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Generalized Resolvents of Linear Relations Generated by Integral Equations with Operator Measures

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Abstract. We consider a symmetric minimal relation L_0 generated by an integral equation with operators measures. We obtain a form of generalized resolvents of L_0 and give a description of boundary value problems associated to generalized resolvents.

1. Introduction

Generalized resolvents of symmetric operators were introduced by M.A. Naimark in 1940 (see, for example, [1]). In [27], A.V. Straus described the generalized resolvents of a symmetric operator generated by a formally self-adjoint differential expression of even order in the scalar case. In [5], these results were spread to the operator case, and in [9] to the case of a differential-operator expression with a non-negative weight operator function. Further, the generalized resolvents of differential operators were studied in many works (a detailed bibliography is available, for example, in [25], [21]).

In this paper, we consider the integral equation

$$y(t) = x_0 - iJ \int_a^t d\mathbf{p}(s)y(s) - iJ \int_a^t d\mathbf{m}(s)f(s),\tag{1}$$

where y is an unknown function, $a \le t \le b$; J is an operator in a separable Hilbert space H, $J = J^*$, $J^2 = E$ (E is the identical operator); \mathbf{p} , \mathbf{m} are operator-valued measures defined on Borel sets $\Delta \subset [a,b]$ and taking values in the set of linear bounded operators acting in H; $x_0 \in H$, $f \in L_2(H, d\mathbf{m}; a, b)$. We assume that the measures \mathbf{p} , \mathbf{m} have bounded variations and \mathbf{p} is self-adjoint, \mathbf{m} is non-negative.

We consider a symmetric minimal relation L_0 generated by equation (1). We obtain a form of generalized resolvents of L_0 and give a description of boundary value problems associated to generalized resolvents. We give a detailed example of constructing a generalized resolvent.

If the measures \mathbf{p} , \mathbf{m} are absolutely continuous (i.e., $\mathbf{p}(\Delta) = \int_{\Delta} p(t)dt$, $\mathbf{m}(\Delta) = \int_{\Delta} m(t)dt$ for all Borel sets $\Delta \subset [a,b]$, where p(t), m(t) are bounded operators for fixed t and the functions ||p(t)||, ||m(t)|| belong to $L_1(a,b)$), then integral equation (1) is transformed to a differential equation with a non-negative weight operator function. Linear relations and operators generated by such differential equations were considered in many works (see [23], [6], [9], further detailed bibliography can be found, for example, in [21], [3]).

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The study of integral equation (1) differs essentially from the study of differential equations by the presence of the following features: i) a representation of a solution of equation (1) using an evolutional family of operators is possible if the measures \mathbf{p} , \mathbf{m} have not common single-point atoms (see [12]); ii) the Lagrange formula contains summands relating to single-point atoms of the measures \mathbf{p} , \mathbf{m} (see [13]). This article substantially uses the results of [17]. Also note that this article partially corrects the errors made in the work [11]. Moreover, equation (1) was considered in [14] under the assumption that \mathbf{m} is the usual Lebesque measure on [a, b] and the set of single-point atoms of the measure \mathbf{p} can be arranged as an increasing sequence converging to b. In [14], a formula for generalized resolvents of L_0 is obtained and a description of boundary value problems related to generalized resolvents is given. In [14], L_0 , L_0^* are operators.

2. Preliminary assertions

Let H be a separable Hilbert space with a scalar product (\cdot, \cdot) and a norm $\|\cdot\|$. We consider a function $\Delta \to \mathbf{P}(\Delta)$ defined on Borel sets $\Delta \subset [a,b]$ and taking values in the set of linear bounded operators acting in H. The function \mathbf{P} is called an operator measure on [a,b] (see, for example, $[4, \operatorname{ch}. 5]$) if it is zero on the empty set and the equality $\mathbf{P}(\bigcup_{n=1}^{\infty} \Delta_n) = \sum_{n=1}^{\infty} \mathbf{P}(\Delta_n)$ holds for disjoint Borel sets Δ_n , where the series converges weakly. Further, we extend any measure \mathbf{P} on [a,b] to a segment $[a,b_0]$ ($b_0 > b$) letting $\mathbf{P}(\Delta) = 0$ for each Borel set $\Delta \subset (b,b_0]$.

By $V_{\Delta}(P)$ we denote $V_{\Delta}(P) = \rho_P(\Delta) = \sup \sum_n ||P(\Delta_n)||$, where the supremum is taken over all finite sums of disjoint Borel sets $\Delta_n \subset \Delta$. The number $V_{\Delta}(P)$ is called the variation of the measure P on the Borel set Δ . Suppose that the measure P has the bounded variation on [a,b]. Then for ρ_P -almost all $s \in [a,b]$ there exists an operator function $s \to \Psi_P(s)$ such that Ψ_P possesses the values in the set of linear bounded operators acting in H, $||\Psi_P(s)|| = 1$, and the equality

$$\mathbf{P}(\Delta) = \int_{\Delta} \Psi_{\mathbf{P}}(s) d\rho_{\mathbf{P}} \tag{2}$$

holds for each Borel set $\Delta \subset [a, b]$. The function Ψ_P is uniquely determined up to values on a set of zero ρ_P -measure. Integral (2) converges with respect to the usual operator norm ([4, ch. 5]).

Further, $\int_{t_0}^t$ stands for $\int_{[t_0t)}$ if $t_0 < t$, for $-\int_{[t,t_0)}$ if $t_0 > t$, and for 0 if $t_0 = t$. This implies that $y(a) = x_0$ in equation (1). A function h is integrable with respect to the measure \mathbf{P} on a set Δ if there exists the Bochner integral $\int_{\Delta} \Psi_{\mathbf{P}}(t)h(t)d\rho_{\mathbf{P}} = \int_{\Delta} (d\mathbf{P})h(t)$. Then the function $y(t) = \int_{t_0}^t (d\mathbf{P})h(s)$ is continuous from the left.

By S_P denote a set of single-point atoms of the measure P (i.e., a set $t \in [a, b]$ such that $P(\{t\}) \neq 0$). The set S_P is at most countable. The measure P is continuous if $S_P = \emptyset$, it is self-adjoint if $(P(\Delta))^* = P(\Delta)$ for each Borel set $\Delta \subset [a, b]$, it is non-negative if $(P(\Delta)x, x) \geq 0$ for all Borel sets $\Delta \subset [a, b]$ and for all elements $x \in H$.

In following Lemma 2.1, \mathbf{p}_1 , \mathbf{p}_2 , \mathbf{q} are operator measures having bounded variations on [a,b] and taking values in the set of linear bounded operators acting in H. Suppose that the measure \mathbf{q} is self-adjoint. We assume that these measures are extended on the segment $[a,b_0] \supset [a,b_0) \supset [a,b]$ in the manner described above.

Lemma 2.1. [13] Let f, g be functions integrable on $[a, b_0]$ with respect to the measure \mathbf{q} and $y_0, z_0 \in H$. Then any functions

$$y(t) = y_0 - iJ \int_{t_0}^t d\mathbf{p}_1(s)y(s) - iJ \int_{t_0}^t d\mathbf{q}(s)f(s), \quad z(t) = z_0 - iJ \int_{t_0}^t d\mathbf{p}_2(s)z(s) - iJ \int_{t_0}^t d\mathbf{q}(s)g(s) \quad (a \le t_0 < b_0, \ t_0 \le t \le b_0)$$

satisfy the following formula (analogous to the Lagrange one):

$$\int_{c_{1}}^{c_{2}} (d\mathbf{q}(t)f(t), z(t)) - \int_{c_{1}}^{c_{2}} (y(t), d\mathbf{q}(t)g(t)) = (iJy(c_{2}), z(c_{2})) - (iJy(c_{1}), z(c_{1})) + \int_{c_{1}}^{c_{2}} (y(t), d\mathbf{p}_{2}(t)z(t)) - \int_{c_{1}}^{c_{2}} (d\mathbf{p}_{1}(t)y(t), z(t)) - \sum_{t \in S_{\mathbf{p}_{1}} \cap S_{\mathbf{p}_{2}} \cap [c_{1}, c_{2})} (iJ\mathbf{p}_{1}(\{t\})y(t), \mathbf{p}_{2}(\{t\})z(t)) - \sum_{t \in S_{\mathbf{q}} \cap S_{\mathbf{p}_{2}} \cap [c_{1}, c_{2})} (iJ\mathbf{q}(\{t\})f(t), \mathbf{q}(\{t\})g(t)) - \sum_{t \in S_{\mathbf{p}_{1}} \cap S_{\mathbf{q}} \cap [c_{1}, c_{2})} (iJ\mathbf{q}(\{t\})g(t)) - \sum_{t \in S_{\mathbf{q}} \cap [c_{1}, c_{2})} (iJ\mathbf{q}(\{t\})f(t), \mathbf{q}(\{t\})g(t)), \quad t_{0} \leq c_{1} < c_{2} \leq b_{0}. \quad (3)$$

Further we assume that measures \mathbf{p} , \mathbf{m} have bounded variations and \mathbf{p} is self-adjoint, \mathbf{m} is non-negative. We consider equation (1), where $x_0 \in H$, f is integrable with respect to the measure \mathbf{m} on [a,b], $a \le t \le b_0$. We construct a continuous measure \mathbf{p}_0 from the measure \mathbf{p} in the following way. We set $\mathbf{p}_0(\{t_k\}) = 0$ for $t_k \in \mathcal{S}_{\mathbf{p}}$ and we set $\mathbf{p}_0(\Delta) = \mathbf{p}(\Delta)$ for all Borel sets such that $\Delta \cap \mathcal{S}_{\mathbf{p}} = \emptyset$. Similarly, we construct a continuous measure \mathbf{m}_0 from the measure \mathbf{m} . We denote $\widehat{\mathbf{p}} = \mathbf{p} - \mathbf{p}_0$, $\widehat{\mathbf{m}} = \mathbf{m} - \mathbf{m}_0$. Then $\widehat{\mathbf{p}}(\{t_k\}) = \mathbf{p}(\{t_k\})$ for all $t_k \in \mathcal{S}_{\mathbf{p}}$ and $\widehat{\mathbf{p}}(\Delta) = 0$ for all Borel sets Δ such that $\Delta \cap \mathcal{S}_{\mathbf{p}} = \emptyset$. The similar equalities hold for the measure $\widehat{\mathbf{m}}$. The measures \mathbf{p}_0 , $\widehat{\mathbf{p}}$, \mathbf{m}_0 , $\widehat{\mathbf{m}}$ are self-adjoint and the measures \mathbf{m}_0 , $\widehat{\mathbf{m}}$ are non-negative.

We replace \mathbf{p} by \mathbf{p}_0 and \mathbf{m} by \mathbf{m}_0 in (1). Then we obtain the equation

$$y(t) = x_0 - iJ \int_a^t d\mathbf{p}_0(s)y(s) - iJ \int_a^t d\mathbf{m}_0(s)f(s). \tag{4}$$

Equations (1), (4) have unique solutions (see [12]).

By $W(t, \lambda)$ denote an operator solution of the equation

$$W(t,\lambda)x_0 = x_0 - iJ \int_a^t d\mathbf{p}_0(s)W(s,\lambda)x_0 - iJ\lambda \int_a^t d\mathbf{m}_0(s)W(s,\lambda)x_0, \tag{5}$$

where $x_0 \in H$, $\lambda \in \mathbb{C}$ (\mathbb{C} is the set of complex numbers). It follows from Lemma 2.1 that $W^*(t,\overline{\lambda})JW(t,\lambda) = J$. The functions $t \to W(t,\lambda)$ and $t \to W^{-1}(t,\lambda) = JW^*(t,\overline{\lambda})J$ are continuous with respect to the uniform operator topology. Consequently there exist constants $\varepsilon_1 > 0$, $\varepsilon_2 > 0$ such that the inequality $\varepsilon_1 ||x||^2 \le ||W(t,\lambda)x||^2 \le \varepsilon_2 ||x||^2$ holds for all $x \in H$, $t \in [a,b_0]$, $\lambda \in C \subset \mathbb{C}$ (C is a compact set).

