \leq \max \left\{\left\|x_{n}-p\right\|^{2},\|u-p\|^{2}\right\} \\
& \vdots \\
& \leq \max \left\{\left\|x_{1}-p\right\|^{2},\|u-p\|^{2}\right\} .
\end{align*}
$$

Therefore, $\left\{\left\|x_{n}-p\right\|^{2}\right\}$ is bounded. Consequently, $\left\{x_{n}\right\},\left\{y_{n}\right\}\left\{u_{n}\right\}$ and $\left\{A u_{n}\right\}$ are all bounded.
From (13), we obtain

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|u_{n}-x_{n}\right\|^{2}=\lim _{n \rightarrow \infty} \beta_{n}\left\|u-x_{n}\right\|^{2}=0 \tag{16}
\end{equation*}
$$

We now consider two cases:
Case 1: Suppose that $\left\{\left\|x_{n}-p\right\|^{2}\right\}$ is monotone decreasing, then $\left\{\left\|x_{n}-p\right\|^{2}\right\}$ is convergent. Thus,

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left(\left\|x_{n}-p\right\|^{2}-\left\|x_{n+1}-p\right\|^{2}\right)=0 \tag{17}
\end{equation*}
$$

From (15), we obtain

$$
\begin{align*}
\alpha_{n}\left(1-\alpha_{n}\right)\left\|u_{n}-T_{n} u_{n}\right\|^{2} \leq & \left\|u_{n}-p\right\|^{2}-\left\|x_{n+1}-p\right\|^{2} \\
\leq & \left(1-\beta_{n}\right)\left\|x_{n}-p\right\|^{2}+\beta_{n}\|u-p\|^{2} \\
& -\left\|x_{n+1}-p\right\|^{2} \rightarrow 0, \text { as } n \rightarrow \infty \tag{18}
\end{align*}
$$

Since $\alpha_{n}=\frac{1+\gamma_{n}\|A\|^{2}}{2}$, then by the condition on $\gamma_{n}$, we obtain

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|u_{n}-T_{n} u_{n}\right\|^{2}=0 \tag{19}
\end{equation*}
$$

Also, from (14) and (19), we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-u_{n}\right\|^{2}=\lim _{n \rightarrow \infty} \alpha_{n}\left\|T_{n} u_{n}-u_{n}\right\|^{2}=0 \tag{20}
\end{equation*}
$$

We obtain from (16) and (20) that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-x_{n}\right\|^{2}=0 \tag{21}
\end{equation*}
$$

It follows from (13), (15) and Proposition 3.1 that

$$
\begin{align*}
\left\|x_{n+1}-y_{n}\right\|^{2} \leq & \left\|y_{n}-p\right\|^{2}-\left\|x_{n+1}-p\right\|^{2} \\
\leq & \left\|u_{n}-p\right\|^{2}-\left\|x_{n+1}-p\right\|^{2} \\
\leq & \left(1-\beta_{n}\right)\left\|x_{n}-p\right\|^{2}+\beta_{n}\|u-p\|^{2}-\left\|x_{n+1}-p\right\|^{2} \\
= & \left(\left\|x_{n}-p\right\|^{2}-\left\|x_{n+1}-p\right\|^{2}\right) \\
& +\beta_{n}\left(\|u-p\|^{2}-\left\|x_{n}-p\right\|^{2}\right) \rightarrow 0, \text { as } n \rightarrow \infty . \tag{22}
\end{align*}
$$

From (20) and (22), we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n+1}-u_{n}\right\|^{2}=0 \tag{23}
\end{equation*}
$$

