



About Almost Geodesic Curves

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Abstract. We determine in \mathbb{R}^n the form of curves C for which also any image under an $(n - 1)$ -dimensional algebraic torus is an almost geodesic with respect to an affine connection ∇ with constant coefficients and calculate the components of ∇ .

1. Introduction

This paper is a result following on from D. Betten researchs [4] and our papers [1, 8–10].

The geodesics and almost geodesics play an important role in differential geometry. For this reason many geometricians study almost geodesic mappings (see [3], [14], [17]). In [12], [13] almost geodesic curves were considered in generalized Riemannian and Kählerian spaces. E. Beltrami [6] has shown that a differentiable curve is a local geodesic with respect to an affine connection ∇ precisely if it is a solution of an Abelian differential equation with coefficients which are functions of the components of ∇ . The investigation with systems of lines of 2-dimensional topological geometries was started in [15]. The explicit calculation of the form of curves C in the n -dimensional real space \mathbb{R}^n which are geodesics or almost geodesics with respect to an affine connection ∇ is not achievable even in the case if the components Γ_{ij}^h of ∇ are constant. But we did it. In [2] the geodesics and special case of almost geodesics were considered. We supposed that with C also all images of C under a real $(n - 1)$ -dimensional algebraic torus are also geodesics, respectively almost geodesics. This implies that the determination of C becomes an algebraic problem (a problem of polynomial identities). Our model allows you to look at known things globally. In this paper we continue to study almost geodesic curves [7], [16] and here we will consider other case.

We consider a curve C homeomorphic to \mathbb{R} which is a closed subset of \mathbb{R}^n and has the form

$$C = (t, f_2(t), \dots, f_n(t)), t \in \mathbb{R}, \quad (1)$$

where $f_i(t): \mathbb{R} \rightarrow \mathbb{R}$, $i = 2, \dots, n$, are three times differentiable non-constant functions. The system

$$\mathfrak{X}(C) = \{(t + c_1, b_2 f_2(t) + c_2, \dots, b_n f_n(t) + c_n), t \in \mathbb{R}\}, \text{ where } b_i \neq 0, c_i \in \mathbb{R},$$

is a set of images of C .

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If every curve of $\mathfrak{X}(C)$ is a geodesic with respect to an affine connection ∇ with constant coefficients Γ_{ij}^h , then the derivatives $f'_i(t)$ of the functions $f_i(t)$ are solutions of the first order linear ordinary differential equations. If every curve of $\mathfrak{X}(C)$ is an almost geodesic with respect to ∇ , then the derivatives $f'_i(t)$ are solutions of harmonic oscillator equations. If $\mathfrak{X}(C)$ consists of Euclidean lines which are geodesics with respect to ∇ , then at the most Γ_{11}^1 may be different from 0. In contrast to this if $\mathfrak{X}(C)$ consists of Euclidean lines then there is huge quantity of non-trivial connections ∇ such that the lines of $\mathfrak{X}(C)$ are almost geodesic with respect to ∇ .

Since we apply results of differential geometry only for the n -dimensional space \mathbb{R}^n , where global coordinates exist and the components Γ_{ij}^h , $h, i, j \in \{1, 2, \dots, n\}$, of any affine connection ∇ can be written in unique way in these coordinates.

Remark 1.1. If coefficients Γ_{ij}^h of an affine connection ∇ are constants then there exist groups of affine movements.

Remark 1.2. It is possible to apply our model for other spaces, because a geodesic and an almost geodesic can be defined in other spaces in the same manner as in \mathbb{R}^n [11].

2. Almost geodesic curves

Let

$$\ell = (t + c_1, b_2 f_2(t) + c_2, \dots, b_n f_n(t) + c_n), \quad t \in \mathbb{R},$$

be a curve of $\mathfrak{X}(C)$. Then

$$\dot{\ell} = (1, b_2 f'_2(t), \dots, b_n f'_n(t)), \quad \ddot{\ell} = (0, b_2 f''_2(t), \dots, b_n f''_n(t)).$$

By an *almost geodesic* of an affine connection ∇ we mean a piecewise C^3 -curve $\gamma: I \rightarrow \mathbb{R}^n$ satisfying

$$\nabla_{\dot{\gamma}}(\nabla_{\dot{\gamma}}\dot{\gamma}) = \varrho \cdot \dot{\gamma} + \sigma \cdot \nabla_{\dot{\gamma}}\dot{\gamma},$$

where $\varrho, \sigma: I \rightarrow \mathbb{R}$ are continuous functions, $I \subset \mathbb{R}$ is an open interval (cf. [16, p. 158], [7, p. 456]).