Lemma 2.2. [17]. Suppose that a function f is integrable with respect to the measure \mathbf{m} . A function g is a solution of the equation

$$y(t) = x_0 - iJ \int_a^t d\mathbf{p}_0(s)y(s) - iJ\lambda \int_a^t d\mathbf{m}_0(s)y(s) - iJ \int_a^t d\mathbf{m}(s)f(s), \quad x_0 \in H, \quad a \le t \le b_0,$$
 (6)

if and only if y has the form

$$y(t) = W(t,\lambda)x_0 - W(t,\lambda)iJ\int_a^t W^*(\xi,\overline{\lambda})d\mathbf{m}(\xi)f(\xi).$$

3. Linear relations generated by the integral equation

This article is a continuation of the work [17]. In this section, we provide definitions and statements from [17] that are used in this article.

Let **B** be a Hilbert space. A linear relation T is understood as any linear manifold $T \subset \mathbf{B} \times \mathbf{B}$. The terminology on the linear relations can be found, for example, in [19], [25], [2]. In what follows we make use of the following notations: $\{\cdot,\cdot\}$ is an ordered pair; $\mathcal{D}(T)$ is the domain of T; $\mathcal{R}(T)$ is the range of T; ker T is a set of elements $x \in \mathbf{B}$ such that $\{x,0\} \in T$; T^{-1} is the relation inverse for T, i.e., the relation formed by the

pairs $\{x', x\}$, where $\{x, x'\} \in T$. A relation T is called surjective if $\mathcal{R}(T) = \mathbf{B}$. A relation T is called invertible or injective if $\ker T = \{0\}$ (i.e., the relation T^{-1} is an operator); it is called continuously invertible if it is closed, invertible, and surjective (i.e., T^{-1} is a bounded everywhere defined operator). A relation T^* is called adjoint for T if T^* consists of all pairs $\{y_1, y_2\}$ such that equality $(x_2, y_1) = (x_1, y_2)$ holds for all pairs $\{x_1, x_2\} \in T$. A relation T is called symmetric if $T \subset T^*$ and self-adjoint if $T = T^*$.

It is known (see, for example, [20, ch.3], [19, ch.1]) that the graph of an operator $T: \mathcal{D}(T) \to \mathbf{B}$ is the set of pairs $\{x, Tx\} \in \mathbf{B} \times \mathbf{B}$, where $x \in \mathcal{D}(T) \subset \mathbf{B}$. Consequently, the linear operators can be treated as linear relations; this is why the notation $\{x_1, x_2\} \in T$ is used also for the operator T. Since all considered relations are linear, we shall often omit the word "linear".

Let **m** is a non-negative operator measure defined on Borel sets $\Delta \subset [a, b]$ and taking values in the set of linear bounded operators acting in the space H. The measure **m** is assumed to have a bounded variation

on [a,b]. We introduce the quasi-scalar product $(x,y)_{\mathbf{m}} = \int_a^{b_0} ((d\mathbf{m})x(t),y(t))$ on a set of step-like functions with values in H defined on the segment $[a,b_0]$. Identifying with zero functions y obeying $(y,y)_{\mathbf{m}}=0$ and making the completion, we arrive at the Hilbert space denoted by $L_2(H,d\mathbf{m};a,b)=\mathfrak{H}$. The elements of \mathfrak{H} are the classes of functions identified with respect to the norm $\|y\|_{\mathbf{m}}=(y,y)_{\mathbf{m}}^{1/2}$. In order not to complicate the terminology, the class of functions with a representative y is indicated by the same symbol and we write $y \in \mathfrak{H}$. The equality of functions in \mathfrak{H} is understood as the equality for associated equivalence classes.

Let us define a *minimal relation* L_0 in the following way. The relation L_0 consists of all pairs $\{\widetilde{y}, f_0\} \in \mathfrak{H} \times \mathfrak{H}$ satisfying the condition: for each pair $\{\widetilde{y}, \widetilde{f_0}\}$ there exists a pair $\{y, f_0\}$ such that the pairs $\{\widetilde{y}, \widetilde{f_0}\}$, $\{y, f_0\}$ are identical in $\mathfrak{H} \times \mathfrak{H}$ and $\{y, f_0\}$ satisfies equation (1) and the equalities

$$y(a) = y(b_0) = y(\alpha) = 0, \quad \alpha \in S_p; \quad \mathbf{m}(\{\beta\}) f_0(\beta) = 0, \quad \beta \in S_m.$$
 (7)

Further, without loss of generality it can be assumed that if $\{y, f_0\} \in L_0$, then equalities (1), (7) hold for this pair. In general, the relation L_0 is not an operator since a function y can happen to be identified with zero in \mathfrak{H} , while f is non-zero. The relation L_0 is symmetric and closed. We note that if $y \in \mathcal{D}(L_0)$, then y is continuous and y(b) = 0 (see[16], [17]).

By $\mathfrak{X}_A = \mathfrak{X}_A(t)$ denote an operator characteristic function of a set A, i.e., $\mathfrak{X}_A(t) = E$ if $t \in A$ and $\mathfrak{X}_A(t) = 0$ if $t \notin A$. We shall often omit the argument t in the notation \mathfrak{X}_A . By $\overline{\mathcal{S}}_p$ denote the closure of the set \mathcal{S}_p . Let \mathcal{S}_0 be the set $t \in [a, b]$ such that y(t) = 0 for all $y \in \mathcal{D}(L_0)$. The set \mathcal{S}_0 is closed and $\overline{\mathcal{S}}_p \cup \{a\} \cup \{b\} \subset \mathcal{S}_0$ (see[17]).

Lemma 3.1. [17]. Suppose $\{y, f\} \in L_0$. Then f(t) = 0 for **m**-almost all $t \in S_0$.

By \mathfrak{H}_0 (by \mathfrak{H}_1) denote a subspace of functions that vanish on $[a,b] \setminus S_0$ (on S_0 , respectively) with respect to the norm in \mathfrak{H} . The subspaces \mathfrak{H}_0 , \mathfrak{H}_1 are orthogonal and $\mathfrak{H} = \mathfrak{H}_0 \oplus \mathfrak{H}_1$. We note that $\mathfrak{H}_0 = \{0\}$ if and only if $\mathbf{m}(S_0) = 0$. We denote $L_{10} = L_0 \cap (\mathfrak{H}_1 \times \mathfrak{H}_1)$. Then $\mathcal{D}(L_{10}) \subset \mathfrak{H}_1$, $\mathcal{R}(L_{10}) \subset \mathfrak{H}_1$. It follows from Lemma 3.1 that

$$L_0^* = (\mathfrak{H}_0 \times \mathfrak{H}_0) \oplus L_{10}^*, \tag{8}$$

i.e., the relation L_0^* consists of all pairs $\{y,f\} \in \mathfrak{H}$ of the form $\{y,f\} = \{u,v\} + \{z,g\} = \{u+z,v+g\}$, where $u,v \in \mathfrak{H}_0$, $\{z,g\} \in L_{10}^*$.

The set $\mathcal{T}_{\mathbf{p}} = (a,b) \setminus \mathcal{S}_0$ is open and it is the union of at most a countable number of disjoint open intervals \mathcal{J}_k , i.e., $\mathcal{T}_{\mathbf{p}} = \bigcup_{k=1}^{k_1} \mathcal{J}_k$ and $\mathcal{J}_k \cap \mathcal{J}_j = \emptyset$ for $k \neq j$, where \mathbb{k}_1 is a natural number (equal to the number of intervals if this number is finite) or the symbol ∞ (if the number of intervals is infinite). By \mathbb{J} denote the set of these intervals \mathcal{J}_k . We note that the boundaries α_k , β_k of any interval $\mathcal{J}_k = (\alpha_k, \beta_k) \in \mathbb{J}$ belong to \mathcal{S}_0 .

We denote

$$w_k(t,\lambda) = \mathfrak{X}_{[\alpha_k,\beta_k)} W(t,\lambda) W^{-1}(\alpha_k,\lambda),\tag{9}$$

where $(\alpha_k, \beta_k) = \mathcal{J}_k \in \mathbb{J}$. Then (see[17])

$$w_{\nu}^{*}(t,\overline{\lambda})Jw_{k}(t,\lambda) = J, \quad \alpha_{k} \leq t < \beta_{k}. \tag{10}$$

By \mathfrak{H}_{10} (by \mathfrak{H}_{11}) denote a subspace of functions that belong to \mathfrak{H}_1 and vanish on \mathcal{S}_m (on $[a,b] \setminus \mathcal{S}_m$, respectively) with respect to the norm in \mathfrak{H}_{0} . So, \mathfrak{H}_{10} (\mathfrak{H}_{11}) consists of functions of the form $\mathfrak{X}_{[a,b]\setminus(\mathcal{S}_0\cup\mathcal{S}_m)}h$ (of the form $\mathfrak{X}_{\mathcal{S}_m\setminus\mathcal{S}_0}h$, respectively), where $h\in\mathfrak{H}$ is an arbitrary function. Therefore,

$$\mathfrak{H}_1 = \mathfrak{H}_{10} \oplus \mathfrak{H}_{11}, \quad \mathfrak{H} = \mathfrak{H}_0 \oplus \mathfrak{H}_{10} \oplus \mathfrak{H}_{11}.$$

Obviously, the space \mathfrak{H}_{11} is the closure in \mathfrak{H} of the linear span of functions that have the form $\mathfrak{X}_{\{\tau\}}(\cdot)x$, where $x \in H$, $\tau \in \mathcal{S}_{\mathbf{m}} \setminus \mathcal{S}_{0}$. By (7), it follows that $\mathfrak{H}_{11} \subset \ker L_{10}^{*}$.

Let $u_k(t, \lambda, \tau)$: $H \rightarrow \mathfrak{H}_1$ be an operator acting by the formula

$$u_{k}(t,\lambda,\tau)x = -\mathfrak{X}_{[a,b]\backslash S_{\mathbf{m}}}w_{k}(t,\lambda)iJ\int_{a}^{t}w_{k}^{*}(s,\overline{\lambda})d\mathbf{m}(s)\lambda\mathfrak{X}_{\{\tau\}}(s)x,\tag{11}$$

where $x \in H$, $\tau \in (\alpha_k, \beta_k) \cap S_{\mathbf{m}}$, $(\alpha_k, \beta_k) = \mathcal{J}_k \in \mathbb{J}$. Then (see[17]) for any $x \in H$ the function

$$u_k(\cdot, \lambda, \tau)x + \mathfrak{X}_{\{\tau\}}(\cdot)x \in \ker(L_{10}^* - \lambda E).$$

Lemma 3.2. [17]. The linear span of functions of the form $\mathfrak{X}_{[a,b]\setminus\mathcal{S}_{\mathbf{m}}}w_k(\cdot,\lambda)x_0$ and $u_k(\cdot,\lambda,\tau)B_kx_j+\mathfrak{X}_{\{\tau\}}(\cdot)B_kx_j$ is dense in $\ker(L_{10}^*-\lambda E)$. Here $x_j,x_0\in H$; $\tau\in(\alpha_k,\beta_k)\cap\mathcal{S}_{\mathbf{m}}$; $B_k:H\to H$ is a bounded continuously invertible operator; $k=1,...,\mathbb{k}_1$ if \mathbb{k}_1 is finite and k is any natural number if \mathbb{k}_1 is infinite.