Since $\left\{u_{n}\right\}$ is bounded, there exists a subsequence $\left\{u_{n_{k}}\right\}$ of $\left\{u_{n}\right\}$ that converges weakly to $z$. Without loss of generality, the subsequence $\left\{\gamma_{n_{k}}\right\}$ of $\left\{\gamma_{n}\right\}$ converges to a point $\bar{\gamma} \in\left(0, \frac{1}{\|A\|^{2}}\right)$. By Lemma 2.3, $A^{*}\left(I-T_{\gamma}\right) A$ is inverse strongly monotone, thus $\left\{A^{*}\left(I-T_{\gamma}\right) A u_{n_{k}}\right\}$ is bounded. It then follows from the firmly nonexpansivity of $P_{C}$ that

$$
\left\|P_{C}\left(I-\gamma_{n_{k}} A^{*}\left(I-T_{\gamma}\right) A\right) u_{n_{k}}-P_{C}\left(I-\bar{\gamma} A^{*}\left(I-T_{\gamma}\right) A\right) u_{n_{k}}\right\| \leq \mid \gamma_{n_{k}}-\bar{\gamma}\left\|A^{*}\left(I-T_{\gamma}\right) A u_{n_{k}}\right\| \rightarrow 0, \text { as } k \rightarrow \infty .
$$

That is,

$$
\lim _{k \rightarrow \infty}\left\|y_{n_{k}}-P_{C}\left(I-\bar{\gamma} A^{*}\left(I-T_{\gamma}\right) A\right) u_{n_{k}}\right\|=0
$$

which implies from (20) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|u_{n_{k}}-P_{C}\left(I-\bar{\gamma} A^{*}\left(I-T_{\gamma}\right) A\right) u_{n_{k}}\right\|=0 \tag{24}
\end{equation*}
$$

It then follows from Lemma 2.5 that $z \in F\left(P_{C}\left(I-\bar{\gamma} A^{*}\left(I-T_{\gamma}\right) A\right)\right)$. Thus, from Lemma 2.4, we obtain that

$$
z \in C \cap A^{-1} F\left(T_{\gamma}\right)
$$

Thus,

$$
A z \in F\left(T_{\gamma}\right)=F(S) .
$$

Next we show that $z \in(M+f)^{-1}(0)$. Since $f$ is $\alpha$-inverse strongly monotone, $f$ is $\frac{1}{\alpha}$-Lipschitz continuous and monotone. It then follows from Lemma 2.6 that $M+f$ is maximal monotone. Let $(v, w) \in G(M+f)$, then $w-f v \in M(v)$. From $x_{n_{k}+1}=J_{\lambda}^{M}(I-\lambda f) y_{n_{k}}$, we obtain

$$
(I-\lambda f) y_{n_{k}} \in(I+\lambda M) x_{n_{k}+1}
$$

That is,

$$
\frac{1}{\lambda}\left(y_{n_{k}}-\lambda f y_{n_{k}}-x_{n_{k}+1}\right) \in M\left(x_{n_{k}+1}\right)
$$

Since $M+f$ is maximal monotone, it is monotone. Thus, we have

$$
\begin{equation*}
\left\langle v-x_{n_{k}+1}, w-f v-\frac{1}{\lambda}\left(y_{n_{k}}-\lambda f y_{n_{k}}-x_{n_{k}+1}\right)\right\rangle \geq 0 \tag{25}
\end{equation*}
$$

which implies

$$
\begin{align*}
\left\langle v-x_{n_{k}+1}, w\right\rangle \geq & \left\langle v-x_{n_{k}+1}, f v+\frac{1}{\lambda}\left(y_{n_{k}}-x_{n_{k}+1}\right)-f y_{n_{k}}\right\rangle \\
= & \left\langle v-x_{n_{k}+1}, f v-f\left(x_{n_{k}+1}\right)\right\rangle+\left\langle v-x_{n_{k}+1}, f\left(x_{n_{k}+1}\right)-f\left(y_{n_{k}}\right)\right\rangle \\
& +\left\langle v-x_{n_{k}+1}, \frac{1}{\lambda}\left(y_{n_{k}}-x_{n_{k}+1}\right)\right\rangle \\
\geq & \left\langle v-x_{n_{k}+1}, f\left(x_{n_{k}+1}\right)-f\left(y_{n_{k}}\right)\right\rangle+\left\langle v-x_{n_{k}+1}, \frac{1}{\lambda}\left(y_{n_{k}}-x_{n_{k}+1}\right)\right\rangle . \tag{26}
\end{align*}
$$

