Filomat 36:1 (2022), 275–288 https://doi.org/10.2298/FIL2201275G



Published by Faculty of Sciences and Mathematics, University of Niš, Serbia Available at: http://www.pmf.ni.ac.rs/filomat

Warped Product Pointwise Hemi-Slant Submanifolds of a Para-Kaehler Manifold

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Abstract. In this paper, we introduce pointwise hemi-slant submanifolds of para-Kaehler manifolds. Using this notion, we investigate the geometry of warped product pointwise hemi-slant submanifolds. We provide some non-trivial examples of such submanifolds.

1. Introduction

The notion of slant submanifolds was introduced by Chen in [10], and the first results on slant submanifolds were collected in his book [11]. Since then, this subject has been studied extensively by many geometers during the last two and half decades. Also, the study of slant submanifolds in a pseudo-Riemannian manifold has been initiated:Chen and Mihai classified slant surfaces in Lorentzian complex space forms in [12]. Arslan et. al defined slant submanifols of a neutral Kaehler manifold in [6], while Alegre studied slant submanifolds of Lorentzian Sasakian and para-Sasakian manifolds in [1]. Recently, slant, bi-slant and quasi bi-slant submanifolds of (para)-Hermitian manifolds have been defined in [2, 3, 5]. As an extension of slant submanifolds, Etayo [17] defined the notion of pointwise slant submanifolds under the name of quasi-slant submanifolds.

On the other hand, Bishop and O'Neill started the concept of warped product which is one of the most effective generalizations of semi-Riemannian manifold. The notion of warped product has recognized various significant contributions in differential geometry as well as in physics, particularly in general theory of relativity [13, 26]. Since then, the study of warped product submanifolds has been investigated by many geometers (see, e.g., [4, 9, 15, 16, 18–21, 24, 25, 27–35] among many others, and for the most up-to-date overview of this subject, see [14]).

In this paper, we introduce pointwise hemi-slant submanifolds of para-Kaehler manifolds and using this notion, we investigate the geometry of warped product pointwise hemi-slant submanifolds of the form $N_{1\varphi} \times N_{2\perp}$ in a para-Kaehler manifold \tilde{N} , where $N_{2\perp}$ is a totally real submanifold and $N_{1\varphi}$ is a neutral proper poitwise slant submanifold of \tilde{N} with slant function φ .

In the present paper, in section 2, we give preliminaries and definitions needed for this paper. In section 3 we define and study pointwise hemi-slant submanifolds of para-Kaehler manifolds. Then, we give some non-trivial examples of pointwise hemi-slant submanifolds and investigate the geometry of the leaves

²⁰²⁰ Mathematics Subject Classification. Primary: 53C15; Secondary: 53C40

Keywords. Warped product, neutral pointwise slant submanifold, pointwise hemi-slant submanifold, para-Kaehler manifold Received: 24 January 2021; Accepted: 01 May 2021

Communicated by Mića S. Stanković

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of distributions. In section 4, we prove some preparatory results and obtain a necessary and sufficient condition for the existence of a submanifold of the form $N_{1\varphi} \times N_{2\perp}$ to be locally warped product and locally semi-Riemannian product. Also, we give some examples illustrating such submanifolds. In section 5 we describe the warped product submanifolds \tilde{N} by giving geometric inequalities in term of second fundamental form and warping function φ for the $N_{1\varphi} \times N_{2\perp}$ of a para-Kaehler manifold.

2. Preliminaries

Let (\tilde{N}, g) be an almost para-Hermitian manifold with almost para-complex structure P and a semi-Riemannian metric g such that

$$P^{2}Y_{1} = Y_{1}, \quad g(PY_{1}, PY_{2}) + g(Y_{1}, Y_{2}) = 0, \tag{1}$$

for all $Y_1, Y_2 \in \Gamma(T\tilde{N})$, where \tilde{V} denotes the Levi-Civita connection on \tilde{N} of the semi-Riemannian metric g. If the para-complex structure P satisfies

$$(\tilde{\nabla}_{Y_1}P)Y_2 = 0, \tag{2}$$

for all $Y_1, Y_2 \in \Gamma(T\tilde{N})$, then \tilde{N} is called a para-Kaehler manifold([23]).

Now, let *N* be a semi-Riemannian submanifold of (\tilde{N}, P, g) and we denote by the same symbol *g* the semi-Riemannian metric induced on *N*. Let $\Gamma(TN)$ be the Lie algebra of vector fields in *N* and $\Gamma(T^{\perp}N)$, the set of all vector fields normal to *N*. If ∇ be the induced Levi-Civita connection on *N*, then the Gauss and Weingarten formulas are given by:

$$\tilde{\nabla}_{Y_1} Y_2 = \nabla_{Y_1} Y_2 + \sigma(Y_1, Y_2), \tag{3}$$

$$\bar{\nabla}_{Y_1}Y_3 = -\mathcal{A}_{Y_3}Y_1 + \nabla^{\perp}_{Y_1}Y_3,\tag{4}$$

for any $Y_1, Y_2 \in \Gamma(TN)$ and $Y_3 \in \Gamma(T^{\perp}N)$, where ∇^{\perp} is the normal connection in the normal bundle $T^{\perp}N$ and \mathcal{A}_{Y_3} is the shape operator of N with respect to the normal vector Y_3 . Also, $\sigma : TN \times TN \to T^{\perp}N$ is the second fundamental form of N in \tilde{N} . Moreover \mathcal{A}_{Y_3} and σ are related by:

$$g(\sigma(Y_1, Y_2), Y_3) = g(\mathcal{A}_{Y_3}Y_1, Y_2)$$
(5)

for any $Y_1, Y_2 \in \Gamma(TN)$ and $Y_3 \in \Gamma(T^{\perp}N)$. For any Y_1 tangent to N we write

$$PY_1 = \alpha Y_1 + \beta Y_1, \tag{6}$$

where αY_1 and βY_1 are the tangential and normal parts of PY_1 , respectively. Also, for any $Y_3 \in \Gamma(T^{\perp}N)$, we get

$$PY_3 = \dot{\alpha}Y_3 + \dot{\beta}Y_3,\tag{7}$$

here αY_3 and βY_3 are the tangential and normal parts of PY_3 , respectively.

In [8], Chen and Garay introduced pointwise slant submanifold in a Kaehler manifold. Let *N* be a submanifold of a Kaehler manifold (\tilde{N} , *P*, *g*). Then the submanifold *N* is called pointwise slant submanifold if at each point $p \in N$, the slant angle $\varphi(Y_1)$ between PY_1 and T_pN is independent of the choice of the non-zero vector $Y_1 \in T_pN$. In this case, the slant angle gives rise to a real-valued function $\varphi : TN - \{0\} \rightarrow R$ which is called the slant function of the pointwise slant submanifold. If αY is the projection of PY_1 over *N*, they can be characterized as $\alpha^2 = \mu Id$.