Let \mathbb{M} be a set consisting of intervals $\mathcal{J} \in \mathbb{J}$ and single-point sets $\{\tau\}$, where $\tau \in \mathcal{S}_m \setminus \mathcal{S}_0$. The set \mathbb{M} is at most countable. Let \mathbb{k} be the number of elements in \mathbb{M} . We arrange the elements of \mathbb{M} in the form of a finite or infinite sequence and denote these elements by \mathcal{E}_k , where k is any natural number if the number of elements in \mathbb{M} is infinite, and $1 \le k \le \mathbb{k}$ if the number of elements in \mathbb{M} is finite.

To each element $\mathcal{E}_k \in \mathbb{M}$ assign an operator function v_k in the following way. If \mathcal{E}_k is the interval, $\mathcal{E}_k = \mathcal{J}_k = (\alpha_k, \beta_k) \in \mathbb{J}$, then

$$v_k(t,\lambda) = \mathfrak{X}_{[\alpha_k,\beta_k)\backslash S_{\mathfrak{m}}} w_k(t,\lambda). \tag{12}$$

If \mathcal{E}_k is a single-point set, $\mathcal{E}_k = \{\tau_k\}, \tau_k \in \mathcal{S}_{\mathbf{m}} \setminus \mathcal{S}_0$, and $\tau_k \in \mathcal{J}_n = (\alpha_n, \beta_n) \in \mathbb{J}$, then

$$v_k(t,\lambda) = u_n(t,\lambda,\tau_k)w_n(\tau_k,\lambda) + \mathfrak{X}_{\{\tau_k\}}(t)w_n(\tau_k,\lambda). \tag{13}$$

Further, we denote $v_k(t, 0) = v_k(t)$. We note that $u_k(t, 0, \tau) = 0$ (see equality (11)).

Let $Q_{k,0}$ be a set $x \in H$ such that the functions $t \to v_k(t)x$ are identical with zero in \mathfrak{S} . We put $Q_k = H \ominus Q_{k,0}$. On the linear space Q_k we introduce a norm $\|\cdot\|_{-}$ by the equality

$$\|\xi_k\|_{-} = \|v_k(\cdot)\xi_k\|_{\mathfrak{H}}, \quad \xi_k \in Q_k. \tag{14}$$

By Q_k^- denote the completion of Q_k with respect to norm (14). The space Q_k^- can be treated as a space with a negative norm with respect to Q_k ([4, ch. 1], [19, ch.2]). By Q_k^+ denote the associated space with a positive norm. The definition of spaces with positive and negative norms implies that $Q_k^+ \subset Q_k \subset Q_k^-$. By $(\cdot, \cdot)_+$ and $\|\cdot\|_+$ we denote the scalar product and the norm in Q_k^+ , respectively.

Remark 3.3. The set $Q_{k,0}$ will not change if the function $v_k(\cdot) = v_k(\cdot,0)$ is replaced by $v_k(\cdot,\lambda)$ in the definition of $Q_{k,0}$. Moreover, with such replacement, the space Q_k^- will not change in the following sense: the set Q_k^- will not change, and the norm in it will be replaced by the equivalent one. The similar statement holds for the space Q_k^+ (see [17]).

Suppose that a sequence $\{x_{kn}\}$, $x_{kn} \in Q_k$, converges in the space Q_k^- to $x_0 \in Q_k^-$ as $n \to \infty$. Then the sequence $\{v_k(\cdot, \lambda)x_{kn}\}$ is fundamental in \mathfrak{H} . Therefore this sequence converges to some element in \mathfrak{H} . By $v_k(\cdot, \lambda)x_0$ we denote this element.

Let $\widetilde{Q}_N^- = Q_1^- \times ... \times Q_N^-$ ($\widetilde{Q}_N^+ = Q_1^+ \times ... \times Q_N^+$) be the Cartesian product of the first N sets Q_k^- (Q_k^+ , respectively) and let $V_N(t,\lambda) = (v_1(t,\lambda),...,v_N(t,\lambda))$ be the operator one-row matrix. It is convenient to treat elements from \widetilde{Q}_N^- as one-column matrices, and to assume that $V_N(t,\lambda)\widetilde{\xi}_N = \sum_{k=1}^N v_k(t,\lambda)\xi_k$, where we denote $\widetilde{\xi}_N = \sum_{k=1}^N v_k(t,\lambda)\xi_k$, where we denote $\widetilde{\xi}_N = \sum_{k=1}^N v_k(t,\lambda)\xi_k$.

 $\operatorname{col}(\xi_1,...,\xi_N) \in \widetilde{Q}_N^-, \ \xi_k \in Q_k^-.$ Let $\ker_k(\lambda)$ be a linear space of functions $t \to v_k(t,\lambda)\xi_k, \ \xi_k \in Q_k^-.$ The space $\ker_k(\lambda)$ is closed in \mathfrak{H} . We denote $\mathcal{K}_N(\lambda) = \ker_1(\lambda) \dotplus ... \dotplus \ker_N(\lambda)$. Obviously, $\mathcal{K}_{N_1}(\lambda) \subset \mathcal{K}_{N_2}(\lambda)$ for $N_1 < N_2$. By $\mathcal{V}_N(\lambda)$ denote the operator $\widetilde{\xi}_N \to V_N(\cdot,\lambda)\widetilde{\xi}_N$, where $\widetilde{\xi}_N \in \widetilde{Q}_N^-.$ The operator $\mathcal{V}_N(\lambda)$ maps continuously and one-to-one \widetilde{Q}_N^- onto $\mathcal{K}_N(\lambda) \subset \mathfrak{H}_1 \subset \mathfrak{H}$.

Let Q_- , Q_+ , Q be linear spaces of sequences, respectively, $\widetilde{\eta} = \{\eta_k\}$, $\widetilde{\varphi} = \{\varphi_k\}$, $\widetilde{\xi} = \{\xi_k\}$, where $\eta_k \in Q_k^-$, $\varphi_k \in Q_k^+$, $\xi_k \in Q_k$; $k \in \mathbb{N}$ if $\mathbb{k} = \infty$, and $1 \le k \le \mathbb{k}$ if \mathbb{k} is finite; \mathbb{k} is the number of elements in \mathbb{M} . We assume that the series $\sum_{k=1}^{\infty} \|\eta_k\|_-^2$, $\sum_{k=1}^{\infty} \|\varphi_k\|_+^2$, $\sum_{k=1}^{\infty} \|\xi_k\|^2$ converge if $\mathbb{k} = \infty$. These spaces become Hilbert spaces if we introduce scalar products by the formulas

$$(\widetilde{\eta},\widetilde{\zeta})_{-} = \sum_{k=1}^{\mathbb{k}} (\eta_{k},\zeta_{k})_{-}, \quad \widetilde{\eta},\widetilde{\zeta} \in Q_{-}; \quad (\widetilde{\varphi},\widetilde{\psi})_{+} = \sum_{k=1}^{\mathbb{k}} (\varphi_{k},\psi_{k})_{+}, \quad \widetilde{\varphi},\widetilde{\psi} \in Q_{+}; \quad (\widetilde{\xi},\widetilde{\sigma}) = \sum_{k=1}^{\mathbb{k}} (\xi_{k},\sigma_{k}), \quad \widetilde{\xi},\widetilde{\sigma} \in Q.$$

The spaces Q_+, Q_- can be treated as spaces with positive and negative norms with respect to Q ([4, ch. 1], [19, ch.2]). So $Q_+ \subset Q \subset Q_-$ and $\gamma_1 \|\widetilde{\varphi}\|_- \le \|\widetilde{\varphi}\| \le \gamma_2 \|\widetilde{\varphi}\|_+$, where $\widetilde{\varphi} \in Q_+$, $\gamma_1, \gamma_2 > 0$. The "scalar product" $(\widetilde{\eta}, \widetilde{\varphi})$ is defined for all $\widetilde{\varphi} \in Q_+$, $\widetilde{\eta} \in Q_-$. If $\widetilde{\eta} \in Q$, then $(\widetilde{\eta}, \widetilde{\varphi})$ coincides with the scalar product in Q.

Let $\mathcal{M} \subset Q_-$ be a set of sequences vanishing starting from a certain number (its own for each sequence). The set \mathcal{M} is dense in the space Q_- . The operator $\mathcal{V}_N(\lambda)$ is the restriction of $\mathcal{V}_{N+1}(\lambda)$ to \widetilde{Q}_N^- . By $\mathcal{V}'(\lambda)$ denote an operator in \mathcal{M} such that $\mathcal{V}'(\lambda)\widetilde{\eta} = \mathcal{V}_N(\lambda)\widetilde{\eta}_N$ for all $N \in \mathbb{N}$, where $\widetilde{\eta} = (\widetilde{\eta}_N, 0, ...)$, $\widetilde{\eta}_N \in \widetilde{Q}_N^-$. The operator $\mathcal{V}'(\lambda)$ admits an extension by continuity to the space Q_- . By $\mathcal{V}(\lambda)$ denote the extended operator. This operator maps continuously and one-to-one Q_- onto $\ker(L_{10}^* - \lambda E) \subset \mathfrak{H}_1 \subset \mathfrak{H}$. Moreover, we denote $\widetilde{V}(t,\lambda)\widetilde{\eta} = (\mathcal{V}(\lambda)\widetilde{\eta})(t)$, where $\widetilde{\eta} = \{\eta_k\} \in Q_-$.

The adjoint operator $\mathcal{V}^*(\lambda)$ maps continuously $\mathfrak H$ onto Q_+ and

$$\mathcal{V}^*(\lambda)f = \int_a^{b_0} \widetilde{V}^*(t,\lambda) d\mathbf{m}(t) f(t). \tag{15}$$

Lemma 3.4. [17]. The operator $V(\lambda)$ maps Q_- onto $\ker(L_{10}^* - \lambda E)$ continuously and one to one. A function z belongs to $\ker(L_{10}^* - \lambda E)$ if and only if there exists an element $\widetilde{\eta} = \{\eta_k\} \in Q_-$ such that $z(t) = (V(\lambda)\widetilde{\eta})(t) = \widetilde{V}(t,\lambda)\widetilde{\eta}$. The operator $V^*(\lambda)$ maps $\mathfrak S$ onto Q_+ continuously, and acts by formula (15), and $\ker V^*(\lambda) = \mathfrak S_0 \oplus \mathcal R(L_{10} - \overline{\lambda}E)$. Moreover, $V^*(\lambda)$ maps $\ker(L_{10}^* - \lambda E)$ onto Q_+ one to one.

The following theorem is proved in [17]. We have changed some designations from [17] to shorten the record.

Theorem 3.5. A pair $\{\widetilde{y}, \widetilde{f}\} \in \mathfrak{H} \times \mathfrak{H}$ belongs to $L_0^* - \lambda E$ if and only if there exist a pair $\{\widehat{y}, \widehat{f}\} \in \mathfrak{H} \times \mathfrak{H}$, functions $y_0, y_0' \in \mathfrak{H}_0$, $y_0, f \in \mathfrak{H}_1$, and an element $\widetilde{\eta} \in Q_-$ such that the pairs $\{\widetilde{y}, \widetilde{f}\}$, $\{\widehat{y}, \widehat{f}\}$ are identical in $\mathfrak{H} \times \mathfrak{H}$ and the equalities

$$\widehat{y} = y_0 + y, \ \widehat{f} = y_0' + f,$$

$$y(t) = \widetilde{V}(t,\lambda)\widetilde{\eta} - \sum_{k=1}^{\mathbb{k}_1} \mathfrak{X}_{[a,b] \setminus \mathcal{S}_{\mathbf{m}}} w_k(t,\lambda) i J \int_a^t w_k^*(s,\overline{\lambda}) d\mathbf{m}(s) f(s)$$
(16)

hold, where the series in (16) converges in \mathfrak{H} , \mathbb{K}_1 is the number of intervals $\mathcal{J}_k \in \mathbb{J}$.