From (22), we have

$$
\begin{equation*}
\left\|f\left(x_{n_{k}+1}\right)-f\left(y_{n_{k}}\right)\right\| \leq \frac{1}{\alpha}\left\|x_{n_{k}+1}-y_{n_{k}}\right\| \rightarrow 0, \text { as } n \rightarrow \infty \tag{27}
\end{equation*}
$$

Also, from (23), we have that $\left\{x_{n_{k}+1}\right\}$ converges weakly to $z$. Thus, we obtain from (26) that

$$
\langle v-z, w\rangle \geq 0 .
$$

By the maximal monotonicity of $M+f$, we have that $0 \in(M+f) z$. That is, $z \in(M+f)^{-1}(0)$. Therefore, $z \in \Gamma$. We now show that $\left\{x_{n}\right\}$ converges strongly to $z$. From (15), we obtain

$$
\begin{align*}
\left\|x_{n+1}-z\right\|^{2} & \leq\left\|u_{n}-z\right\|^{2} \\
& =\left\|\left(1-\beta_{n}\right)\left(x_{n}-z\right)+\beta_{n}(u-z)\right\|^{2} \\
& =(1-\beta)^{2}\left\|x_{n}-z\right\|^{2}+\beta_{n}^{2}\|u-z\|^{2}+2 \beta_{n}\left(1-\beta_{n}\right)\left\langle x_{n}-z, u-z\right\rangle \\
& \leq\left(1-\beta_{n}\right)\left\|x_{n}-z\right\|^{2}+\beta_{n}\left[\beta_{n}\|u-z\|^{2}+2\left(1-\beta_{n}\right)\left\langle x_{n}-z, u-z\right\rangle\right] \tag{28}
\end{align*}
$$

Applying Lemma 2.7 to (28), we conclude that $\left\{x_{n}\right\}$ converges strongly to $z$.
Case 2. Assume that $\left\{\left\|x_{n}-x^{*}\right\|^{2}\right\}$ is not monotone decreasing. Set $\Gamma_{n}=\left\|x_{n}-x^{*}\right\|^{2}$ and let $\tau: \mathbb{N} \rightarrow \mathbb{N}$ be a mapping defined for all $n \geq n_{0}$ (for some large $n_{0}$ ) by

$$
\tau(n):=\max \left\{k \in \mathbb{N}: k \leq n, \Gamma_{k} \leq \Gamma_{k+1}\right\} .
$$

Then, by Lemma 2.9, we have that $\{\tau(n)\}$ is a non-decreasing sequence such that $\tau(n) \rightarrow \infty$, as $n \rightarrow \infty$ and

$$
\Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}, \forall n \geq n_{0}
$$

From (18), we have

$$
\begin{align*}
\alpha_{\tau(n)}\left(1-\alpha_{\tau(n)}\right)\left\|u_{\tau(n)}-T_{\tau(n)} u_{\tau(n)}\right\|^{2} & \leq\left\|x_{\tau(n)}-p\right\|^{2}-\left\|x_{\tau(n)+1}-p\right\|^{2}+\beta_{\tau(n)}\|u-p\|^{2}-\beta_{\tau(n)}\left\|x_{\tau(n)}-p\right\|^{2} \\
& \leq \beta_{\tau(n)}\left(\|u-p\|^{2}-\left\|x_{\tau(n)}-p\right\|^{2}\right) \rightarrow 0, \text { as } n \rightarrow \infty . \tag{29}
\end{align*}
$$

By condition on $\left\{\alpha_{\tau(n)}\right\}$, we obtain

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|u_{\tau(n)}-T_{\tau(n)} u_{\tau(n)}\right\|^{2}=0 \tag{30}
\end{equation*}
$$

Also, from (22), we have

$$
\begin{align*}
\left\|x_{\tau(n)+1}-y_{\tau(n)}\right\|^{2} & \leq\left(\left\|x_{\tau(n)}-p\right\|^{2}-\left\|x_{\tau(n)+1}-p\right\|^{2}\right)+\beta_{\tau(n)}\left(\|u-p\|^{2}-\left\|x_{\tau(n)}-p\right\|^{2}\right) \\
& \leq \beta_{\tau(n)}\left(\|u-p\|^{2}-\left\|x_{\tau(n)}-p\right\|^{2}\right) \rightarrow 0, \text { as } n \rightarrow \infty . \tag{31}
\end{align*}
$$

Following the same line of argument as in Case 1, we can show that $\left\{x_{\tau(n)}\right\}$ converges weakly to $z \in \Gamma$.