We say that a semi-Riemannian submanifold N of a para-Hermitian manifold (\tilde{N}, P, q) is called a pointwise slant if for every non-lightlike $Y_1 \in \Gamma(TN)$, the quotient $g(\alpha Y_1, \alpha Y_1)/g(PY_1, PY_1)$ is non-constant. A submanifold is called invariant if it is a pointwise slant with slant function zero, that is if $g(\alpha Y_1, \alpha Y_1)/g(PY_1, PY_1) =$ 1 for all non-lightlike $Y_1 \in \Gamma(TN)$. It is called anti-invariant if $\alpha Y_1 = 0$ for all $Y_1 \in \Gamma(TN)$. In other cases, it is called a proper pointwise slant submanifolds.

Definition 2.1. Let N be a proper pointwise slant submanifold of a para-Hermitian manifold (\tilde{N}, P, q). We say that it is of

type 1 if for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$, αY_1 is timelike (spacelike), and $\frac{\|\alpha Y_1\|}{\|PY_1\|} > 1$, type 2 if for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$, αY_1 is timelike (spacelike), and $\frac{\|\alpha Y_1\|}{\|PY_1\|} < 1$.

The proof of the following result is the same as slant submanifolds (see [2]and [3]), therefore we omit its proof.

Theorem 2.2. Let N be a semi-Riemannian submanifold of a para-Hermitian manifold (\tilde{N} , P, q). Then, (i) N is a pointwise slant submanifold of type 1 if and only if for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$, αY_1 *is timelike (spacelike), and there exists a function* $\mu \in (1, \infty)$ *such that*

$$\alpha^2 Y_1 = \mu Y_1. \tag{8}$$

If φ denotes the slant function of N then $\mu = \cosh^2 \varphi$.

(ii) N is a pointwise slant submanifold of type 2 if and only if for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$, αY_1 is timelike (spacelike), and there exists a function $\mu \in (0, 1)$ such that

$$\alpha^2 Y_1 = \mu Y_1. \tag{9}$$

If φ denotes the slant function of N then $\mu = \cos^2 \varphi$.

In every case, a real-valued function φ is called the slant function of the proper pointwise slant submanifold. From the Theorem 2.2, we have:

Corollary 2.3. Let \mathcal{D} be a distribution on N. Then,

(i) \mathcal{D} is a proper pointwise slant of type 1 if and only if for any spacelike (timelike) vector field $Y_1 \in \Gamma(\mathcal{D})$, αY_1 is timelike (spacelike), and there exists a function $\mu \in (1, \infty)$ such that

$$(\alpha Q_{\varphi})^2 Y_1 = \mu Y_1 \tag{10}$$

where Q_{φ} denotes the orthogonal projection on \mathcal{D} . Also, in this case $\mu = \cosh^2 \varphi$. (ii) \mathcal{D} is a proper pointwise slant of type 2 if and only if for any spacelike (timelike) vector field $Y_1 \in \Gamma(\mathcal{D})$, αY_1 is *timelike (spacelike), and there exists a function* $\mu \in (0, 1)$ *such that*

$$(\alpha Q_{\varphi})^2 Y_1 = \mu Y_1 \tag{11}$$

where Q_{φ} denotes the orthogonal projection on \mathcal{D} . Also, in this case $\mu = \cos^2 \varphi$.

In every case, a real-valued function φ is called the slant function of the proper pointwise slant distribution.

Let us point out that for both proper pointwise slant distributions of type 1 and 2, if Y_1 is a spacelike tangent vector field, then αY_1 is a timelike tangent vector field. So, all type 1, and type 2 proper pointwise slant distributions are neutral.

Remember that a para-holomorphic distribution satisfies $P\mathcal{D} = \mathcal{D}$, so every para-holomorphic distribution is a pointwise slant distribution with slant function zero. It is called a totally real distribution if $P\mathcal{D} \subseteq T^{\perp}N$, therefore every totaly distribution is anti-invariant.

If \mathcal{D} is a para-holomorphic distribution, then $\|\alpha Y_1\| = \|PY_1\|$, for all $Y_1 \in \Gamma(\mathcal{D})$. If \mathcal{D} is a totally real distribution, then $||\alpha Y_1|| = 0$, for all $Y_1 \in \Gamma(\mathcal{D})$.

3. Proper pointwise hemi-slant submanifolds

In this section we define and study proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N}, P, g) .

Definition 3.1. A semi-Riemannian submanifold N of a para-Hermitian (\tilde{N} , P, g) is called a pointwise bi-slant submanifold if the tangent space admits a decomposition $TN = \mathcal{D}_{\varphi} \oplus \mathcal{D}_{\omega}$ with both \mathcal{D}_{φ} and \mathcal{D}_{ω} pointwise slant distributions with slant functions φ and ω .

It is called a pointwise semi-slant submanifold if the tangent space admits a decomposition $TN = \mathcal{D}_{\tau} \oplus \mathcal{D}_{\varphi}$ with \mathcal{D}_{τ} a para-holomorphic distribution and \mathcal{D}_{φ} a proper pointwise slant distribution with slant function φ .

It is called a pointwise hemi-slant submanifold if the tangent space admits a decomposition $TN = \mathcal{D}_{\perp} \oplus \mathcal{D}_{\varphi}$ with \mathcal{D}_{\perp} a totally real distribution and \mathcal{D}_{φ} a proper pointwise slant distribution with slant function φ .

Note that given a pseudo-Euclidean space R_n^{2n} with coordinates $(x_1, ..., x_{2n})$ on R_n^{2n} , we can naturally choose an almost paracomplex structure *P* on R_n^{2n} as follows:

$$P(\frac{\partial}{\partial x_{2i}}) = \frac{\partial}{\partial x_{2i-1}}, \ P(\frac{\partial}{\partial x_{2i-1}}) = \frac{\partial}{\partial x_{2i}},$$

where i = 1, ..., n. Let R_n^{2n} be a pseudo-Euclidean space of signature (+, -, +, -, ...) with respect to the canonical basis $(\frac{\partial}{\partial x_1}, ..., \frac{\partial}{\partial x_{2n}})$.

Now, we can present some examples of proper pointwise hemi-slant submanifolds.

Example 3.2. Let N be a semi-Riemannian submanifold of R_4^8 defined by the immersion $\phi : N \to R_4^8$.

 $\phi(u, v, t, s) = (\sin u, \sin v, \cos u, \cos v, t, k_1, k_2, s),$

such that $u \neq v \neq 0$, for non-vanishing functions u and v on N. Then N is a neutral pointwise hemi-slant submanifold of type 2 with neutral anti-invariant distribution $\mathcal{D}_{\perp} = Span\{Y_3 = \frac{\partial}{\partial x_5}, Y_4 = \frac{\partial}{\partial x_8}\}$ and the neutral pointwise slant distribution of type 2 $\mathcal{D}_{\varphi} = Span\{Y_1 = \cos u \frac{\partial}{\partial x_1} - \sin u \frac{\partial}{\partial x_3}, Y_2 = \cos v \frac{\partial}{\partial x_2} - \sin v \frac{\partial}{\partial x_4}\}$ with slant function $\varphi = u - v$.