4. The description of generalized resolvents

Let T be a symmetric relation, $T \subset \mathbf{B} \times \mathbf{B}$ (\mathbf{B} is a Hilbert space), and let \widetilde{T} be a self-adjoint extension of T to $\widetilde{\mathbf{B}}$, where $\widetilde{\mathbf{B}}$ is a Hilbert space, $\widetilde{\mathbf{B}} \supset \mathbf{B}$, and scalar products coincide in \mathbf{B} and $\widetilde{\mathbf{B}}$. By P denote an orthogonal projection of $\widetilde{\mathbf{B}}$ onto \mathbf{B} . The function $\lambda \to R_{\lambda}$ defined by the formula $R_{\lambda} = P(\widetilde{T} - \lambda E)^{-1}|_{\mathbf{B}}$, $\operatorname{Im}\lambda \neq 0$, is called the generalized resolvent of the relation T (see, for example, [1, ch.9]).

A.V. Straus (see [26]) obtained a formula for all generalized resolvents of a symmetric operator. It is shown in [18] that this formula remains true for symmetric relations also. By \Re_{λ} denote a defect subspace of the symmetric relation T, i.e., the orthogonal complement in \mathbf{B} of the range of the relation $T - \lambda E$. We fix some number λ_0 (Im $\lambda_0 \neq 0$). Let $\lambda \to \mathcal{F}(\lambda)$ be a holomorphic operator function, where $\mathcal{F}(\lambda): \Re_{\lambda_0} \to \Re_{\overline{\lambda_0}}$ is a bounded operator, $\|\mathcal{F}(\lambda)\| \leq 1$, Im $\lambda \cdot \text{Im}\lambda_0 > 0$. Let $T_{\mathcal{F}(\lambda)}$ be the relation consisting of all pairs of the form $\{y_0 + \mathcal{F}(\lambda)z - z, y_1 + \lambda_0 \mathcal{F}(\lambda)z - \overline{\lambda_0}z\}$, where $\{y_0, y_1\} \in T$, $z \in \Re_{\lambda_0}$. Then (see [26], [18]) the family of operators R_{λ} is a generalized resolvent of T if and only if R_{λ} can be represented in the form

$$R_{\lambda} = (T_{\mathcal{F}(\lambda)} - \lambda E)^{-1}, \quad \text{Im} \lambda \cdot \text{Im} \lambda_0 > 0.$$
 (17)

Theorem 4.1. Let R_{λ} (Im $\lambda \neq 0$) be a generalized resolvent of the relation L_{10} and $y = R_{\lambda}f$. Then

$$y(t) = \int_{a}^{b} \widetilde{V}(t,\lambda) M(\lambda) \widetilde{V}^{*}(s,\overline{\lambda}) d\mathbf{m}(s) f(s) +$$

$$+ 2^{-1} \sum_{n=1}^{k_{1}} \int_{a}^{b} \mathfrak{X}_{[\alpha_{n},\beta_{n}) \setminus S_{\mathbf{m}}}(t) w_{n}(t,\lambda) \operatorname{sgn}(s-t) i J w_{n}^{*}(s,\overline{\lambda}) d\mathbf{m}(s) \mathfrak{X}_{[a,b] \setminus S_{\mathbf{m}}}(s) f(s) - \lambda^{-1} \sum_{n=1}^{k_{1}} \mathfrak{X}_{S_{\mathbf{m}} \cap (\alpha_{n},\beta_{n})}(t) f(t), \quad (18)$$

where $M(\lambda): Q_+ \to Q_-$ is the bounded operator such that $M(\overline{\lambda}) = M^*(\lambda)$, $\operatorname{Im}\lambda \neq 0$. The function $\lambda \to M(\lambda)\widetilde{x}$ is holomorphic for every $\widetilde{x} \in Q_+$ in the half-planes $\operatorname{Im}\lambda \neq 0$. If $S_{\mathbf{m}} = \emptyset$, then

$$(\operatorname{Im}\lambda)^{-1}\operatorname{Im}(M(\lambda)\widetilde{x},\widetilde{x}) \geqslant 0 \tag{19}$$

for every λ (Im $\lambda \neq 0$) and for every $\widetilde{x} \in Q_+$.

Proof. Suppose $y = R_{\lambda}f$. By (17), it follows that the pair $\{y, f\} \in L_{10}^* - \lambda E$. Equality (18) follows from (17) and [17, Theorem 4.3]. Using (18), we get

$$y(t) = \widetilde{V}(t,\lambda)M(\lambda) \int_{a}^{b} \widetilde{V}^{*}(s,\overline{\lambda})d\mathbf{m}(s)f(s) + \sum_{n=1}^{k_{1}} \left(-2^{-1}\mathfrak{X}_{[\alpha_{n},\beta_{n})\backslash\mathcal{S}_{\mathbf{m}}}(t)w_{n}(t,\lambda)iJ\int_{\alpha_{n}}^{t} w_{n}^{*}(s,\overline{\lambda})d\mathbf{m}(s)\mathfrak{X}_{[a,b]\backslash\mathcal{S}_{\mathbf{m}}}(s)f(s) + 2^{-1}\mathfrak{X}_{[\alpha_{n},\beta_{n})\backslash\mathcal{S}_{\mathbf{m}}}(t)w_{n}(t,\lambda)iJ\int_{t}^{\beta_{n}} w_{n}^{*}(s,\overline{\lambda})d\mathbf{m}(s)\mathfrak{X}_{[a,b]\backslash\mathcal{S}_{\mathbf{m}}}(s)f(s)\right) - \lambda^{-1}\sum_{n=1}^{k_{1}}\mathfrak{X}_{\mathcal{S}_{\mathbf{m}}\cap(\alpha_{n},\beta_{n})}(t)f(t). \tag{20}$$

Let us prove that the function $\lambda \to M(\lambda)\widetilde{x}$ is holomorphic for every $\widetilde{x} \in Q_+$ (Im $\lambda \neq 0$). We denote $S(\lambda) = M(\lambda)\mathcal{V}^*(\overline{\lambda})$. It follows from (18) and the holomorphicity of the function $\lambda \to R_\lambda$ that the function $\lambda \to V(\lambda)S(\lambda)f$ is holomorphic. Using (10), we obtain that the function $\lambda \to S(\lambda)f$ is holomorphic. Now the holomorphicity of the function $\lambda \to M(\lambda)$ follows from Lemma 4.2. This Lemma is formulated after the proof of the Theorem. In Lemma 4.2 it should be taken that $\mathcal{B}_1 = \mathfrak{H}_1$, $\mathcal{B}_2 = Q_+$, $\mathcal{B}_3 = Q_-$, $T_1(\lambda) = \mathcal{V}^*(\overline{\lambda})$, $T_2(\lambda) = M(\lambda)$, $T_3(\lambda) = S(\lambda)$.

We note that the equality $R_{\lambda}^* = R_{\overline{\lambda}}$ implies $M(\overline{\lambda}) = M^*(\lambda)$.

Let us prove that (19) holds under the condition $S_{\mathbf{m}} = \emptyset$. Then $\mathbf{m} = \mathbf{m}_0$. It follows from Lemma 3.4 that there exists a function $f \in \mathfrak{H}$ such that $\widetilde{x} = \mathcal{V}^*(\overline{\lambda})f$. Let $p_n : Q_- \to Q_n^-$ be the operator defined by the formula $p_n\widetilde{\xi} = \xi_n$, where $\widetilde{\xi} = \{\xi_n\} \in Q_-$. We denote $M_n(\lambda) = p_nM(\lambda)$, $x_n = p_n\widetilde{x}$. Since $S_{\mathbf{m}} = \emptyset$, we obtain from (20)

$$y(t) = \sum_{n=1}^{\mathbb{k}_{1}} \mathfrak{X}_{[\alpha_{n},\beta_{n})}(t)w_{n}(t,\lambda)M_{n}(\lambda)\widetilde{x} + 2^{-1}\sum_{n=1}^{\mathbb{k}_{1}} \left(-\mathfrak{X}_{[\alpha_{n},\beta_{n})}(t)w_{n}(t,\lambda)iJ \int_{\alpha_{n}}^{t} w_{n}^{*}(s,\overline{\lambda})d\mathbf{m}(s)f(s) + \mathfrak{X}_{[\alpha_{n},\beta_{n})}(t)w_{n}(t,\lambda)iJ \int_{t}^{\beta_{n}} w_{n}^{*}(s,\overline{\lambda})d\mathbf{m}(s)f(s) \right). \tag{21}$$

We denote

$$z(t) = \widetilde{V}(t,\lambda)(M(\lambda)\widetilde{x} - 2^{-1}i\widetilde{J}\widetilde{x}) = \sum_{n=1}^{k_1} z_n(t), \quad z_n(t) = \mathfrak{X}_{[\alpha_n,\beta_n)}z = w_n(t,\lambda)(M_n(\lambda)\widetilde{x} - 2^{-1}iJx_n),$$

where \widetilde{I} is the operator in Q acting as $\widetilde{I\xi} = \{I\xi_k\}, \widetilde{\xi} = \{\xi_k\} \in Q$. Using (9), (10), (21), we get

$$y(\alpha_n) = M_n(\lambda)\widetilde{x} + 2^{-1}iJx_n, \quad z_n(\alpha_n) = M_n(\lambda)\widetilde{x} - 2^{-1}iJx_n, \tag{22}$$

$$\lim_{t \to \beta_n = 0} y(t) = \lim_{t \to \beta_n = 0} z_n(t) = W(\beta_n, \lambda) W^{-1}(\alpha_n, \lambda) (M_n(\lambda) \widetilde{x} - 2^{-1} i J x_n). \tag{23}$$

It follows from Lemmas 3.2, 3.4 that $z \in \ker L_{10}^* - \lambda E$. Consequently, $\{y-z, f\} \in L_{10}^* - \lambda E$, $\{y+z, f\} \in L_{10}^* - \lambda E$. Then the pairs $\{y-z, g_1\} \in L_{10}^*$, $\{y+z, g_2\} \in L_{10}^*$, where

$$g_1 = f + \lambda(y - z), \quad g_2 = f + \lambda(y + z).$$
 (24)

We denote $y_n = \mathfrak{X}_{[\alpha_n,\beta_n)}y$, $g_{1n} = \mathfrak{X}_{[\alpha_n,\beta_n)}g_1$, $g_{2n} = \mathfrak{X}_{[\alpha_n,\beta_n)}g_2$, $f_n = \mathfrak{X}_{[\alpha_n,\beta_n)}f$. Then $\{y_n - z_n, g_{1n}\} \in L_{10}^*$, $\{y_n + z_n, g_{2n}\} \in L_{10}^*$. Taking into account Theorem 3.5 (for $\lambda = 0$) and (22), we obtain

$$y_n(t) - z_n(t) = w_n(t,0)iJx_n - w_n(t,0)iJ\int_{\alpha_n}^t w_n^*(s,\overline{\lambda})d\mathbf{m}(s)g_{1n}(s),$$

$$y_n(t) + z_n(t) = 2w_n(t,0)M_n(\lambda)\widetilde{x} - w_n(t,0)iJ\int_{\alpha_n}^t w_n^*(s,\overline{\lambda})d\mathbf{m}(s)g_{2n}(s).$$