Now for all $n \geq n_{0}$, we have from (28) that

$$
\begin{aligned}
0 & \leq\left\|x_{\tau(n)+1}-z\right\|^{2}-\left[\left\|x_{\tau(n)}-z\right\|^{2}\right. \\
& \leq\left(1-\beta_{\tau(n)}\right)\left\|x_{\tau(n)}-z\right\|^{2}+\beta_{\tau(n)}\left[\beta_{\tau(n)}\|u-z\|^{2}+2\left(1-\beta_{\tau(n)}\right)\left\langle x_{\tau(n)}-z, u-z\right\rangle\right]-\left\|x_{\tau(n)}-z\right\|^{2},
\end{aligned}
$$

which implies

$$
\left\|x_{\tau(n)}-z\right\|^{2} \leq \beta_{\tau(n)}\|u-z\|^{2}+2\left(1-\beta_{\tau(n)}\right)\left\langle x_{\tau(n)}-z, u-z\right\rangle \rightarrow 0, \text { as } n \rightarrow \infty .
$$

Hence

$$
\lim _{n \rightarrow \infty}\left\|x_{\tau(n)}-z\right\|^{2}=0
$$

Therefore,

$$
\lim _{n \rightarrow \infty} \Gamma_{\tau(n)}=\lim _{n \rightarrow \infty} \Gamma_{\tau(n)+1}=0
$$

Moreover, for $n \geq n_{0}$, it is clear that $\Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}$ if $n \neq \tau(n)$ (that is $\left.\tau(n)<n\right)$ because $\Gamma_{j}>\Gamma_{j+1}$ for $\tau(n)+1 \leq j \leq n$.
Consequently for all $n \geq n_{0}$,

$$
0 \leq \Gamma_{n} \leq \max \left\{\Gamma_{\tau(n)}, \Gamma_{\tau(n)+1}\right\}=\Gamma_{\tau(n)+1} .
$$

Thus, $\lim _{n \rightarrow \infty} \Gamma_{n}=0$. That is $\left\{x_{n}\right\}$ converges strongly to $z$.
If $S$ is a nonexpansive mapping defined on $H_{2}$, then we obtain the following result.
Corollary 3.3. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $M: H_{1} \rightarrow 2^{H_{1}}$ be multivalued maximal monotone mapping and $f: H_{1} \rightarrow H_{1}$ be an $\alpha$-inverse strongly monotone mapping. Let $S: H_{2} \rightarrow H_{2}$ be a nonexpansive mapping. Assume that $\Gamma=\left\{z \in(M+f)^{-1}(0): A z \in F(S)\right\} \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in H_{1}$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{32}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}(I-S) A u_{n}\right) \\
x_{n+1}=J_{\lambda}^{M}(I-\lambda f) y_{n}, n \geq 1
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), \lambda \in(0,2 \alpha)$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Gamma$.

In view of Remark 1.3, we obtain the following result.
Corollary 3.4. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A$ : $H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $f: C \rightarrow H_{1}$ be an $\alpha$-inverse strongly monotone mapping and $S: H_{2} \rightarrow H_{2}$ be $\mu$-strictly pseudocontractive mapping. Assume that $\Gamma=\{z \in \operatorname{VIP}(C, f): A z \in F(S)\} \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in C$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{33}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}(I-S) A u_{n}\right) \\
x_{n+1}=P_{C}(I-\lambda f) y_{n}, n \geq 1
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), \lambda \in(0,2 \alpha)$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Gamma$.

Proof. From Theorem 3 of [36], we have that $\left(f+N_{C}\right)^{-1}(0)=V I P(C, f)$, where $N_{C}$ is the normal cone of $C$. Thus, by setting $M=N_{C}$ in Theorem 3.2, we obtain the desired result.