Example 3.3. Let N be a semi-Riemannian submanifold of R_4^8 defined by the immersion $\phi : N \to R_4^8$:

$$\phi(u, v, t, s) = (v, \sinh u, \cosh u, u, t, k_1, k_2, s),$$

such that u > 2 and $v \neq 0$, for non-vanishing function u on N. Then N is a neutral pointwise hemi-slant submanifold of type 1 with neutral anti-invariant distribution $\mathcal{D}_{\perp} = Span\{Y_3 = \frac{\partial}{\partial x_3}, Y_4 = \frac{\partial}{\partial x_8}\}$ and the neutral pointwise slant distribution of type 1 $\mathcal{D}_{\varphi} = Span\{Y_1 = \cosh u \frac{\partial}{\partial x_2} + \sinh u \frac{\partial}{\partial x_3} + \frac{\partial}{\partial x_4}, Y_2 = \frac{\partial}{\partial x_1}\}$ with slant function $\varphi = \cosh^{-1}(\frac{\cosh u}{\sqrt{2}})$.

Let *N* be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , *P*, *g*), and set the projections on the distributions \mathcal{D}_{\perp} and \mathcal{D}_{φ} by Q_{\perp} and Q_{φ} , respectively. Then we can write

$$Y_1 = Q_{\perp} Y_1 + Q_{\varphi} Y_1$$
 (12)

for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$. Applying *P* to equation (12) and using (6), we get

$$PY_1 = \beta Q_\perp Y_1 + \alpha Q_\varphi Y_1 + \beta Q_\varphi Y_1. \tag{13}$$

From (13), we have

 $\beta Q_{\perp} Y_1 \in \Gamma(\mathcal{D}_{\perp}), \ \alpha Q_{\perp} Y_1 = 0, \tag{14}$

$$\alpha Q_{\varphi} Y_1 \in \Gamma(\mathcal{D}_{\varphi}), \ \beta Q_{\varphi} Y_1 \in \Gamma(TN_{\perp}).$$
(15)

Using (6) in (13), we obtain

$$\alpha Y_1 = \alpha Q_{\varphi} Y_1, \ \beta Y_1 = \beta Q_{\perp} Y_1 + \beta Q_{\varphi} Y_1 \tag{16}$$

for any spacelike (timelike) vector field $Y_1 \in \Gamma(TN)$. Since $\Gamma(\mathcal{D}_{\varphi})$ is a proper pointwise slant distribution, from Theorem 2.2 and Corollary 2.3, we conclude that

$$type1: \alpha^2 Y_1 = (\cosh^2 \varphi) Y_1, \ type2: \alpha^2 Y_1 = (\cos^2 \varphi) Y_1$$
 (17)

for any spacelike (timelike) vector field $Y_1 \in \Gamma(\mathcal{D}_{\varphi})$ and a real-valued function φ defined on *N*. We give the following results for the characterization of proper pointwise hemi-slant submanifold.

Proposition 3.4. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then N is a proper pointwise hemi-slant submanifold if and only if there exists a function $\mu \in (1, \infty)$ and a distribution of type 1 \mathcal{D} on N such that

(a) $\mathcal{D} = \{Y_1 \in \Gamma(TN) : (\alpha_{\mathcal{D}})^2 Y_1 = \mu Y_1\},\$ (b) $\alpha Y_2 = 0$ for any spacelike(timelike) vector field $Y_2 \in \Gamma(TN)$ orthogonal to \mathcal{D} . Moreover, if φ denotes the slant function of N then $\mu = \cosh^2 \varphi$.

Proof. Let *N* be a proper pointwise hemi-slant submanifold of (\tilde{N}, P, g) . By setting $\mu = \cosh^2 \varphi$ and using (14) and (15), we obtain that $\mathcal{D} = \mathcal{D}_{\varphi}$, which follows *a* and *b*. Conversely, (a) and (b) imply that $TN = \mathcal{D} \oplus \mathcal{D}_{\perp}$. Since $\alpha(\mathcal{D}) \subseteq \mathcal{D}$, we received from (b) that \mathcal{D}_{\perp} is a totally real distribution. \Box

In a similar way, we obtain:

Proposition 3.5. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then N is a proper pointwise hemi-slant submanifold if and only if there exists a function $\mu \in (0, 1)$ and a distribution of type 2 \mathcal{D} on N such that

(a) $\mathcal{D} = \{Y_1 \in \Gamma(TN) : (\alpha_{\mathcal{D}})^2 Y_1 = \mu Y_1\},\$

(b) $\alpha Y_2 = 0$ for any spacelike(timelike) vector field $Y_2 \in \Gamma(TN)$ orthogonal to \mathcal{D} . Moreover, if φ denotes the slant function of N then $\mu = \cos^2 \varphi$.

From the above Propositions, we have:

Corollary 3.6. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then \mathcal{D}_{φ} is a proper pointwise slant distribution of

type 1 if and only if $g(\alpha Y_1, \alpha Y_2) = -\cosh^2 \varphi g(Y_1, Y_2)$, $g(\beta Y_1, \beta Y_2) = \sinh^2 \varphi g(Y_1, Y_2)$, type 2 if and only if $g(\alpha Y_1, \alpha Y_2) = -\cos^2 \varphi g(Y_1, Y_2)$, $g(\beta Y_1, \beta Y_2) = -\sin^2 \varphi g(Y_1, Y_2)$ for all spacelike (timelike) vector fields $Y_1, Y_2 \in \Gamma(\mathcal{D}_{\varphi})$.

Using (1), (6) and (7), the Propositions 3.4 and 3.5, we get:

Lemma 3.7. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then \mathcal{D}_{φ} is a proper pointwise slant distribution of

type 1 if and only if (a) $\dot{\alpha}\beta Y_1 = (-\sinh^2 \varphi)Y_1$, (b) $\dot{\beta}\beta Y_1 = -\beta \alpha Y_1$, type 2 if and only if (a) $\dot{\alpha}\beta Y_1 = (\sin^2 \varphi)Y_1$), (b) $\dot{\beta}\beta Y_1 = -\beta \alpha Y_1$, for all spacelike (timelike) vector field $Y_1 \in \Gamma(\mathcal{D}_{\varphi})$.

Now we examine the conditions for integrability and totally geodesic foliation of distributions associated with the definition of proper pointwise hemi-slant submanifolds of a para-Kaehler manifold.

Theorem 3.8. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then the totally real distribution \mathcal{D}_{\perp} is integrable.

Proof. It is known that is a para-Kaehler manifold, then $d\mathcal{F} = 0$, where d is exterior derivative and \mathcal{F} is the fundamental 2–form defined $\mathcal{F}(Y_1, Y_2) = g(Y_1, PY_2)$ for any spacelike (timelike) vector fields $Y_1, Y_2 \in \Gamma(\tilde{N})$ (see [23]). Since \mathcal{F} is closed ($d\mathcal{F} = 0$), for any spacelike (timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}_{\varphi})$ and $Y_2, Y_3 \in \Gamma(\mathcal{D}_{\perp})$ we have

$$\begin{aligned} 3d\mathcal{F}(\alpha Y_1, Y_2, Y_3) &= \alpha Y_1 \mathcal{F}(Y_2, Y_3) - Y_2 \mathcal{F}(\alpha Y_1, Y_3) + Y_3 \mathcal{F}(\alpha Y_1, Y_2) \\ &= -\mathcal{F}([\alpha Y_1, Y_2], Y_3) + \mathcal{F}([\alpha Y_1, Y_3], Y_2) - \mathcal{F}([Y_2, Y_3], \alpha Y_1) = 0 \end{aligned}$$