Using the components of ∇ the system of differential equations for almost geodesics has the form

$$\ddot{\gamma}^h + \sum_{i,j,k=1}^n (\partial_k \Gamma_{ij}^h + \Gamma_{ij}^\ell \Gamma_{\ell k}^h) \dot{\gamma}^i \dot{\gamma}^j \dot{\gamma}^k + 2 \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\gamma}^i \dot{\gamma}^j + \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\gamma}^i \dot{\gamma}^j = \varrho(t) \cdot \dot{\gamma}^h + \sigma(t) \cdot (\dot{\gamma}^h + \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\gamma}^i \dot{\gamma}^j). \quad (2)$$

A curve ℓ of $\mathfrak{X}(C)$ is an almost geodesic with respect to a connection ∇ with constant coefficients $\{\Gamma_{ij}^h\}$ if and only if according to (2) we have

$$\ddot{\ell}^h + \sum_{i,j,k=1}^n \Gamma_{ij}^\ell \Gamma_{\ell k}^h \dot{\ell}^i \dot{\ell}^j \dot{\ell}^k + 2 \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\ell}^i \dot{\ell}^j + \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\ell}^i \dot{\ell}^j = \varrho(t) \cdot \dot{\ell}^h + \sigma(t) \cdot (\dot{\ell}^h + \sum_{i,j=1}^n \Gamma_{ij}^h \dot{\ell}^i \dot{\ell}^j). \quad (3)$$

We rewrite the formula (3) for $h = 1$ and obtain the function $\varrho(t)$. For $h = 2, \dots, n$ after substitution $\varrho(t)$ in (3) we get

$$\begin{aligned} b_h f_h'''(t) + \sum_{m=1}^n \Gamma_{m1}^h \Gamma_{11}^m + \sum_{i=2, m=1}^n (\Gamma_{mi}^h \Gamma_{11}^m + \Gamma_{m1}^h \Gamma_{i1}^m + \Gamma_{m1}^h \Gamma_{1i}^m) b_i f_i'(t) + \\ \sum_{i,j=2, m=1}^n (\Gamma_{mi}^h \Gamma_{j1}^m + \Gamma_{mi}^h \Gamma_{1j}^m + \Gamma_{m1}^h \Gamma_{ij}^m) b_i b_j f_i'(t) f_j'(t) + \\ \sum_{i,j,k=2, m=1}^n \Gamma_{mi}^h \Gamma_{jk}^m b_i b_j b_k f_i'(t) f_j'(t) f_k'(t) + \end{aligned}$$

$$\begin{aligned} & \sum_{i=2}^n (2\Gamma_{i1}^h + \Gamma_{1i}^h) b_i f_i''(t) + \sum_{i,j=2}^n (2\Gamma_{ij}^h + \Gamma_{ji}^h) b_i b_j f_i''(t) f_j'(t) - \\ & b_h f_h'(t) \left(\sum_{m=1}^n \Gamma_{m1}^1 \Gamma_{11}^m + \sum_{i=2,m=1}^n (\Gamma_{mi}^1 \Gamma_{11}^m + \Gamma_{m1}^1 \Gamma_{i1}^m + \Gamma_{m1}^1 \Gamma_{1i}^m) b_i f_i'(t) + \right. \\ & \sum_{i,j=2,m=1}^n (\Gamma_{mi}^1 \Gamma_{j1}^m + \Gamma_{mi}^1 \Gamma_{1j}^m + \Gamma_{m1}^1 \Gamma_{ij}^m) b_i b_j f_i'(t) f_j'(t) + \\ & \left. \sum_{i,j,k=2,m=1}^n \Gamma_{mi}^1 \Gamma_{jk}^m b_i b_j b_k f_i'(t) f_j'(t) f_k'(t) + \right. \\ & \left. \sum_{i=2}^n (2\Gamma_{i1}^1 + \Gamma_{1i}^1) b_i f_i''(t) + \sum_{i,j=2}^n (2\Gamma_{ij}^1 + \Gamma_{ji}^1) b_i b_j f_i''(t) f_j'(t) \right) = \\ & \sigma(t) \cdot \left(\Gamma_{11}^h - \Gamma_{11}^1 + 2 \sum_{i=2}^n (\Gamma_{1i}^h + \Gamma_{i1}^h - \Gamma_{1i}^1 - \Gamma_{i1}^1) b_i f_i'(t) + \sum_{i,j=2}^n (\Gamma_{ij}^h - \Gamma_{ij}^1) b_i b_j f_i'(t) f_j'(t) \right). \end{aligned} \tag{4}$$