In the following Theorem, we study the class of SMVIP introduced by Moudafi [34].

Theorem 3.5. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $M_{1}: H_{1} \rightarrow 2^{H_{1}}$ and $M_{2}: H_{2} \rightarrow 2^{H_{2}}$ be multivalued maximal monotone mappings. Let $f: H_{1} \rightarrow H_{1}$ be $\alpha$-inverse strongly monotone mapping and $g: H_{2} \rightarrow H_{2}$ be $\beta$-inverse strongly monotone mapping. Assume that $\Gamma=\left\{z \in\left(M_{1}+f\right)^{-1}(0): A z \in\left(M_{2}+g\right)^{-1}(0)\right\} \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in H_{1}$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{34}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}\left(I-J_{\lambda}^{M_{2}}(I-\lambda g)\right) A u_{n}\right) \\
x_{n+1}=J_{\lambda}^{M_{1}}(I-\lambda f) y_{n}, n \geq 1
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), 0<\lambda<2 \alpha, 2 \beta$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Gamma$.

Proof. We know that, for any $\lambda>0, F\left(J_{\lambda}^{M_{2}}(I-\lambda g)\right)=\left(M_{2}+g\right)^{-1}(0)$ and for $\lambda \in(0,2 \beta), J_{\lambda}^{M_{2}}(I-\lambda g)$ is nonexpansive. Thus, setting $S=J_{\lambda}^{M_{2}}(I-\lambda g)$ in Corollary 3.3, we obtain the desired result.

By setting $M_{1}=N_{C}$ and $M_{2}=N_{Q}$ in Theorem 3.5, where $N_{C}$ and $N_{Q}$ are the normal cones of $C$ and $Q$ respectively, we obtain the following result.

Corollary 3.6. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $f: H_{1} \rightarrow H_{1}$ be $\alpha$-inverse strongly monotone mapping and $g: Q \rightarrow H_{2}$ be $\beta$-inverse strongly monotone mapping. Assume that $\Gamma=\{z \in \operatorname{VIP}(C, f): A z \in \operatorname{VIP}(Q, g)\} \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in C$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{35}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}\left(I-P_{Q}(I-\lambda g)\right) A u_{n}\right) \\
x_{n+1}=P_{C}(I-\lambda f) y_{n}, n \geq 1
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), 0<\lambda<2 \alpha, 2 \beta$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Gamma$.

## 4. Application to Split convex minimization problems

Let $F: H \rightarrow \mathbb{R}$ be a convex and differentiable function, and $M: H \rightarrow(-\infty,+\infty]$ be a proper convex and lower semi-continuous function. We know that if $\nabla F$ is $\frac{1}{\alpha}$-Lipschitz continuous, then it is $\alpha$-inverse strongly monotone, where $\nabla F$ is the gradient of $F$ (see Remark 1.1). It is also known that the subdifferential $\partial M$ of $M$ is maximal monotone (see [36]). Moreover,

$$
F\left(x^{*}\right)+M\left(x^{*}\right)=\min _{x \in H}[F(x)+M(x)] \Leftrightarrow 0 \in \nabla F\left(x^{*}\right)+\partial M\left(x^{*}\right)
$$

Now, consider the following class of Split Convex Minimization Problem (SCMP): Find

$$
\begin{equation*}
x^{*} \in H_{1} \text { such that } F\left(x^{*}\right)+M\left(x^{*}\right)=\min _{x \in H_{1}}[F(x)+M(x)], \text { and such that } A x^{*} \in F(S), \tag{36}
\end{equation*}
$$

where $A: H_{1} \rightarrow H_{2}$ is a bounded linear operator, $F$ and $M$ is as defined above, $S: H_{2} \rightarrow H_{2}$ is a strictly pseudocontractive mapping. Suppose the solution set of problem (36) is $\Omega$, then setting $M=\partial M$ and $f=\nabla F$ in Theorem 3.2, we obtain the following result.