Since \mathcal{D}_{\perp} and \mathcal{D}_{φ} are orthogonal and \mathcal{D}_{\perp} is anti-invariant, using Proposition 3.4 and (6) we get

$$Y_2 g(\beta \alpha Y_1, Y_3) - \cosh^2 \varphi g([Y_2, Y_3], Y_1) - g([Y_2, Y_3], \beta \alpha Y_1) = 0$$

Since $[Y_2, Y_3] \in \Gamma(TN)$ and $\beta \alpha Y_1 \in \Gamma(TN_{\perp})$ we obtain

$$\cosh^2 \varphi g([Y_2, Y_3], Y_1) = 0.$$

Since *N* is a proper pointwise hemi-slant submanifold and Y_1, Y_2, Y_3 are all non-zero, we have $[Y_2, Y_3] \in \Gamma(\mathcal{D}_{\perp})$. \Box

Note that the Theorem 3.8 holds for proper pointwise slant submanifold $N_{1\varphi}$ of type 2. From the Theorem 3.8, we have:

Corollary 3.9. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then the totally real distribution \mathcal{D}_{\perp} is integrable if and only if for any spacelike (timelike) vector fields $Y_1, Y_2 \in \Gamma(\mathcal{D}_{\perp})$ the shape operator satisfies $\mathcal{R}_{PY_2}Y_1 = \mathcal{R}_{PY_1}Y_2$.

Theorem 3.10. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then the totally real distribution \mathcal{D}_{\perp} defines a totally geodesic foliation if and only if for every spacelike (timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}_{\perp})$ and $Y_3 \in \Gamma(\mathcal{D}_{\varphi})$, $\mathcal{A}_{PY_1} \alpha Y_3 = \mathcal{A}_{\beta \alpha Y_3} Y_1$.

Proof. For any spacelike (timelike) vector fields $Y_1, Y_2 \in \Gamma(\mathcal{D}_{\perp})$ and $Y_3 \in \Gamma(\mathcal{D}_{\varphi})$, using (1)-(7) we get

$$g(\nabla_{Y_{1}}Y_{2}, Y_{3}) = -g(\bar{\nabla}_{Y_{1}}PY_{2}, PY_{3}) = -g(\bar{\nabla}_{Y_{1}}PY_{2}, \alpha Y_{3}) + g(\bar{\nabla}_{Y_{1}}Y_{2}, \dot{\alpha}\beta Y_{3}) + g(\bar{\nabla}_{Y_{1}}Y_{2}, \dot{\beta}\beta Y_{3}).$$
(18)

From (4), (5) and Lemma 3.7(type 1), we obtain

$$g(\nabla_{Y_1}Y_2, Y_3) = g(\mathcal{A}_{PY_2}Y_1, \alpha Y_3) - \sinh^2 \varphi g(\tilde{\nabla}_{Y_1}Y_2, Y_3)$$

= $-g(\mathcal{A}_{\beta \alpha Y_3}Y_1, Y_2).$

Using (3), we get

$$\cosh^2 \varphi g(\nabla_{Y_1} Y_2, Y_3) = g(\mathcal{A}_{PY_2} \alpha Y_3, Y_1) - g(\mathcal{A}_{\beta \alpha Y_3} Y_2, Y_1)$$

Now, analogous to the proof of the Theorems 3.8 and 3.10 we give the following results for proper pointwise hemi-slant submanifolds.

Theorem 3.11. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then the proper pointwise slant distribution \mathcal{D}_{φ} is integrable if and only if

$$g(\mathcal{A}_{\beta\alpha Y_2}Y_1 - \mathcal{A}_{PY_1}\alpha Y_2, Y_3) = g(\mathcal{A}_{\beta\alpha Y_3}Y_1 - \mathcal{A}_{PY_1}\alpha Y_3, Y_2)$$

for every spacelike (timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}_{\perp})$ and $Y_2, Y_3 \in \Gamma(\mathcal{D}_{\varphi})$.

Theorem 3.12. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then the proper pointwise slant distribution \mathcal{D}_{φ} defines a totally geodesic foliation if and only if $\mathcal{A}_{\beta\alpha Y_2}Y_1 - \mathcal{A}_{PY_1}\alpha Y_2 = 0$ for any spacelike (timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}_{\perp})$ and $Y_2 \in \Gamma(\mathcal{D}_{\varphi})$.

From the Theorems 3.10 and 3.12 we have:

Corollary 3.13. Let N be a proper pointwise hemi-slant submanifold of a para-Kaehler manifold (\tilde{N} , P, g). Then a necessary and sufficient condition for N to be locally semi-Riemannian product of the form $N = N_1 \times N_{2\varphi}$ is that the Weingarten operator satisfies $\mathcal{A}_{\beta\alpha Y_2}Y_1 - \mathcal{A}_{PY_1}\alpha Y_2 = 0$ for any spacelike (timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}_{\perp})$ and $Y_2 \in \Gamma(\mathcal{D}_{\varphi})$, where N_1 is a totally real submanifold and $N_{2\varphi}$ is a proper pointwise slant submanifold of \tilde{N} .

4. Warped products $N_{1\varphi} \times_h N_{2\perp}$ in para-Kaehler manifolds

Let (N_1, g_1) and (N_2, g_2) be two semi-Riemannian manifolds, let $h : N_1 \to R_+$, and let $\eta_1 : N_1 \times N_2 \to N_1$ and $\eta_2 : N_1 \times N_2 \to N_2$ the projection maps given by $\eta_1(r, s) = r$ and $\eta_2(r, s) = s$ for all $(r, s) \in N_1 \times N_2$. The warped product([7]) $N = N_1 \times N_2$ is the manifold $N_1 \times N_2$ equipped with the semi-Riemannian structure such that

 $g(Y_1, Y_2) = g_1(\eta_{1*}Y_1, \eta_{1*}Y_2) + (h \circ \eta_1)^2 g_2(\eta_{2*}Y_1, \eta_{2*}Y_2)$

for every spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(TN)$, here * denotes the tangent map. The function *h* is called the warping function of the warped product manifold. In particular, if the warping function is constant, then the manifold *N* is said to be trivial.

Lemma 4.1. ([7]) For spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(TN_1)$ and $Y_3, Y_4 \in \Gamma(TN_2)$, we get on warped product manifold $N = N_1 \times_h N_2$ that $(a) \nabla_{Y_1} Y_2 \in \Gamma(TN_1)$, $(b) \nabla_{Y_1} Y_3 = \nabla_{Y_3} Y_1 = (\frac{Y_1h}{h}) Y_3$, $(c) \nabla_{Y_3} Y_4 = \frac{-g(Y_3, Y_4)}{h} \nabla h$, where ∇ denotes the Levi-Civita connection on N and ∇h is the gradient of h defined by $g(\nabla h, Y_1) = Y_1h$.

It is also important to note that for a warped product $N = N_1 \times_h N_2$, N_1 is totally geodesic and N_2 is totally umbilical in N([7]).