One can determine σ only if not all coefficients in (4) are zero. In [2] we treated the case that for $h \geq 2$ one has

$$\Gamma_{i1}^h + \Gamma_{1i}^h = \Gamma_{i1}^1 + \Gamma_{1i}^1, \quad i \geq 1, \quad \text{and} \quad \Gamma_{ij}^h = \Gamma_{ij}^1 \quad \text{for all } i, j \geq 2.$$

Now let an α and i_0, j_0 such that for these indices we have

$$\Gamma_{11}^\alpha \neq \Gamma_{11}^1 \text{ or } \Gamma_{i_0 1}^\alpha + \Gamma_{1 i_0}^\alpha \neq \Gamma_{i_0 1}^1 + \Gamma_{1 i_0}^1, \text{ or } \Gamma_{i_0 j_0}^\alpha \neq \Gamma_{i_0 j_0}^1, \quad i_0, j_0 \geq 2. \tag{5}$$

In this case the coefficient of σ is not identically zero, and we can compute σ . Putting the expression of σ into relation (4) we obtain

$$\begin{aligned} & \left((\Gamma_{11}^\alpha - \Gamma_{11}^1) + 2(\Gamma_{1i_0}^\alpha + \Gamma_{i_0 1}^\alpha - \Gamma_{1i_0}^1 - \Gamma_{i_0 1}^1) f_{i_0}' b_{i_0} + (\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1) f_{i_0}' f_{j_0}' b_{i_0} b_{j_0} \right) \cdot \\ & \left(T_{h111} + (f_h''' - T_{1111} f_h') b_h + \sum_{i=2}^n (S_{h11i} f_i' + (2\Gamma_{i1}^h + \Gamma_{1i}^h) f_i'') b_i - \right. \\ & \sum_{i=2}^n (S_{1i11} f_i' + (2\Gamma_{i1}^1 + \Gamma_{1i}^1) f_i'') f_i' b_h b_i + \sum_{i,j=2}^n (S_{hij1} f_i' f_j' + (2\Gamma_{ij}^h + \Gamma_{ji}^h) f_i' f_j'') b_i b_j - \\ & \sum_{i,j=2}^n (S_{11ij} f_i' f_j' + (2\Gamma_{ij}^1 + \Gamma_{ji}^1) f_i' f_j'') f_i' b_h b_i b_j + \sum_{i,j,k=2}^n T_{hijk} f_i' f_j' f_k' b_i b_j b_k - \sum_{i,j,k=2}^n T_{1ijk} f_i' f_j' f_k' b_h b_i b_j b_k \left. \right) = \\ & \left((\Gamma_{11}^h - \Gamma_{11}^1) + 2 \sum_{i=2}^n (\Gamma_{1i}^h + \Gamma_{i1}^h - \Gamma_{1i}^1 - \Gamma_{i1}^1) f_i' b_i + \sum_{i,j=2}^n (\Gamma_{ij}^h - \Gamma_{ij}^1) f_i' f_j' b_i b_j \right) \cdot \\ & \left(T_{\alpha 111} + (f_\alpha''' - T_{1111} f_\alpha') b_\alpha + (S_{\alpha 11 i_0} f_{i_0}' + (2\Gamma_{i_0 1}^\alpha + \Gamma_{1 i_0}^\alpha) f_{i_0}'') b_{i_0} - (S_{1 i_0 11} f_{i_0}' + (2\Gamma_{i_0 1}^1 + \Gamma_{1 i_0}^1) f_{i_0}'') f_\alpha' b_h b_{i_0} + \right. \\ & (S_{\alpha i_0 j_0 1} f_{i_0}' f_{j_0}' + (2\Gamma_{i_0 j_0}^\alpha + \Gamma_{j_0 i_0}^\alpha) f_{i_0}' f_{j_0}'') f_{i_0}' b_{i_0} b_{j_0} - (S_{1 i_0 j_0} f_{i_0}' f_{j_0}' + (2\Gamma_{i_0 j_0}^1 + \Gamma_{j_0 i_0}^1) f_{i_0}' f_{j_0}'') f_\alpha' f_{j_0}' b_\alpha b_{i_0} b_{j_0} + \\ & \left. \sum_{k=2}^n T_{\alpha i_0 j_0 k} f_{i_0}' f_{j_0}' f_k' b_{i_0} b_{j_0} b_k - \sum_{k=2}^n T_{1 i_0 j_0 k} f_\alpha' f_{i_0}' f_{j_0}' f_k' b_\alpha b_{i_0} b_{j_0} b_k \right), \end{aligned} \tag{6}$$