It follows from Lemma 2.2 that formula (3) can be applied to the functions $y_n - z_n$, $y_n + z_n$ on the interval $[\alpha_n, \beta]$ ($\alpha_n < \beta < \beta_n$). Using (3), we get

$$\int_{\alpha_{n}}^{\beta} (d\mathbf{m}(t)g_{1n}(t), y_{n}(t) + z_{n}(t)) - \int_{\alpha_{n}}^{\beta} (y_{n}(t) - z_{n}(t), d\mathbf{m}(t)g_{2n}) =$$

$$= (iJ(y_{n}(\beta) - z_{n}(\beta)), y_{n}(\beta) + z_{n}(\beta)) - (iJ(y_{n}(\alpha_{n}) - z_{n}(\alpha_{n})), y_{n}(\alpha_{n}) + z_{n}(\alpha_{n})). \quad (25)$$

Passing to the limit as $\beta \rightarrow \beta_n - 0$ in (25) and taking into account (22), (23), we obtain

$$\int_{\alpha_n}^{\beta_n} (d\mathbf{m}(t)g_{1n}(t), y_n(t) + z_n(t)) - \int_{\alpha_n}^{\beta_n} (y_n(t) - z_n(t), d\mathbf{m}(t)g_{2n}) = 2(x_n, M_n(\lambda)\widetilde{x}).$$
 (26)

On the other hand, using (24), we get

$$(f_n, y_n + z_n)_{\mathfrak{H}} - (y_n - z_n, f_n)_{\mathfrak{H}} = (g_{1n} - \lambda(y_n - z_n), y_n + z_n)_{\mathfrak{H}} - (y_n - z_n, g_{2n} - \lambda(y_n + z_n))_{\mathfrak{H}} =$$

$$= (g_{1n}, y_n + z_n)_{\mathfrak{H}} - (y_n - z_n, g_{2n})_{\mathfrak{H}} - (\lambda - \overline{\lambda})(y_n - z_n, y_n + z_n)_{\mathfrak{H}}. \tag{27}$$

Combining (26) and (27), we obtain

$$(f_n, y_n + z_n)_{\mathfrak{H}} - (y_n - z_n, f_n)_{\mathfrak{H}} = 2(x_n, M_n(\lambda)\widetilde{x}) - (\lambda - \overline{\lambda})(y_n - z_n, y_n + z_n)_{\mathfrak{H}}.$$

Therefore,

$$(f, y+z)_5 - (y-z, f)_5 = 2(\widetilde{x}, M(\lambda)\widetilde{x}) - (\lambda - \overline{\lambda})(y-z, y+z)_5. \tag{28}$$

Equation (28) implies that

$$\operatorname{Im}[(f, y + z)_{\mathfrak{H}} - (y - z, f)_{\mathfrak{H}}] = 2\operatorname{Im}(\widetilde{x}, M(\lambda)\widetilde{x}) - \operatorname{Im}[(\lambda - \overline{\lambda})((y, y)_{\mathfrak{H}} - (z, y)_{\mathfrak{H}} + (y, z)_{\mathfrak{H}} - (z, z)_{\mathfrak{H}})].$$

Therefore,

$$\operatorname{Im}[(f, y)_{5} - (y, f)_{5}] = 2\operatorname{Im}(\widetilde{x}, M(\lambda)\widetilde{x}) - \operatorname{Im}[(\lambda - \overline{\lambda})((y, y)_{5} - (z, z)_{5})].$$

Consequently,

$$(\operatorname{Im}\lambda)^{-1}\operatorname{Im}(M(\lambda)\widetilde{x},\widetilde{x}) = \|z\|_{\mathfrak{H}}^{2} + (\operatorname{Im}\lambda)^{-1}\operatorname{Im}(R_{\lambda}f,f)_{\mathfrak{H}} - (R_{\lambda}f,R_{\lambda}f)_{\mathfrak{H}}.$$

Since $(\text{Im}\lambda)^{-1}\text{Im}(R_{\lambda}f,f)_{\mathfrak{H}} - (R_{\lambda}f,R_{\lambda}f)_{\mathfrak{H}} \ge 0$, we see that (19) holds. The theorem is proved. \square

Lemma 4.2. [10]. Let \mathcal{B}_1 , \mathcal{B}_2 , \mathcal{B}_3 be Banach spaces. Suppose bounded operators $T_3(\lambda): \mathcal{B}_1 \to \mathcal{B}_3$, $T_1(\lambda): \mathcal{B}_1 \to \mathcal{B}_2$, $T_2(\lambda): \mathcal{B}_2 \to \mathcal{B}_3$ satisfy the equality $T_3(\lambda) = T_2(\lambda)T_1(\lambda)$ for every fixed λ belonging to some neighborhood of a point λ_1 and suppose the range of operator $T_1(\lambda_1)$ coincides with \mathcal{B}_2 . If functions $T_1(\lambda)$, $T_3(\lambda)$ are strongly differentiable at the point λ_1 , then function $T_2(\lambda)$ is strongly differentiable at λ_1 .

Remark 4.3. It follows from Lemma 3.1 and (8) that $L_0 \cap \mathfrak{H}_0 \times \mathfrak{H}_0 = \{0,0\}$. Therefore any generalized resolvent \widetilde{R}_{λ} of the relation L_0 has the form $\widetilde{R}_{\lambda} = R_{0\lambda} \oplus R_{\lambda}$, where R_{λ} is some generalized resolvent of L_{10} and $R_{0\lambda}$ is a generalized resolvent of the relation $\{0,0\}$, i.e., $R_{0\lambda} = (T_{\mathcal{F}(\lambda)} - \lambda E)^{-1}$ (see (17)), $T_{\mathcal{F}(\lambda)}$ is the relation consisting of pairs of the form $\{\mathcal{F}(\lambda)z - z, \lambda_0\mathcal{F}(\lambda)z - \overline{\lambda}_0z\}$ (here $\mathcal{F}(\lambda):\mathfrak{H}_0 \to \mathfrak{H}_0$ is a bounded operator, $\|\mathcal{F}(\lambda)\| \leq 1$, $z \in \mathfrak{H}_0$, the operator function $\lambda \to \mathcal{F}(\lambda)$ is holomorphic, $\mathrm{Im}\lambda \cdot \mathrm{Im}\lambda_0 > 0$).

Remark 4.4. In general, if $S_m \neq \emptyset$, then the inequality $(\text{Im}\lambda)^{-1}\text{Im}(M(\lambda)\widetilde{x},\widetilde{x}) < 0$ is possible (see Remark 6.1).

5. Boundary value problems connected with generalized resolvents

To shorten the notation, we denote $w_k(t,0) = w_k(t)$, $\widetilde{V}(t,0) = \widetilde{V}(t)$, V(0) = V. It follows from Lemma 3.4 (for $\lambda = 0$) that V^*f ($f \in \mathfrak{H}$) is an element of the space $Q_+ \subset Q$, i.e., a sequence with elements of the form

$$\mathfrak{X}_{[\alpha_n,\beta_n)\backslash S_{\mathbf{m}}} \int_{\alpha_n}^{\beta_n} w_n^*(t) d\mathbf{m}(t) f(t), \tag{29}$$

$$\boldsymbol{w}_{n}^{*}(\tau_{nk})\mathbf{m}(\{\tau_{nk}\})f(\tau_{nk}) \tag{30}$$

(and possibly with zeros), where $\tau_{nk} \in (S_{\mathbf{m}} \setminus S_0) \cap \mathcal{J}_n$; $(\alpha_n, \beta_n) = \mathcal{J}_n$; $\mathcal{J}_n \in \mathbb{J}$; $1 \le n \le \mathbb{k}_1$ if the number \mathbb{k}_1 of intervals $\mathcal{J}_n \in \mathbb{J}$ is finite, and n is any natural number if $\mathbb{k}_1 = \infty$. We replace elements (29) by zeros in \mathcal{V}^*f . By \mathcal{V}_0^*f denote the resulting sequence. So, \mathcal{V}_0^*f is a sequence with elements of form (30) (and possibly with zeros). Further, we replace each element (29) and (30) in \mathcal{V}^*f by the element

$$\sigma_n = \int_{\alpha_n}^{\beta_n} w_n^*(t) d\mathbf{m}(t) f(t) = \int_{\alpha_n}^{\beta_n} \mathfrak{X}_{[\alpha_n, \beta_n) \setminus \mathcal{S}_{\mathbf{m}}} w_n^*(t) d\mathbf{m}(t) f(t) + \sum_{\tau_{nk} \in \mathcal{S}_{\mathbf{m}} \cap (\alpha_n, \beta_n)} w_n^*(\tau_{nk}) \mathbf{m}(\{\tau_{nk}\}) f(\tau_{nk}).$$
(31)

By $\mathcal{V}_* f$ denote the resulting sequence. We claim that $\mathcal{V}_* f \in Q_-$. Indeed, let $\mathcal{V}_* f = \widetilde{\sigma} = \{\sigma_n\}$. It follows from (9), (10), (31) that $\|\sigma_n\| < \varepsilon_1 \|f\|_{\mathfrak{H}} = \varepsilon_2$, where $\varepsilon_1 > 0$, ε_1 is independent of n. Then

$$\widetilde{\mathcal{V}\sigma} = \mathcal{V}(0)\widetilde{\sigma} = \sum_{n=1}^{k_1} \left(\mathfrak{X}_{[\alpha_n,\beta_n) \setminus \mathcal{S}_{\mathbf{m}}} w_n(t) \sigma_n + \sum_{\tau_{nk} \in \mathcal{S}_{\mathbf{m}} \cap (\alpha_n,\beta_n)} \mathfrak{X}_{[\tau_{nk}]} w_n(\tau_{nk}) \sigma_n \right),$$

and

$$\left\| \mathcal{V}\widetilde{\sigma} \right\|_{\mathfrak{H}}^{2} = \sum_{n=1}^{\mathbb{k}_{1}} \left(\left\| \mathfrak{X}_{[\alpha_{n},\beta_{n})\backslash\mathcal{S}_{\mathbf{m}}} w_{n}(t)\sigma_{n} \right\|_{\mathfrak{H}}^{2} + \sum_{\tau_{nk}\in\mathcal{S}_{\mathbf{m}}\cap(\alpha_{n},\beta_{n})} \left\| \mathfrak{X}_{\{\tau_{nk}\}} w_{n}(\tau_{nk})\sigma_{n} \right\|_{\mathfrak{H}}^{2} \right) = \sum_{n=1}^{\mathbb{k}_{1}} \left\| w_{n}(t)\sigma_{n} \right\|_{\mathfrak{H}}^{2} \leqslant \varepsilon_{3}, \quad \varepsilon_{3} > 0. \quad (32)$$

By (14), (15), (32), and the definition of Q_- , it follows that $\widetilde{\sigma} \in Q_-$. We note that this proof uses only the boundedness of the sequence $\{\sigma_n\}$ in H.