In this section, we investigate the existence of warped product submanifolds $N_{1\varphi} \times_h N_{2\perp}$ of para-Kaehler manifolds such that $N_{1\varphi}$ is a proper pointwise slant submanifold and $N_{2\perp}$ is a totally real submanifold of \tilde{N} . First, we are going to give some examples of a warped product pointwise hemi-slant submanifold of the form $N_{1\varphi} \times_h N_{2\perp}$.

Example 4.2. Consider a semi-Riemannian submanifold of R_4^8 with the cartesian coordinates $(x_1, ..., x_8)$ and the almost para-complex structure

$$P(\frac{\partial}{\partial x_{2i}}) = \frac{\partial}{\partial x_{2i-1}}, \ P(\frac{\partial}{\partial x_{2i-1}}) = \frac{\partial}{\partial x_{2i}}, \ 1 \le i \le 4.$$

Let R_4^8 be a semi-Euclidean space of signature (+,-,+,-,+,-) with respect to the canonical basis $(\frac{\partial}{\partial x_1}, ..., \frac{\partial}{\partial x_8})$. Let N be defined by the immersion ψ as follows

 $\psi(u, v, t) = (\sinh u, v, u, \cosh u, \cosh(t^3), a, \sinh(t^3), b)$

for any non-vanishing function u on N, where a, b are constants and u > 1. Then the tangent space TN of N is spanned by the following vectors

$$\psi_u = \cosh u \frac{\partial}{\partial x_1} + \frac{\partial}{\partial x_3} + \sinh u \frac{\partial}{\partial x_4}, \ \psi_v = \frac{\partial}{\partial x_2},$$

Y. Gündüzalp / Filomat 36:1 (2022), 275–288

$$\psi_t = 3t^2 \sinh(t^3) \frac{\partial}{\partial x_5} + 3t^2 \cosh(t^3) \frac{\partial}{\partial x_7}.$$

Then we obtain

$$P\psi_u = \cosh u \frac{\partial}{\partial x_2} + \sinh u \frac{\partial}{\partial x_3} + \frac{\partial}{\partial x_4}, \quad P\psi_v = \frac{\partial}{\partial x_1},$$
$$P\psi_t = 3t^2 \sinh(t^3) \frac{\partial}{\partial x_6} + 3t^2 \cosh(t^3) \frac{\partial}{\partial x_8}.$$

It is easy to see that $P\psi_t \perp TN = span\{\psi_u, \psi_v, \psi_t\}$ and thus, we consider $D_\perp = span\{\psi_t\}$ is a spacelike totally real distribution and $D_{\varphi} = span\{\psi_u, \psi_v\}$ is a neutral proper poitwise slant distribution of type 1 with slant function $\varphi = \cosh^{-1}(\frac{\cosh u}{\sqrt{2}})$. It is easy to observe that D_{φ} and D_\perp are integrable. If we denote the integral manifolds of D_{φ} and D_\perp by $N_{1\varphi}$ and $N_{2\perp}$, respectively, then the metric tensor of N is given by

$$ds^2 = 2du^2 - dv^2 + 9t^4 \cosh(2t^3)dt^2.$$

Thus, N is a warped product submanifold of the form $N = N_{1\varphi} \times_h N_{2\perp}$ in R_4^8 with the warping function $h = 3t^2 \sqrt{\cosh(2t^3)}$.

Example 4.3. Let N be an immersed semi-Riemannian submanifold of a para-Kaehler manifold \tilde{N} (as given in *Example 4.2*) defined by

$$\psi(x, y, z) = (\sin x, \sin y, \cos x, \cos y, \cos e^z, a, \sin e^z, b)$$

such that $u \neq v \neq 0$, for non-vanishing functions u and v on N. Then the tangent space TN of N is spanned by the following vectors:

$$\psi_x = \cos x \frac{\partial}{\partial x_1} - \sin x \frac{\partial}{\partial x_3}, \quad \psi_x = \cos y \frac{\partial}{\partial x_2} - \sin y \frac{\partial}{\partial x_4},$$
$$\psi_z = -e^z \sin(e^z) \frac{\partial}{\partial x_5} + e^z \cos(e^z) \frac{\partial}{\partial x_7}.$$

Thus, we consider $D_{\perp} = span\{\psi_z\}$ is a spacelike totally real distribution and $D_{\varphi} = span\{\psi_x, \psi_y\}$ is a neutral proper poitwise slant distribution of type 2 with slant function $\varphi = u - v$. It is easy to observe that D_{φ} and D_{\perp} are integrable. If we denote the integral manifolds of D_{φ} and D_{\perp} by $N_{1\varphi}$ and $N_{2\perp}$, respectively, then the metric tensor of N is given by

$$ds^2 = dx^2 - dy^2 + e^{2z} dz^2.$$

Hence, N is a 3-dimensional pointwise hemi-slant warped product submanifold of R^8_A with the warping function $h = e^z$.

Example 4.4. Let N be defined by the immersion ψ as follows

 $\psi(x, y, z, t) = (\sinh x, \sinh y, \cosh y, \cosh x, \sinh(z + t), z, \sinh(z + t), t)$

for any non-vanishing functions x and y on N. Then the tangent space TN of N is spanned by the following vectors

$$\psi_{x} = \cosh x \frac{\partial}{\partial x_{1}} + \sinh x \frac{\partial}{\partial x_{4}}, \quad \psi_{y} = \cosh y \frac{\partial}{\partial x_{2}} + \sinh y \frac{\partial}{\partial x_{3}},$$
$$\psi_{z} = \cosh(z+t) \frac{\partial}{\partial x_{5}} + \frac{\partial}{\partial x_{6}} + \cosh(z+t) \frac{\partial}{\partial x_{7}}, \quad \psi_{t} = \cosh(z+t) \frac{\partial}{\partial x_{5}} + \cosh(z+t) \frac{\partial}{\partial x_{7}} + \frac{\partial}{\partial x_{8}}.$$

It is easy to see that $P\psi_z$ and $P\psi_t \perp TN = span\{\psi_x, \psi_y, \psi_z, \psi_t\}$ and thus, we consider $D_\perp = span\{\psi_z, \psi_t\}$ is a spacelike totally real distribution and $D_{\varphi} = span\{\psi_x, \psi_y\}$ is a neutral proper poitwise slant distribution of type 1 with slant function $\alpha^2 = \cosh^2(x - y)$. It is easy to observe that D_{φ} and D_\perp are integrable. If we denote the integral manifolds of D_{φ} and D_\perp by $N_{1\varphi}$ and $N_{2\perp}$, respectively, then the metric tensor of N is given by

$$ds^{2} = dx^{2} - dy^{2} + \cosh(2(z+t))(dz^{2} + dt^{2}).$$

Thus, N is a pointwise hemi-slant warped product submanifold of the form $N = N_{1\varphi} \times_h N_{2\perp}$ in R_4^8 with the warping function $h = \sqrt{\cosh(2(z+t))}$.

282

Now we will consider warped product pointwise hemi-slant submanifolds $N = N_{1\varphi} \times_h N_{2\perp}$ such that $N_{1\varphi}$ is a neutral proper pointwise slant submanifold and $N_{2\perp}$ is a totally real submanifold of a para-Kaehler manifold \tilde{N} .