where

$$S_{ABCD} \stackrel{\text{def}}{=} \sum_{m=1}^n \left(\Gamma_{mD}^A \Gamma_{BC}^m + \Gamma_{mB}^A (\Gamma_{DC}^m + \Gamma_{CD}^m) \right),$$

$$T_{ABCD} \stackrel{\text{def}}{=} \sum_{m=1}^n \Gamma_{mB}^A \Gamma_{CD}^m.$$

If $n = 2$, then $h = \alpha = 2$ and from (6) we obtain that any plane curve of the system $\mathfrak{X}(C)$, where C has the form (1), is an almost geodesic if the affine connection Γ_{ij}^h satisfies the conditions (5). Hence we assume $n \geq 3$.

Now we consider the first case, when

$$\Gamma_{11}^h = \Gamma_{11}^1 \text{ for all } 2 \leq h \leq n \text{ and } \Gamma_{i1}^h + \Gamma_{1i}^h = \Gamma_{i1}^1 + \Gamma_{1i}^1 \text{ for all } 2 \leq i \leq n, \tag{7}$$

but there exists an α and i_0, j_0 such that

$$\Gamma_{i_0 j_0}^\alpha \neq \Gamma_{i_0 j_0}^1. \tag{8}$$

Writing a system of equations and conditions which follow from (6) and using linear independence functions we get differential equations. Integrating them (see. [5]) we obtain the following

Theorem 2.1. *Let C be a curve of the form (1) and ∇ be a connection with constant coefficients $\{\Gamma_{ij}^h\}$ satisfying relations (7), (8).*

Then any curve ℓ of $\mathfrak{X}(C)$ is almost geodesic with respect to ∇ if and only if ℓ is represented by the functions f_h, f_α, f_{i_0} having the following forms

- * $f_h(t) = \hat{C}_h e^{\lambda_1^h t} + \hat{D}_h e^{\lambda_2^h t}$, where $\hat{C}_h, \hat{D}_h \in \mathbb{R}$ are not both zero and $a_h^2 - 4c_h > 0$,
- * $f_h(t) = (\tilde{C}_h t + \tilde{D}_h) e^{-\frac{a_h}{2} t}$, where $\tilde{C}_h, \tilde{D}_h \in \mathbb{R}$ are not both zero and $a_h^2 - 4c_h = 0$,
- * $f_h(t) = e^{-a_h t/2} \left(\bar{C}_h \cos \frac{\sqrt{a_h^2 - 4c_h}}{2} t + \bar{D}_h \sin \frac{\sqrt{a_h^2 - 4c_h}}{2} t \right)$, where $\bar{C}_h, \bar{D}_h \in \mathbb{R}$ are not both zero and $a_h^2 - 4c_h < 0$

with

$$a_h = 2\Gamma_{h1}^h + \Gamma_{1h}^h, \quad c_h = S_{h11h} - T_{1111},$$

$$\lambda_1^h = \frac{-a_h - \sqrt{a_h^2 - 4c_h}}{2}, \quad \lambda_2^h = \frac{-a_h + \sqrt{a_h^2 - 4c_h}}{2};$$