Theorem 4.1. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces, and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $F: H_{1} \rightarrow \mathbb{R}$ be a convex and differentiable function such that $\nabla F$ is $\frac{1}{\alpha}$-Lipschitz continuous, and $M: H_{1} \rightarrow(-\infty,+\infty]$ be a proper convex and lower semi-continuous
function. Let $S: H_{2} \rightarrow H_{2}$ be $\mu$-strictly pseudocontractive mapping. Suppose $\Omega \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in H_{1}$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u,  \tag{37}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}(I-S) A u_{n}\right), \\
x_{n+1}=J_{\lambda}^{\partial M}(I-\lambda \nabla F) y_{n}, n \geq 1,
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), 0<\lambda<2 \alpha, 2 \beta$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Omega$.
Next, we consider the following class of SCMP: Find

$$
\begin{equation*}
x^{*} \in H_{1} \text { such that } F\left(x^{*}\right)+M_{1}\left(x^{*}\right)=\min _{x \in H_{1}}\left[F(x)+M_{1}(x)\right] \tag{38}
\end{equation*}
$$

and such that $y^{*}=A x^{*} \in H_{2}$, solves

$$
\begin{equation*}
G\left(x^{*}\right)+M_{2}\left(x^{*}\right)=\min _{x \in H_{2}}\left[G(x)+M_{2}(x)\right] . \tag{39}
\end{equation*}
$$

Suppose the solution set of problem (38)-(38) is $\Omega$, then setting $M_{1}=\partial M_{1}, M_{2}=\partial M_{2}, f=\nabla F$ and $g=\nabla G$ in Theorem 3.5, we obtain the following result.

Theorem 4.2. Let $H_{1}$ and $H_{2}$ be real Hilbert spaces, and $C$ be a nonempty closed and convex subset of $H_{1}$. Let $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator such that $A \neq 0$. Let $M_{1}: H_{1} \rightarrow(-\infty,+\infty]$ and $M_{2}: H_{2} \rightarrow(-\infty,+\infty]$ be proper convex and lower semi-continuous functions. Let $F: H_{1} \rightarrow H_{1}$ be convex and differentiable function such that $\nabla F$ is $\frac{1}{\alpha}$-Lipschitz continuous and $G: H_{2} \rightarrow H_{2}$ be convex and differentiable function such that $\nabla G$ is $\frac{1}{\beta}$-Lipschitz continuous. Assume that $\Omega \neq \emptyset$ and the sequence $\left\{x_{n}\right\}$ be generated for arbitrary $x_{1}, u \in H_{1}$ by

$$
\left\{\begin{array}{l}
u_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} u  \tag{40}\\
y_{n}=P_{C}\left(u_{n}-\gamma_{n} A^{*}\left(I-J_{\lambda}^{\partial M_{2}}(I-\lambda \nabla G)\right) A u_{n}\right) \\
x_{n+1}=J_{\lambda}^{\partial M_{1}}(I-\lambda \nabla F) y_{n}, n \geq 1
\end{array}\right.
$$

where $\left\{\gamma_{n}\right\} \subset[a, b]$ for some $a, b \in\left(0, \frac{1}{\|A\|^{2}}\right), 0<\lambda<2 \alpha, 2 \beta$ and $\left\{\beta_{n}\right\} \subset(0,1)$ such that $\lim _{n \rightarrow \infty} \beta_{n}=0$ and $\sum_{n=1}^{\infty} \beta_{n}=\infty$. Then, the sequence $\left\{x_{n}\right\}$ converges strongly to an element of $\Omega$.

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[^0]:    2010 Mathematics Subject Classification. Primary 47H09; Secondary 47H10, 49J20, 49J40
    Keywords. Monotone variational inclusion problem; variational inequality problem; convex minimization problem; strictly pseudocontractive mapping; maximal monotone mapping.

    Received: 28 July 2017; Accepted: 18 October 2017
    Communicated by Naseer Shahzad
    Email addresses: jerryezeora@yahoo.com (Jeremiah Nkwegu Ezeora), izuchukwuc@ukzn. ac.za; izuchukwu_c@yahoo.com (Chinedu Izuchukwu)