Lemma 4.5. Let $N = N_{1\varphi} \times_h N_{2\perp}$ be a pointwise hemi-slant warped product submanifold of a para-Kaehler manifold \tilde{N} . Then

$$g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3) = (-\cosh^2 \varphi)(Y_1 \ln h)g(Y_3, Y_4) + g(\mathcal{A}_{\beta \alpha Y_1} Y_3, Y_4)$$
(19)

for any spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(TN_{1\varphi})$ and $Y_3, Y_4 \in \Gamma(TN_{2\perp})$.

Proof. From (1)-(6) we obtain

$$g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3) = -g(\nabla_{Y_3}Y_1, Y_4) + g(\tilde{\nabla}_{Y_3}P\beta Y_1, Y_4).$$
⁽²⁰⁾

Using Lemma 4.1, Lemma 3.7(type 1) and (7) we get

$$g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3) = -(Y_1 \ln h)g(Y_3, Y_4) + g(\bar{\nabla}_{Y_3}(-\sinh^2 \varphi)Y_1, Y_4) + g(\bar{\nabla}_{Y_3}(-\beta \alpha Y_1), Y_4).$$

From the fact that φ is slant function and using (4) we obtain

$$g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3) = -(Y_1 \ln h)g(Y_3, Y_4) - (\sinh^2 \varphi)g(\nabla_{Y_3}Y_1, Y_4) + g(\mathcal{A}_{\beta\alpha Y_1}Y_3, Y_4),$$

since $g(Y_1, Y_4) = 0$. Using (3) we have

$$g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3) = (-\cosh^2)(Y_1 \ln h)g(Y_3, Y_4) + g(\mathcal{A}_{\beta\alpha Y_1}Y_3, Y_4).$$

Theorem 4.6. Let N be a pointwise hemi-slant warped product submanifold of a para-Kaehler manifold \tilde{N} . Then N is locally isometric to pointwise hemi-slant warped product submanifold of the form $N = N_{1\varphi} \times_h N_{2\perp}$ if and only if the shape operator of N satisfies

$$\mathcal{A}_{PY_4}\alpha Y_1 - \mathcal{A}_{\beta\alpha Y_1}Y_4 = (-\cosh^2 \varphi)(Y_1 \ln h)Y_4,$$
(21)

for some function τ on N such that $Y_3(\tau) = 0$, where spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(\mathcal{D}_{\varphi})$ and $Y_3, Y_4 \in \Gamma(\mathcal{D}_{\perp})$.

Proof. Let us consider that *N* is a pointwise hemi-slant warped product submanifold of a para-Kaehler manifold \tilde{N} . Then, Lemma 4.5, we have (21). We know that *h* is a function on N_2 , therefore setting $\tau = \ln h$ implies that $Y_3(\tau) = 0$. Conversely we assume that *N* is a pointwise hemi-slant submanifold of \tilde{N} such that (21) holds. Taking the inner product of (21) with Y_2 , we can say from Theorem 3.12 that the integral manifold $N_{1\varphi}$ of \mathcal{D}_{φ} is totally geodesic foliation in *N*. Thus, by Corollary 3.9 the distribution \mathcal{D}_{\perp} is integrable if and only if

$$g(\mathcal{A}_{PY_3}Y_4, \alpha Y_1) = g(\mathcal{A}_{PY_4}\alpha Y_1, Y_3)$$
(22)

for any spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(\mathcal{D}_{\varphi})$ and $Y_3, Y_4 \in \Gamma(\mathcal{D}_{\perp})$. From (19) and (22) we obtain

$$g(\mathcal{A}_{PY_3}Y_4, \alpha Y_1) = (-\cosh^2 \varphi)g(\nabla_{Y_3}Y_1, Y_4) + g(\mathcal{A}_{\beta \alpha Y_1}Y_3, Y_4)$$
(23)

on the other hand, taking the inner product of (21) with Y_3 we obtain

$$g(\mathcal{A}_{PY_4}\alpha Y_1 - \mathcal{A}_{\beta\alpha Y_1}Y_4, Y_3) = g((-\cosh^2 \varphi)(Y_1 \ln h)Y_4, Y_3).$$
(24)

From (23), (24) and Lemma 4.1, we have

$$-q(\sigma_{\perp}(Y_3, Y_4), Y_1) = q(Y_1(\tau)Y_3, Y_4) = q(Y_3, Y_4)q(\nabla\tau, Y_1).$$

Thus $\sigma_{\perp}(Y_3, Y_4) = g(Y_3, Y_4)(-\nabla \tau)$, here σ_{\perp} is a second fundamental form of \mathcal{D}_{\perp} in *N* and $\nabla \tau$ is a gradient of $\tau = \ln h$. Hence the integrable manifold N_2 of \mathcal{D}_{\perp} is totally umbilical submanifold in *N* and its mean curvature is non-zero and parallel and $Y_3(\tau) = 0$ for every spacelike (timelike) vector field $Y_3 \in \Gamma(\mathcal{D}_{\perp})$. Therefore, from Theorem 1.2 ([22], page 211), we deduce that *N* is a pointwise hemi-slant warped product submanifold of \tilde{N} . \Box

Now we maintain a necessary and sufficient condition for a warped product submanifold of the form $N = N_{1\varphi} \times_h N_{2\perp}$ to be a semi-Riemannian product.

Theorem 4.7. A pointwise hemi-slant warped product submanifold of the form $N = N_{1\varphi} \times_h N_{2\perp}$ of a para-Kaehler manifold \tilde{N} is simply a locally semi-Riemannian product if and only if the shape operator satisfies $\mathcal{A}_{\beta\alpha Y_3}Y_1 = 0$, for every spacelike(timelike) vector fields $Y_3 \in \Gamma(N_{1\varphi})$ and $Y_1 \in \Gamma(N_{2\perp})$.

Proof. **Proof.** For all spacelike(timelike) vector fields $Y_3 \in \Gamma(N_{1\varphi})$ and $Y_1, Y_2 \in \Gamma(N_{2\perp})$, using (1)-(3) we have $g(\nabla_{Y_1}Y_3, Y_2) = -g(\tilde{\nabla}_{Y_1}PY_3, PY_2)$. From (1),(2) and (6) we get

$$g(\nabla_{Y_1}Y_3, Y_2) = g(\nabla_{Y_1}\alpha^2 Y_3, Y_2) + g(\nabla_{Y_1}\beta\alpha Y_3, Y_2) - g(\nabla_{Y_1}\beta Y_3, PY_2).$$

Using type 1 (17), (3)-(5) and the fact that $g(Y_2, Y_3) = 0$, we obtain

$$g(\nabla_{Y_1}Y_3, Y_2) = (\cosh^2 \varphi)g(\tilde{\nabla}_{Y_1}Y_3, Y_2) - g(\sigma(Y_1, Y_2), \beta \alpha Y_3) - g(\nabla_{Y_1}^{\perp} \beta Y_3, PY_2).$$
(25)

Hence, from Lemma 4.1, we get

$$(\sinh^2 \varphi)(Y_3 \ln h)gY_1, Y_2) = g(\sigma(Y_1, Y_2), \beta \alpha Y_3) + g(\nabla_{Y_1}^{\perp} \beta Y_3, PY_2).$$
(26)