- * $f_\alpha(t) = C_\alpha t^2 + D_\alpha t + E$, where $C_\alpha, D_\alpha, E \in \mathbb{R}$, C_α, D_α are not both zero and $\gamma_\alpha = 0$,
- * $f_\alpha(t) = \hat{C}_\alpha e^{\sqrt{-\gamma_\alpha} t} - \hat{D}_\alpha e^{-\sqrt{-\gamma_\alpha} t}$, where $\hat{C}_\alpha, \hat{D}_\alpha \in \mathbb{R}$ are not both zero and $\gamma_\alpha < 0$,
- * $f_\alpha(t) = \hat{C}_\alpha \sin(\sqrt{\gamma_\alpha} t) - \hat{D}_\alpha \cos(\sqrt{\gamma_\alpha} t)$, where $\hat{C}_\alpha, \hat{D}_\alpha \in \mathbb{R}$ are not both zero and $\gamma_\alpha > 0$

with

$$\gamma_\alpha = \frac{(\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1)(T_{h\alpha ij} + T_{h\alpha ji} + T_{hi\alpha j} + T_{hi\alpha j} + T_{hj\alpha i} + T_{hj\alpha i})}{\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h} - T_{1111};$$

- * $f_{i_0}(t) = \hat{C}_{i_0} e^{\lambda_1^{i_0} t} + \hat{D}_{i_0} e^{\lambda_2^{i_0} t}$, where $\hat{C}_{i_0}, \hat{D}_{i_0} \in \mathbb{R}$ are not both zero and $a_{i_0}^2 - 4c_{i_0} > 0$,
- * $f_{i_0}(t) = (\tilde{C}_{i_0} t + \tilde{D}_{i_0}) e^{-\frac{a_{i_0}}{2} t}$, where $\tilde{C}_{i_0}, \tilde{D}_{i_0} \in \mathbb{R}$ are not both zero and $a_{i_0}^2 - 4c_{i_0} = 0$,
- * $f_{i_0}(t) = e^{-a_{i_0} t/2} \left(\bar{C}_{i_0} \cos \frac{\sqrt{a_{i_0}^2 - 4c_{i_0}}}{2} t + \bar{D}_{i_0} \sin \frac{\sqrt{a_{i_0}^2 - 4c_{i_0}}}{2} t \right)$, where $\bar{C}_{i_0}, \bar{D}_{i_0} \in \mathbb{R}$ are not both zero and $a_{i_0}^2 - 4c_{i_0} < 0$

with

$$a_{i_0} = 2\Gamma_{i_0 1}^{i_0} + \Gamma_{1 i_0}^{i_0},$$

$$c_{i_0} = \frac{(\Gamma_{i_0 j_0}^{i_0} - \Gamma_{i_0 j_0}^1)(T_{hi_0ij} + T_{hi_0ji} + T_{hii_0j} + T_{hij_0i} + T_{hj_0i_0} + T_{hj_0i_0})}{\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h} + S_{i_0 11 i_0} - T_{1111},$$

$$\lambda_1^{i_0} = \frac{-a_{i_0} - \sqrt{a_{i_0}^2 - 4c_{i_0}}}{2}, \quad \lambda_2^{i_0} = \frac{-a_{i_0} + \sqrt{a_{i_0}^2 - 4c_{i_0}}}{2}.$$

The components $\{\Gamma_{ij}^h\}$ of affine connection ∇ satisfy the following relations

$$2\Gamma_{ij}^1 + \Gamma_{ji}^1 = 0, \quad 2\Gamma_{i_0 j_0}^\alpha + \Gamma_{j_0 i_0}^\alpha = 0, \quad 2\Gamma_{ij}^h + \Gamma_{ji}^h = 0, \quad 2\Gamma_{i_0 i}^{i_0} + \Gamma_{i i_0}^{i_0} = 0,$$

$$\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^k - \Gamma_{ji}^k = 0 \text{ for } k = i_0, \alpha, \quad 2\Gamma_{ik}^k + \Gamma_{ki}^k - 2\Gamma_{i1}^1 - \Gamma_{1i}^1 = 0 \text{ for } k = i_0, h,$$

$$(\Gamma_{ij_0}^1 + \Gamma_{j_0 i}^1 - \Gamma_{ij_0}^h - \Gamma_{j_0 i}^h)S_{1i_0 11} = 0, \quad (\Gamma_{ij_0}^1 + \Gamma_{j_0 i}^1 - \Gamma_{ij_0}^h - \Gamma_{j_0 i}^h)(2\Gamma_{i_0 1}^1 + \Gamma_{1 i_0}^1) = 0,$$