Further, we replace each element (30) in $\mathcal{V}_0^* f$ by the element $\int_{\alpha_n}^{\tau_{nk}} w^*(s) d\mathbf{m}(s) f(s)$. By $\mathcal{V}_{*\tau} f$ denote the resulting sequence. Then $\mathcal{V}_{*\tau} f \in Q_-$ (the proof is the same as for $\mathcal{V}_* f$). It follows from the definition $\mathcal{V}^* f$, $\mathcal{V}_0^* f$, that the equalities

$$(\mathcal{V}^*f, \mathcal{V}_0^*g) = (\mathcal{V}_0^*f, \mathcal{V}g) = (\mathcal{V}_0^*f, \mathcal{V}_0^*g), \quad (\mathcal{V}_{*\tau}f, \mathcal{V}^*g) = (\mathcal{V}_{*\tau}f, \mathcal{V}_0^*g), \quad f, g \in \mathfrak{H},$$
(33)

$$\sum_{n=1}^{k_1} \left(i \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) f(s), \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) g(s) \right) = (i \widetilde{f} \mathcal{V}_* f, \mathcal{V}^* g) = (i \widetilde{f} \mathcal{V}^* f, \mathcal{V}_* g), \quad f, g \in \mathfrak{H}$$
(34)

hold. Using (10), we obtain

$$(iJw_n^*(\tau_{nk})\mathbf{m}(\{\tau_{nk}\})f(\tau_{nk}), w_n^*(\tau_{nk})\mathbf{m}(\{\tau_{nk}\})g(\tau_{nk})) = (iJ\mathbf{m}(\{\tau_{nk}\})f(\tau_{nk}), \mathbf{m}(\{\tau_{nk}\})g(\tau_{nk})), f, g \in \mathfrak{H}.$$

Therefore,

$$\sum_{n=1}^{k_1} (iJw_n^*(\tau_{nk})\mathbf{m}(\{\tau_{nk}\})f(\tau_{nk}), w_n^*(\tau_{nk})\mathbf{m}(\{\tau_{nk}\})g(\tau_{nk})) = \sum_{n=1}^{k_1} (iJ\mathbf{m}(\{\tau_{nk}\})f(\tau_{nk}), \mathbf{m}(\{\tau_{nk}\})g(\tau_{nk})) = (i\widetilde{J}\mathcal{V}_0^*f, \mathcal{V}_0^*g).$$
(35)

We denote $\mathbf{H}_{-} = \mathfrak{H}_{0} \times \mathbf{Q}_{-}$, $\mathbf{H}_{+} = \mathfrak{H}_{0} \times \mathbf{Q}_{+}$. Suppose a pair $\{\widetilde{y}, \widetilde{f}\} \in L_{0}^{*}$. By Theorem 3.5 (for $\lambda = 0$), there exists a pair $\{\widehat{y}, \widehat{f}\}$ such that the pairs $\{\widetilde{y}, \widehat{f}\}$, $\{\widehat{y}, \widehat{f}\}$ are identical in $\mathfrak{H} \times \mathfrak{H}$ and equalities

$$\widehat{y} = y_0 + y, \ \widehat{f} = y_0' + f, \ y(t) = \widetilde{V}(t)\widetilde{\eta} - \sum_{n=1}^{\mathbb{k}_1} \mathfrak{X}_{[a,b] \setminus \mathcal{S}_{\mathbf{m}}}(t)w_n(t)iJ \int_a^t w_n^*(s)d\mathbf{m}(s)f(s)$$
(36)

hold, where $y_0, y_0' \in \mathfrak{H}_0$, $\{y, f\} \in L_{10}^*$, $\widetilde{\eta} \in Q_-$, the series in (36) converges in \mathfrak{H} , \mathbb{R}_1 is the number of intervals $\mathcal{J}_n \in \mathbb{J}$. With each such pair $\{\widehat{y}, \widehat{f}\}$ we associate a pair of boundary values $\{Y, Y'\} \in \mathbf{H}_- \times \mathbf{H}_+$ by formulas

$$Y = \{y_0, Y_{10}\} \in \mathbf{H}_- = \mathfrak{H}_0 \times Q_-, \quad Y' = \{y_0', Y_{10}'\} \in \mathbf{H}_+ = \mathfrak{H}_0 \times Q_+, \tag{37}$$

where

$$Y_{10} = \widetilde{\eta} - 2^{-1} i \widetilde{J} \mathcal{V}_* f + 2^{-1} i \widetilde{J} \mathcal{V}_0^* f + i \widetilde{J} \mathcal{V}_{*\tau} f, \quad Y_{10}' = \mathcal{V}^* f.$$
(38)

Let Γ denote the operator that takes each pair $\{\widehat{y}, \widehat{f}\} \in L_0^*$ to the ordered pair $\{Y, Y'\}$ of boundary values Y, Y', i.e., $\Gamma\{\widehat{y}, \widehat{f}\} = \{Y, Y'\}$. We put $\Gamma_1\{\widehat{y}, \widehat{f}\} = Y$, $\Gamma_2\{\widehat{y}, \widehat{f}\} = Y'$. It follows from Lemma 3.4 that if pairs $\{\widehat{y}_1, \widehat{f}_1\}$, $\{\widehat{y}, \widehat{f}\}$ are identical in $\mathfrak{H} \times \mathfrak{H}$, then their boundary values coincide.

Theorem 5.1. The range $\mathcal{R}(\Gamma)$ of the operator Γ coincides with $\mathbf{H}_- \times \mathbf{H}_+$ and "the Green formula"

$$(\widehat{f},\widehat{z})_{\mathfrak{H}} - (\widehat{y},\widehat{g})_{\mathfrak{H}} = (Y',Z) - (Y,Z') \tag{39}$$

 $holds, where \ \{\widehat{y}, \widehat{f}\}, \{\widehat{z}, \widehat{g}\} \in L_0^*, \ \Gamma\{\widehat{y}, \widehat{f}\} = \{Y, Y'\}, \ \Gamma\{\widehat{z}, \widehat{g}\} = \{Z, Z'\}.$

Proof. The equality $\mathcal{R}(\Gamma) = \mathbf{H}_- \times \mathbf{H}_+$ follows from Lemma 3.4 and formulas (8), (36)-(38). Let us prove (39). Suppose that a pair $\{y, f\}$ has form (36) and a pair $\{\widehat{z}, \widehat{g}\}$ has the form $\widehat{z} = z_0 + z$, $\widehat{g} = z_0' + g$, where $\{z, g\} \in L_{10}^*$, $z_0, z_0' \in \mathfrak{H}_0$, and

$$z(t) = \widetilde{V}(t)\widetilde{\zeta} - \sum_{n=1}^{k_1} \mathfrak{X}_{[a,b] \setminus \mathcal{S}_{\mathbf{m}}}(t)w_n(t)iJ \int_{\alpha_n}^{\beta_n} w_n^*(s)d\mathbf{m}(s)g(s), \quad \widetilde{\zeta} \in Q_-.$$

$$(40)$$

Then

$$(\widehat{f},\widehat{z})_{\mathfrak{H}} - (\widehat{y},\widehat{g})_{\mathfrak{H}} = (y'_{0},z_{0})_{\mathfrak{H}} - (y_{0},z'_{0})_{\mathfrak{H}} + (f,z)_{\mathfrak{H}} - (y,g)_{\mathfrak{H}}.$$

Thus, it is enough to prove the equality

$$(f,z)_{\mathfrak{H}} - (y,g)_{\mathfrak{H}} = (Y'_{10},Z_{10}) - (Y_{10},Z'_{10}).$$

We define the functions F_n , G_n , \widetilde{F} , \widetilde{G} by the equalities

$$F_n(t) = -w_n(t)iJ \int_{\alpha_n}^t w_n^*(s) d\mathbf{m}(s) f(s), \quad G_n(t) = -w_n(t)iJ \int_{\alpha_n}^t w_n^*(s) d\mathbf{m}(s) g(s), \quad \widetilde{F}(t) = \sum_{n=1}^{k_1} F_n(t), \quad \widetilde{G}(t) = \sum_{n=1}^{k_1} G_n(t). \quad (41)$$

It follows from Lemma 2.2 that the functions F_n , G_n are solutions of equation (6) on $[\alpha_n, \beta_n)$ for $\alpha_0 = 0$ (α_n) is the solution if α_n , α_n are replaced by α_n , α_n , respectively, in (6)). Using (10) and Lemma 2.1 for α_n are α_n , α_n are α_n , α_n are replaced by α_n , α_n are solutions of equation (6) on α_n and α_n for α_n are solutions of equation (6) on α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solutions of equation (6) on α_n , α_n are solution (6) on α_n , α_n , α_n are solution (6) on α_n , α_n , α_n are solution (6) on α_n , α_n

$$\int_{\alpha_{n}}^{\beta} (f(s), d\mathbf{m}(s)G_{n}(s)) - \int_{\alpha_{n}}^{\beta} (F_{n}(s), d\mathbf{m}(s)g(s)) = \left(iJw_{n}(\beta)iJ\int_{\alpha_{n}}^{\beta} w_{n}^{*}(s)d\mathbf{m}(s)f(s), w_{n}(\beta)iJ\int_{\alpha_{n}}^{\beta} w_{n}^{*}(s)d\mathbf{m}(s)g(s)\right) - \sum_{\tau \in \mathcal{S}_{\mathbf{m}} \cap [\alpha_{n}, \beta)} (iJ\mathbf{m}(\{\tau\})f(\tau), \mathbf{m}(\{\tau\})g(\tau)) = \left(iJ\int_{\alpha_{n}}^{\beta} w_{n}^{*}(s)d\mathbf{m}(s)f(s), \int_{\alpha_{n}}^{\beta} w_{n}^{*}(s)d\mathbf{m}(s)g(s)\right) - \sum_{\tau \in \mathcal{S}_{\mathbf{m}} \cap [\alpha_{n}, \beta)} (iJ\mathbf{m}(\{\tau\})f(\tau), \mathbf{m}(\{\tau\})g(\tau)). \tag{42}$$

Passing to the limit as $\beta \rightarrow \beta_n - 0$ in (42), we obtain that (42) will remain true if β is replaced by β_n . Therefore,

$$\int_{\alpha_n}^{\beta_n} (f(s), d\mathbf{m}(s)G_n(s)) - \int_{\alpha_n}^{\beta_n} (F_n(s), d\mathbf{m}(s)g(s)) = \left(iJ \int_{\alpha_n}^{\beta_n} w_n^*(s)d\mathbf{m}(s)f(s), \int_{\alpha_n}^{\beta_n} w_n^*(s)d\mathbf{m}(s)g(s)\right) - \sum_{\tau \in \mathcal{S}_{\mathbf{m}} \cap [\alpha_n, \beta_n)} (iJ\mathbf{m}(\{\tau\})f(\tau), \mathbf{m}(\{\tau\})g(\tau)). \tag{43}$$

Taking into account (41), (43), and (35), we obtain

$$(f,G)_{\mathfrak{H}} - (F,g)_{\mathfrak{H}} = \sum_{n=1}^{k_1} \left(iJ \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) f(s), \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) g(s) \right) - (i\widetilde{J} \mathcal{V}_0^* f, \mathcal{V}_0^* g). \tag{44}$$

Further, we define the functions F_{n0} , G_{n0} , \widetilde{F}_0 , \widetilde{G}_0 by the equalities

$$F_{n0}(t) = \mathfrak{X}_{[\alpha_n, \beta_n) \setminus \mathcal{S}_{\mathbf{m}}} F_n(t), \quad G_{n0}(t) = \mathfrak{X}_{[\alpha_n, \beta_n) \setminus \mathcal{S}_{\mathbf{m}}} G_n(t), \quad \widetilde{F}_0 = \sum_{n=1}^{k_1} F_{n0}, \quad \widetilde{G}_0 = \sum_{n=1}^{k_1} G_{n0}. \tag{45}$$