Interchanging Y_1 and Y_2 in (26) and then, subtracting from (26), we have:

$$g(\nabla_{Y_1}^{\perp}\beta Y_3, PY_2) = g(\nabla_{Y_2}^{\perp}\beta Y_3, PY_1).$$
(27)

Furthermore from (1),(3),(4) and (6) we obtain

$$g(\nabla_{Y_1}^{\perp}\beta Y_3, PY_2) = -(Y_3 \ln h)g(Y_1, Y_2) - g(\tilde{\nabla}_{Y_1}\alpha Y_3, PY_2).$$
(28)

Again by interchanging Y_1 and Y_2 in (28) we conclude that (27) holds if and only if

$$g(\tilde{\nabla}_{Y_1}\alpha Y_3, PY_2) = -g(\tilde{\nabla}_{Y_1}PY_2, \alpha Y_3) = 0.$$
⁽²⁹⁾

Using type 1,(17) and (1)-(6) we have

$$(-\cosh^2 \varphi)(Y_3 \ln h)g(Y_1, Y_2) + g(\sigma(Y_1, Y_2), \beta \alpha Y_3) = 0.$$
(30)

Hence, from (30) we can say that *h* is constant if and only if $g(\sigma(Y_1, Y_2), \beta \alpha Y_3) = 0$, since $N_{1\varphi}$ is proper pointwise slant submanifold and Y_3 is non-zero spacelike(timelike)vector field.

We say that a hemi-slant submanifold is mixed geodesic if

$$\sigma(Y_1, Y_3) = 0 \tag{31}$$

for all spacelike(timelike) vector fields $Y_1 \in \Gamma(\mathcal{D}\varphi)$ and $Y_3 \in \Gamma(\mathcal{D}\perp)$.

Lemma 4.8. For a mixed geodesic pointwise hemi-slant warped product submanifold $N = N_{1\varphi} \times_h N_{2\perp}$ of a para-Kaehler manifold \tilde{N} Then, we obtain

$$g(\sigma(Y_1, Y_2), PY_3) = 0$$
(32)

$$(\alpha Y_1 \ln h)g(\sigma(Y_3, Y_4) = g(\sigma(Y_3, Y_4), \beta Y_1)$$
(33)

for spacelike(timelike) vector fields $Y_1, Y_2 \in \Gamma(N_{1\varphi})$ and $Y_3, Y_4 \in \Gamma(N_{2\perp})$.

Proof. From (1) and (2) we obtain $g(\sigma(Y_1, Y_2), PY_3) = -g(\tilde{\nabla}_{Y_1}PY_2, Y_3)$. From here, $g(\sigma(Y_1, Y_2), PY_3) = g(\tilde{\nabla}_{Y_1}Y_3, PY_2)$. Using (6), we have $g(\sigma(Y_1, Y_2), PY_3) = g(\nabla_{Y_1}Y_3, \alpha Y_2) + g(\sigma(Y_1, Y_3), \beta Y_2)$. Thus from Lemma 4.1 we get (32). In a similar way, we have (33). \Box

Note that the Lemma 4.8 holds for proper pointwise slant submanifold $N_{1\varphi}$ of type 2.

5. An optimal inequality

We establish general sharp geometric inequality for proper pointwise hemi-slant warped product submanifolds of the form $N_{1\varphi} \times_h N_{2\perp}$ of a para-Kaehler manifold (\tilde{N}, P, g).

Let $x \in N$ and $\{E_1, ..., E_m, \hat{E}_1, ..., \hat{E}_n, PE_1, ..., PE_m, \tilde{E}_1, ..., \tilde{E}_n\}$ be an orthonormal basis of the tangent space $T_x \tilde{N}$ such that $\{E_1, ..., E_m, \hat{E}_1, ..., \hat{E}_n\}$ are tangent to N at x and $\{PE_1, ..., PE_m, \tilde{E}_1, ..., \tilde{E}_n\}$ are normal to N, and thus $T_x \tilde{N} = T_x N \oplus T_x^{\perp} N$. Now, we can take $\{E_1, ..., E_m, \hat{E}_1, ..., \hat{E}_n\}$ in such a way that $\{E_1, ..., E_m\}$ form an orthonormal basis of \mathcal{D}_{\perp} and $\{\hat{E}_1, ..., \hat{E}_n\}$ form an orthonormal basis of \mathcal{D}_{\perp} , where $dim \mathcal{D}_{\perp} = m$ and $dim \mathcal{D}_{\varphi} = n$. We can take $\{PE_1, ..., PE_m, \tilde{E}_1, ..., \tilde{E}_n\}$ in such a way that $\{PE_1, ..., PE_m, \tilde{E}_1, ..., \tilde{E}_n\}$ form an orthonormal frame of $\beta(\mathcal{D}_{\varphi})$. Since the metric on $N_{1\varphi}$ of a warped product $N_{1\varphi} \times_h N_{2\perp}$ is neutral, it is even-dimensional([9]). Thus n = 2p. Then, we can choose a orthonormal frames $\{\hat{E}_1, ..., \hat{E}_{2p}\}$ of \mathcal{D}_{φ} in such a way that

$$\hat{E}_{1} = sech\varphi\alpha\hat{E}_{1}, ..., \hat{E}_{2p} = sech\varphi\alpha\hat{E}_{2p-1}, (type1) \tilde{E}_{1} = csch\varphi\beta\tilde{E}_{1}, ..., \tilde{E}_{2p} = csch\varphi\beta\tilde{E}_{2p}, (type1)$$

where φ is the slant function. We note that such an orthonormal frame is called an adapted frame ([2]).

Let us consider

• on \mathcal{D}_{\perp} : an orthonormal basis $\{E_i\}_{i=1,\dots,m}$, where $m = boy \mathcal{D}_{\perp}$; moreover, one can suppose that $\epsilon_i = g(E_i, E_i) = 1$.

• on $P(\mathcal{D}_{\perp})$: an orthonormal basis $\{PE_j\}_{j=1,\dots,m}$, where $m = boy P(\mathcal{D}_{\perp})$ and $\epsilon_i^* = g(PE_j, PE_j) = -1$.

• on (\mathcal{D}_{φ}) : an orthonormal basis $\{\hat{E}_a\}_{a=1,\dots,n}$, where $n = boy(\mathcal{D}_{\varphi})$ and $\hat{\epsilon}_a = g(\hat{E}_a, \hat{E}_a) = \mp 1$.

• on $\beta(\mathcal{D}_{\varphi})$: an orthonormal basis $\{\tilde{E}_b\}_{b=1,\dots,n}$, where $n = boy\beta(\mathcal{D}_{\varphi})$ and $\tilde{\epsilon}_b = g(\tilde{E}_b, \tilde{E}_b) = \mp 1$.

Theorem 5.1. Let $N = N_{1\varphi} \times_h N_{2\perp}$ be a mixed geodesic warped product submanifold of a para-Kaehler manifold \tilde{N} such that $N_{1\varphi}$ is a *n*-dimensional neutral proper pointwise slant submanifold and $N_{2\perp}$ is a *m*-dimensional totally real submanifold of N. Suppose that $N_{2\perp}$ is spacelike. Then, the squared norm of the second fundamental form $||\sigma||^2$ of N satisfies

$$\|\sigma\|^2 \le m \coth^2 \varphi \|\nabla(\ln h)\|^2,\tag{34}$$

where $\nabla(\ln h)$ is the gradient of $\ln h$.