$$(\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h)(2\Gamma_{i_0 1}^\alpha + \Gamma_{1 i_0}^\alpha) = 0,$$

$$(\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1)(S_{hij1} + S_{hji1}) + (\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h)T_{\alpha 111} = 0,$$

$$(\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1)(T_{h111} + S_{hi_0 j_0 1} + S_{hj_0 i_0 1}) + (\Gamma_{i_0 j_0}^1 + \Gamma_{j_0 i_0}^1 - \Gamma_{i_0 j_0}^h - \Gamma_{j_0 i_0}^h)T_{\alpha 111} = 0,$$

$$(\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1)(S_{kki1} + S_{kik1} - S_{1i11}) + (\Gamma_{ik}^1 + \Gamma_{ki}^1 - \Gamma_{ik}^k - \Gamma_{ki}^k)T_{\alpha 111} = 0 \text{ for } k = i_0, h,$$

$$(\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h)T_{1i_0 j_0 k} + (\Gamma_{ik}^1 + \Gamma_{ki}^1 - \Gamma_{ik}^h - \Gamma_{ki}^h)T_{1i_0 j_0 j} +$$

$$(\Gamma_{jk}^1 + \Gamma_{kj}^1 - \Gamma_{jk}^h - \Gamma_{kj}^h)T_{1i_0 j_0 i} = 0,$$

$$S_{i11h} = 2\Gamma_{h1}^i + \Gamma_{1h}^i = 0 \text{ if } f'_h \neq D_h e^{-\frac{a_h}{2}t}, \quad S_{i11h} = \frac{1}{2}a_h(2\Gamma_{h1}^i + \Gamma_{1h}^i) \text{ if } f'_h = D_h e^{-\frac{a_h}{2}t},$$

$$(\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h)(T_{\alpha i_0 j_0 \alpha} - S_{11 i_0 j_0}) + (\Gamma_{i\alpha}^1 + \Gamma_{\alpha i}^1 - \Gamma_{i\alpha}^h - \Gamma_{\alpha i}^h)T_{\alpha i_0 j_0 j} +$$

$$(\Gamma_{j\alpha}^1 + \Gamma_{\alpha j}^1 - \Gamma_{j\alpha}^h - \Gamma_{\alpha j}^h)T_{\alpha i_0 j_0 i} = 0,$$

$$(\Gamma_{i_0 j_0}^1 - \Gamma_{i_0 j_0}^\alpha)(T_{1i_0 j_0 i} + T_{1i_0 i j_0} + T_{1j_0 i_0 i} + T_{1j_0 i_0 i_0} + T_{1i_0 j_0 j_0} + T_{1i_0 j_0 i_0}) +$$

$$(\Gamma_{ki}^1 + \Gamma_{ik}^1 - \Gamma_{ki}^h - \Gamma_{ik}^h)S_{\alpha i_0 j_0 1} = 0 \text{ for } k = j_0, h,$$

$$(\Gamma_{i_0 j_0}^\alpha - \Gamma_{i_0 j_0}^1)(T_{hi_0ij} + T_{hi_0ji} + T_{hii_0j} + T_{hij_0i} + T_{hj_0i_0} + T_{hj_0i_0}) +$$

$$(\Gamma_{ij}^1 + \Gamma_{ji}^1 - \Gamma_{ij}^h - \Gamma_{ji}^h)S_{\alpha 11 i_0} = 0,$$

$$T_{i_0 111} - S_{1j_0 11} + S_{i_0 i_0 j_0 1} + S_{i_0 j_0 i_0 1} = 0,$$

$$T_{\alpha i_0 ij} + T_{\alpha i_0 ji} + T_{\alpha i_0 j_0} + T_{\alpha j_0 i_0} + T_{\alpha j_0 i} + T_{\alpha j_0 i_0} = 0,$$

$$T_{kkij} + T_{kkji} + T_{kikj} + T_{kijk} + T_{kjk i} + T_{kjk i} - S_{11ij} - S_{11jl} = 0 \text{ for } k = i_0, h, \alpha.$$

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