Using (43), we get

$$(f, G_{n0})_{\S} - (F_{n0}, g)_{\S} = (f, G_n)_{\S} - (F_n, g)_{\S} +$$

$$+ (f, \mathfrak{X}_{S_{\mathbf{m}}} w_n(t)iJ \int_{\alpha_n}^t w_n^*(s) d\mathbf{m}(s) g(s))_{\S} - (\mathfrak{X}_{S_{\mathbf{m}}} w_n(t)iJ \int_{\alpha_n}^t w_n^*(s) d\mathbf{m}(s) f(s), g(s))_{\S} =$$

$$= \left(iJ \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) f(s), \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) g(s)\right) - \sum_{\tau \in S_{\mathbf{m}} \cap [\alpha_n, \beta_n)} (iJ\mathbf{m}(\{\tau\}) f(\tau), \mathbf{m}(\{\tau\}) g(\tau)) -$$

$$- \sum_{\tau \in S_{\mathbf{m}} \cap [\alpha_n, \beta_n)} (iJw_n^*(\tau) f(\tau), \int_{\alpha_n}^\tau w_n^*(s) d\mathbf{m}(s) g(s)) - \sum_{\tau \in S_{\mathbf{m}} \cap [\alpha_n, \beta_n)} (iJ \int_{\alpha_n}^\tau w_n^*(s) d\mathbf{m}(s) f(s), w_n^*(\tau) g(\tau)). \tag{46}$$

By (35), (45), (46), we obtain

$$(f,G_0)_{\mathfrak{H}} - (F_0,g)_{\mathfrak{H}} = \sum_{n=1}^{\mathbb{K}_1} \left(iJ \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) f(s), \int_{\alpha_n}^{\beta_n} w_n^*(s) d\mathbf{m}(s) g(s) \right) - \left(i\widetilde{J} \mathcal{V}_0^* f, \mathcal{V}_0^* g \right) - \left(i\widetilde{J} \mathcal{V}_0^* f, \mathcal{V}_{*\tau} g \right) - \left(i\widetilde{J} \mathcal{V}_{*\tau} f, \mathcal{V}_0^* g \right). \tag{47}$$

It follows from (38), (40) that the equalities

$$(f, \mathcal{V}\widetilde{\zeta})_{5} = (\mathcal{V}^{*}f, \widetilde{\zeta}) = (\mathcal{V}^{*}f, Z_{10} + 2^{-1}i\widetilde{j}\mathcal{V}_{*}q - 2^{-1}i\widetilde{j}\mathcal{V}_{*7}q - i\widetilde{j}\mathcal{V}_{*7}q), \tag{48}$$

$$(\widetilde{\mathcal{V}\eta}, q)_{5} = (\widetilde{\eta}, \mathcal{V}^*q) = (Y_{10} + 2^{-1}i\widetilde{j}\mathcal{V}_*f - 2^{-1}i\widetilde{j}\mathcal{V}_{*f}^*f - i\widetilde{j}\mathcal{V}_{*\tau}f, \mathcal{V}^*q)$$

$$(49)$$

hold. Using (33), (34), (47), (48), (49), we get

$$\begin{split} &(f,z)_{\mathfrak{H}} - (y,g)_{\mathfrak{H}} = (f,\mathcal{V}\zeta + G_{0})_{\mathfrak{H}} - (\mathcal{V}\eta + F_{0},g)_{\mathfrak{H}} = (\mathcal{V}^{*}f,\zeta) - (\eta,\mathcal{V}^{*}g) + (f,G_{0})_{\mathfrak{H}} - (F_{0},g)_{\mathfrak{H}} = \\ &= (\mathcal{V}^{*}f,Z_{10} + 2^{-1}i\widetilde{J}\mathcal{V}_{*}g - 2^{-1}i\widetilde{J}\mathcal{V}_{*}^{*}g - i\widetilde{J}\mathcal{V}_{*\tau}g) - (Y_{10} + 2^{-1}i\widetilde{J}\mathcal{V}_{*}f - 2^{-1}i\widetilde{J}\mathcal{V}_{*}^{*}f - i\widetilde{J}\mathcal{V}_{*\tau}g,\mathcal{V}^{*}g) + (f,G_{0})_{\mathfrak{H}} - (F_{0},g)_{\mathfrak{H}} = \\ &= (Y_{10}',Z_{10}) - 2^{-1}(i\widetilde{J}\mathcal{V}^{*}f,\mathcal{V}_{*}g) + 2^{-1}(i\widetilde{J}\mathcal{V}^{*}f,\mathcal{V}_{0}^{*}g) + (i\widetilde{J}\mathcal{V}^{*}f,\mathcal{V}_{*\tau}g) - \\ &- (Y_{10},Z_{10}') - 2^{-1}(i\widetilde{J}\mathcal{V}_{*}f,\mathcal{V}^{*}g) + 2^{-1}(i\widetilde{J}\mathcal{V}_{0}^{*}f,\mathcal{V}^{*}g) + (i\widetilde{J}\mathcal{V}_{*\tau}f,\mathcal{V}^{*}g) + \\ &+ (i\widetilde{J}\mathcal{V}_{*},\mathcal{V}^{*}g) - (i\widetilde{J}\mathcal{V}_{0}^{*}f,\mathcal{V}_{0}^{*}g) - (i\widetilde{J}\mathcal{V}_{*\tau}f,\mathcal{V}_{0}^{*}g) - (i\widetilde{J}\mathcal{V}_{*\tau}f,\mathcal{V}_{0}^{*}g) = (Y_{10}',Z_{10}) - (Y_{10},Z_{10}'). \end{split}$$

The theorem is proved. \Box

By Lemma 3.2 (for $\lambda = 0$), it follows that functions $\mathfrak{X}_{\{\tau\}}(\cdot)x$ ($x \in H$, $\tau \in \mathcal{S}_{\mathbf{m}}$) belong to ker L_{10}^* . Consequently equality (36) is reduced to the form

$$\widehat{y} = y_0 + y, \quad \widehat{f} = y_0' + f, \quad y(t) = \widetilde{V}(t)\widetilde{\xi} - \sum_{n=1}^{k_1} w_n(t)iJ \int_a^t w_n^*(s)d\mathbf{m}(s)f(s), \tag{50}$$

where $\widetilde{\xi} = \{\xi_k\} \in Q_-$, $\xi_k = \eta_k$ (see (36)) if v_k has form (12) and

$$\xi_k = \eta_k + iJ \int_{\alpha_n}^{\tau_k} w_n^*(s) d\mathbf{m}(s) f(s)$$
(51)

if v_k has form (13) for $\lambda = 0$.

Corollary 5.2. *If the pair* $\{y, f\}$ *has form* (50)*, then*

$$Y_{10} = \widetilde{\xi} - 2^{-1}i\widetilde{j}\mathcal{V}_* f + 2^{-1}i\widetilde{j}\mathcal{V}_0^* f, \quad Y_{10}' = \mathcal{V}^* f.$$
 (52)

Proof. Equality (52) follows from (38) and (51). \Box

We note that the case where functions y, f have form (50) was considered in [16]. Equality (44) is proved in [16]; however, in [16], there is a mistake in formula (52): V^* is written in the first equality instead of V_* .

From the theory of spaces with positive and negative norms (see [4, ch. 1], [19, ch. 2]), it follows that there exist isometric operators $\delta_-: Q_- \to Q$, $\delta_+: Q_+ \to Q$ such that the equality $(\widetilde{\eta}, \widetilde{\varphi}) = (\delta_- \widetilde{\eta}, \delta_+ \widetilde{\varphi})$ holds for all $\widetilde{\eta} \in Q_-$, $\widetilde{\varphi} \in Q_+$. We denote $\mathcal{H} = \mathfrak{H}_0 \times Q$. Suppose $\{\widetilde{y}, \widetilde{f}\} \in L_0^*$. According to Theorem 3.5 (for $\lambda = 0$), there exists a pair $\{\widehat{y}, \widehat{f}\}$ such that the pairs $\{\widetilde{y}, \widehat{f}\}$, $\{\widehat{y}, \widehat{f}\}$ are identical in $\mathfrak{H} \times \mathfrak{H}$ and equalities (36) hold. To each such pair $\{\widehat{y}, \widehat{f}\}$ assign a pair of boundary values $\gamma\{\widehat{y}, \widehat{f}\} = \{\mathcal{Y}, \mathcal{Y}'\} \in \mathcal{H} \times \mathcal{H}$ by the formulas

$$\boldsymbol{\mathcal{Y}} = \gamma_1\{\widehat{\boldsymbol{y}}, \widehat{\boldsymbol{f}}\} = \{y_0, \delta_- Y_{10}\}, \quad \boldsymbol{\mathcal{Y}}' = \gamma_2\{\widehat{\boldsymbol{y}}, \widehat{\boldsymbol{f}}\} = \{y_0', \delta_+ Y_{10}'\}.$$

By Theorem 5.1, it follows that the operator γ maps L_0^* onto $\mathcal{H} \times \mathcal{H}$ and equality

$$(\widehat{f},\widehat{z})_{5} - (\widehat{y},\widehat{q})_{5} = (\mathcal{Y}',\mathcal{Z}) - (\mathcal{Y},\mathcal{Z}') \tag{53}$$

holds, where $\{\widehat{y}, \widehat{f}\}$, $\{\widehat{z}, \widehat{g}\} \in L_0^*$, $\gamma\{\widehat{y}, \widehat{f}\} = \{\mathcal{Y}, \mathcal{Y}'\}$, $\gamma\{\widehat{z}, \widehat{g}\} = \{\mathcal{Z}, \mathcal{Z}'\}$. This implies that the ordered triple $(\mathcal{H}, \gamma_1, \gamma_2)$ is the space of boundary values (a boundary triplet in another terminology) for L_0 in the sense of papers [22], [7], [8] (see also [19, ch. 3]). It was established in the articles [22], [7], [8] that for the space of boundary values, formula (53) implies the following statement.

Corollary 5.3. If U is a unitary operator on \mathcal{H} , then the restriction of the relation L_0^* to the set of pairs $\{\widehat{y}, \widehat{f}\} \in L_0^*$ satisfying the condition

$$(U-E)\mathcal{Y}' - (U+E)\mathcal{Y} = 0 \tag{54}$$

is a self-adjoint extension of L_0 . Conversely, any self-adjoint extension of L_0 is the restriction of L_0^* to the set of pairs $\{\widehat{y}, \widehat{f}\} \in L_0^*$ satisfying (54), where a unitary operator U is uniquely determined by an extension.

This statement is proved in [16] for the boundary values (52). It is established in [15] provided that **m** is the usual Lebesque measure on [a, b] (i.e., $\mathbf{m}([\alpha, \beta)) = \beta - \alpha$, where $a \le \alpha < \beta \le b$). We note that F.S. Rofe-Beketov [24] first applied linear relations to describe self-adjoint extensions of differential operators.

We consider boundary value problem

$$\widehat{f} = \lambda \widehat{y} + h, \quad (K(\lambda) - E)\mathcal{Y}' - i(K(\lambda) + E)\mathcal{Y} = 0, \tag{55}$$

where $\{\mathcal{Y}, \mathcal{Y}'\} = \gamma\{\widehat{y}, \widehat{f}\}; h \in \mathfrak{H}; \lambda \to K(\lambda)$ is a holomorphic operator function in \mathcal{H} such that $||K(\lambda)|| \leq 1$; $\mathrm{Im}\lambda > 0$.

From (53) and [7], [8] we obtain the following statement.