Proof. Since $\|\sigma\|^2 = \|\sigma(\mathcal{D}_{\varphi}, \mathcal{D}_{\varphi})\|^2 + 2\|\sigma(\mathcal{D}_{\varphi}, \mathcal{D}_{\perp})\|^2 + \|\sigma(\mathcal{D}_{\perp}, \mathcal{D}_{\perp})\|^2$, if *N* is mixed geodesic we obtain

$$\|\sigma\|^2 = \|\sigma(\mathcal{D}_{\varphi}, \mathcal{D}_{\varphi})\|^2 + \|\sigma(\mathcal{D}_{\perp}, \mathcal{D}_{\perp})\|^2.$$
(35)

The first factor of the right hand side of (35) can be written as

$$\|\sigma(\mathcal{D}_{\varphi},\mathcal{D}_{\varphi})\|^{2} = \sum_{r=1}^{2p+m} \sum_{c,d=1}^{2p} g(\sigma(\hat{E}_{c},\hat{E}_{d}),\bar{E}_{r})^{2}.$$

Using the adapted frame, we have

$$\|\sigma(\mathcal{D}_{\varphi}, \mathcal{D}_{\varphi})\|^{2} = \sum_{i=1}^{m} \sum_{c,d=1}^{2p} g(\sigma(\hat{E}_{c}, \hat{E}_{d}), PE_{i})^{2} + \sum_{a=1}^{2p} \sum_{c,d=1}^{2p} g(\sigma(\hat{E}_{c}, \hat{E}_{d}), csch\varphi\beta\hat{E}_{a})^{2}.$$
(36)

From (32), we get

$$\|\sigma(\mathcal{D}_{\varphi}, \mathcal{D}_{\varphi})\|^{2} = \sum_{a=1}^{2p} \sum_{c,d=1}^{2p} g(\sigma(\hat{E}_{c}, \hat{E}_{d}), \operatorname{csch}\varphi\beta\hat{E}_{a})^{2}.$$
(37)

On the other hand we can write the second factor of the right side of (35) as

$$\|\sigma(\mathcal{D}_{\perp},\mathcal{D}_{\perp})\|^2 = \sum_{r=1}^{2p+m} \sum_{i,j=1}^m g(\sigma(E_i,E_j),\bar{E}_r)^2.$$

Using the adapted frame we arrive at

$$\|\sigma(\mathcal{D}_{\perp},\mathcal{D}_{\perp})\|^{2} = \sum_{k=1}^{m} \sum_{i,j=1}^{m} g(\sigma(E_{i},E_{j}),PE_{k})^{2} + \sum_{c=1}^{2p} \sum_{i,j=1}^{m} g(\sigma(E_{i},E_{j}),csch\varphi\beta\hat{E}_{c})^{2}.$$
(38)

From (33), we get

$$\|\sigma(\mathcal{D}_{\perp},\mathcal{D}_{\perp})\|^{2} = \sum_{k=1}^{m} \sum_{i,j=1}^{m} g(\sigma(E_{i},E_{j}),PE_{k})^{2} + m \sum_{c=1}^{2p} csch^{2}\varphi(\alpha \hat{E}_{c}\ln h)^{2}.$$
(39)

Further we can write (39) as

$$\|\sigma(\mathcal{D}_{\perp}, \mathcal{D}_{\perp})\|^{2} = \sum_{k=1}^{m} \sum_{i,j=1}^{m} g(\sigma(E_{i}, E_{j}), PE_{k})^{2} + m(csch^{2}\varphi(\alpha \hat{E}_{1}(\ln h))^{2} + csch^{2}\varphi(\alpha \hat{E}_{2}(\ln h))^{2} + ... + csch^{2}\varphi(\alpha \hat{E}_{2p}(\ln h))^{2}).$$
(40)

From (40) and using the adapted frame, we have

$$\begin{aligned} \|\sigma(\mathcal{D}_{\perp},\mathcal{D}_{\perp})\|^2 &= \sum_{k=1}^m \sum_{i,j=1}^m g(\sigma(E_i,E_j),PE_k)^2 + m(\coth^2\varphi(\operatorname{sech}\varphi\alpha\hat{E}_1(\ln h))^2 \\ &+ \operatorname{csch}^2\varphi(\operatorname{sech}\varphi\alpha^2\hat{E}_1(\ln h))^2 + \operatorname{coth}^2\varphi(\operatorname{sech}\varphi\alpha\hat{E}_3(\ln h))^2 \\ &+ \operatorname{csch}^2\varphi(\operatorname{sech}\varphi\alpha^2\hat{E}_3(\ln h))^2 + \ldots + \operatorname{coth}^2\varphi(\operatorname{sech}\varphi\alpha\hat{E}_{2p-1}(\ln h))^2 \\ &+ \operatorname{csch}^2\varphi(\operatorname{sech}\varphi\alpha^2\hat{E}_{2p-1}(\ln h))^2). \end{aligned}$$

Using the Proposition 3.4, we obtain

$$\|\sigma(\mathcal{D}_{\perp}, \mathcal{D}_{\perp})\|^{2} = \sum_{k=1}^{m} \sum_{i,j=1}^{m} g(\sigma(E_{i}, E_{j}), PE_{k})^{2} + m \sum_{c=1}^{2p} (\coth^{2}[\tilde{E}_{2c-1}(\ln h))^{2} + \tilde{E}_{2c-1}(\ln h))^{2}$$
$$= \sum_{k=1}^{m} \sum_{i,j=1}^{m} g(\sigma(E_{i}, E_{j}), PE_{k})^{2} + m \coth^{2} \|\nabla(\ln h)\|^{2}.$$
(41)

286

From (35), (37) and (41) we obtain (34).

If the equality sign of (34) holds identically, then $N_{1\varphi}$ is totally geodesic and $N_{2\perp}$ a totally umbilical submanifold in \tilde{N} . \Box

Remark 5.2. If the manifold $N_{2\perp}$ of Theorem 5.1 is timelike, then (34) shall be replaced by

 $\|\sigma\|^2 \ge m \coth^2 \varphi \|\nabla(\ln h)\|^2.$

In a similar way, for proper pointwise slant submanifold $N_{1\phi}$ of type 2, we obtain the following result:

Theorem 5.3. Let $N = N_{1\varphi} \times_h N_{2\perp}$ be a mixed geodesic warped product submanifold of a para-Kaehler manifold \tilde{N} such that $N_{1\varphi}$ is a *n*-dimensional neutral proper pointwise slant submanifold and $N_{2\perp}$ is a *m*-dimensional totally real submanifold of N. Suppose that $N_{2\perp}$ is spacelike(respectively, timelike). Then, the squared norm of the second fundamental form $||\sigma||^2$ of N satisfies

$$\|\sigma\|^{2} \le m \cot^{2} \varphi \|\nabla(\ln h)\|^{2} \ (respectively, \ \|\sigma\|^{2} \ge m \cot^{2} \varphi \|\nabla(\ln h)\|^{2}) \tag{43}$$

where $\nabla(\ln h)$ is the gradient of $\ln h$.

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