Theorem 5.4. There exists a one-to-one mapping between boundary problems (55) and generalized resolvents of the operator L_0 . Every solution y of problem (55) determines a generalized resolvent \widetilde{R}_{λ} by the formula $y = \widetilde{R}_{\lambda}h$ and, conversely, for any generalized resolvent \widetilde{R}_{λ} there exists a function $K(\lambda)$ such that the function $y = \widetilde{R}_{\lambda}h$ is the solution of (55).

6. The example

We consider equation (1) on a segment [0,b] and assume that $H = \mathbb{C}$, J = E = 1, $\mathbf{p} = 0$, $\mathbf{m} = \mathbf{m}_0 + \widehat{\mathbf{m}}$, where \mathbf{m}_0 is the usual Lebesque measure (we write ds instead of $d\mathbf{m}_0(s)$), $0 < \tau < b$, $\widehat{\mathbf{m}}(\{\tau\}) = 1$ and $\widehat{\mathbf{m}}(\Delta) = 0$ for all Borel sets such that $\tau \notin \Delta$. So, $S_{\mathbf{m}} = \{\tau\}$. Thus, equation (1) has the form

$$y(t) = x_0 - i \int_0^t d\mathbf{m}(s) f(s). \tag{56}$$

It follows from the definition of L_0 and (7), (56) that L_0 is an operator and if $y = L_0 f$, then

$$y(t) = -i \int_0^t f(s)ds$$
, $y(b) = 0$, $f(\tau) = 0 \Leftrightarrow y'(t) = -if(t)$, $y(0) = y(b) = 0$, $f(\tau) = 0$.

Since $S_0 = \{0, b\}$ and $\mathbf{m}(S_0) = 0$, we have $\mathfrak{H}_0 = \{0\}$ and $L_{10}^* = L_0^*$ in equality (8). Equation (5) (for $x_0 = 1$) takes the form

$$W(t,\lambda) = 1 - i\lambda \int_0^t W(s,\lambda)ds, \quad \lambda \in \mathbb{C}.$$

Therefore, $W(t,\lambda) = e^{-i\lambda t}$. Obviously, if $\lambda = 0$, then W(t,0) = 1. The number of intervals $\mathcal{J}_k \in \mathbb{J}$ is $\mathbb{k}_1 = 1$. We write $w(t,\lambda)$ instead of $w_1(t,\lambda)$. Then $w(t,\lambda) = \mathfrak{X}_{[0,b)}W(t,\lambda)$. Without loss of generality it can be assumed that $w(t,\lambda) = W(t,\lambda) = e^{-i\lambda t}$.

The set \mathbb{M} consists of the interval (0, b) and the single-point set $\{\tau\}$. Hence the number of elements of \mathbb{M} is $\mathbb{k} = 2$. Using (12), (13), and the equality $\mathbf{m}(\{\tau\}) = 1$, we get

$$v_1(t,\lambda) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}w(t,\lambda) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t} = \begin{cases} e^{-i\lambda t} & \text{for } t \neq \tau, \\ 0 & \text{for } t = \tau \end{cases} ;$$

$$(57)$$

$$v_{2}(t,\lambda) = u_{1}(t,\lambda,\tau)e^{-i\lambda\tau} + \mathfrak{X}_{\{\tau\}}(t)e^{-i\lambda\tau} = -\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{t}e^{i\lambda s}d\mathbf{m}(s)\lambda\mathfrak{X}_{\{\tau\}}(s)e^{-i\lambda\tau} + \mathfrak{X}_{\{\tau\}}(t)e^{-i\lambda\tau} = \begin{cases} 0 & \text{for } t < \tau, \\ e^{-i\lambda\tau} & \text{for } t = \tau, \\ -\lambda ie^{-i\lambda t} & \text{for } t > \tau. \end{cases}$$
(58)

Therefore,

$$v_1^*(t,\overline{\lambda}) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{i\lambda t} = \begin{cases} e^{i\lambda t} & \text{for } t \neq \tau, \\ 0 & \text{for } t = \tau \end{cases}; \quad v_2^*(t,\overline{\lambda}) = \begin{cases} 0 & \text{for } t < \tau, \\ e^{i\lambda \tau} & \text{for } t = \tau, \\ \lambda i e^{i\lambda t} & \text{for } t > \tau. \end{cases}$$
(59)

If $\lambda = 0$, then equalities (58), (59) imply that

$$v_1(t) = v_1(t,0) = \mathfrak{X}_{[0,b] \setminus \{\tau\}}(t) = \begin{cases} 1 & \text{for } t \neq \tau, \\ 0 & \text{for } t = \tau \end{cases}; \quad v_2(t) = v_2(t,0) = \mathfrak{X}_{\{\tau\}}(t) = \begin{cases} 0 & \text{for } t \neq \tau, \\ 1 & \text{for } t = \tau. \end{cases}$$
(60)

By (14), (60), it follows that $Q_{10} = Q_{20} = \{0\}$ and $Q_1 = Q_1^- = Q_1^+ = Q_2 = Q_2^- = Q_2^+ = H = \mathbb{C}$. Therefore, $Q = Q_- = Q_+ = \mathbb{C}^2$.

The domain $\mathcal{D}(L_0)$ of L_0 is dense in $\mathfrak{H} = L_2(\mathbb{C}, d\mathbf{m}; 0, b)$. This yields that L_0^* is an operator. Using Theorem 3.5, we obtain

$$y(t) = v_1(t,\lambda)\eta_1 + v_2(t,\lambda)\eta_2 - \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)e^{-i\lambda t}i\int_0^t e^{i\lambda s}d\mathbf{m}(s)f(s)$$

$$\tag{61}$$

for all $y \in \mathcal{D}(L_0^* - \lambda E)$, where $\eta_1, \eta_2 \in \mathbb{C}$, $f = (L_0^* - \lambda E)y$. For $\lambda = 0$, it follows from (61) that

$$y(t) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)\eta_1 + \mathfrak{X}_{\{\tau\}}(t)\eta_2 - \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)i\int_0^t d\mathbf{m}(s)u(s), \tag{62}$$

where $u = L_0^* y$. Since $\mathfrak{X}_{\{\tau\}} \xi \in \ker L_0^*$ for all $\xi \in \mathbb{C}$, we obtain

$$y(t) = \xi_1 + \mathfrak{X}_{\{\tau\}}(t)\xi_2 - i\int_0^t d\mathbf{m}(s)u(s), \quad \xi_1, \xi_2 \in \mathbb{C}.$$

Taking into account (37), (38), (62), and the equality $\mathbf{m}(\{\tau\}) = 1$, we see that the boundary values $Y = \mathcal{Y}$, $Y' = \mathcal{Y}'$ are calculated by the formulas

$$Y = \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} - 2^{-1}i \begin{pmatrix} \int_0^b d\mathbf{m}(s)u(s) \\ \int_0^b d\mathbf{m}(s)u(s) \end{pmatrix} + 2^{-1}i \begin{pmatrix} 0 \\ u(\tau) \end{pmatrix} + i \begin{pmatrix} 0 \\ \int_0^\tau d\mathbf{m}(s)u(s) \end{pmatrix}, \quad Y' = \begin{pmatrix} \int_0^b u(s)ds \\ u(\tau) \end{pmatrix}, \tag{63}$$

where y has form (62), $u = L_0^* y$.

Let \mathcal{L} be an operator such that $L_0 \subset \mathcal{L} \subset L_0^*$. Suppose that \mathcal{L} is the restriction of L_0^* to a set of functions satisfying the condition Y = 0. It follows from Corollary 5.3 that \mathcal{L} is the self-adjoint operator. Let us find the function

$$M(\lambda) = \begin{pmatrix} M_{11}(\lambda) & M_{12}(\lambda) \\ M_{21}(\lambda) & M_{22}(\lambda) \end{pmatrix} : \mathbb{C}^2 \to \mathbb{C}^2$$

$$(64)$$

that corresponds to the resolvent $R_{\lambda} = (\mathcal{L} - \lambda E)^{-1}$. We denote

$$x_1 = x_1(f,\lambda) = \int_0^b v_1^*(s,\overline{\lambda}) d\mathbf{m}(s) f(s) = \int_0^b e^{i\lambda s} f(s) ds,$$
(65)

$$x_2 = x_2(f,\lambda) = \int_0^b v_2^*(s,\overline{\lambda}) d\mathbf{m}(s) f(s) = e^{i\lambda\tau} f(\tau) + \int_\tau^b i\lambda e^{i\lambda s} f(s) ds.$$
 (66)

Then equality (20) takes the form

$$y(t) = v_1(t,\lambda)(M_{11}(\lambda)x_1 + M_{12}(\lambda)x_2) + v_2(t,\lambda)(M_{21}(\lambda)x_1 + M_{22}(\lambda)x_2) - 2^{-1}\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_0^t e^{i\lambda s}f(s)ds + 2^{-1}\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_t^b e^{i\lambda s}f(s)ds - \lambda^{-1}\mathfrak{X}_{\{\tau\}}(t)f(\tau). \tag{67}$$

By elementary transformations, equality (67) is converted to the following form

$$y(t) = v_{1}(t,\lambda)(M_{11}(\lambda)x_{1} + M_{12}(\lambda)x_{2}) + v_{2}(t,\lambda)(M_{21}(\lambda)x_{1} + M_{22}(\lambda)x_{2}) -$$

$$- \mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{t}e^{i\lambda s}f(s)ds + 2^{-1}\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{b}e^{i\lambda s}f(s)ds - \lambda^{-1}\mathfrak{X}_{\{\tau\}}(t)f(\tau).$$
 (68)

Using (57), (58), we obtain that in equality (68)

$$v_1(t,\lambda)(M_{11}(\lambda)x_1 + M_{12}(\lambda)x_2) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}(M_{11}(\lambda)x_1 + M_{12}(\lambda)x_2),$$

$$v_2(t,\lambda)(M_{21}(\lambda)x_1 + M_{22}(\lambda)x_2) = \begin{cases} 0 & \text{for } t < \tau, \\ e^{-i\lambda\tau}(M_{21}(\lambda)x_1 + M_{22}(\lambda)x_2) & \text{for } t = \tau, \\ -\lambda i e^{-i\lambda t}(M_{21}(\lambda)x_1 + M_{22}(\lambda)x_2) & \text{for } t > \tau. \end{cases}$$

To find $M_{12}(\lambda)$, $M_{22}(\lambda)$, we take the function $f_1(t) = \mathfrak{X}_{\{\tau\}}(t)$, i.e., $f_1(t) = 1$ if $t = \tau$ and $f_1(t) = 0$ if $t \neq \tau$ (by $\{Y_1, Y_1'\}$ denote the corresponding pair of boundary values). It follows from (59), (65), (66) that $x_1 = 0$, $x_2 = e^{i\lambda\tau}$. We denote $y_1 = R_{\lambda}f_1$. Using (68), we obtain

$$y_1(t) = v_1(t, \lambda) M_{12}(\lambda) e^{i\lambda \tau} + v_2(t, \lambda) M_{22}(\lambda) e^{i\lambda \tau} - \lambda^{-1} \mathfrak{X}_{\{\tau\}}(t).$$
(69)

We denote $u_1 = L_0^* y_1 = \lambda y_1 + f_1$. Then using (69), we get

$$u_1(t) = \lambda v_1(t, \lambda) M_{12}(\lambda) e^{i\lambda \tau} + \lambda v_2(t, \lambda) M_{22}(\lambda) e^{i\lambda \tau}. \tag{70}$$

By (60), (62), (69), it follows that

$$y_1(t) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)M_{12}(\lambda)e^{i\lambda\tau} + \mathfrak{X}_{\{\tau\}}(t)(M_{22}(\lambda) - \lambda^{-1}) - \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)i\int_0^t d\mathbf{m}(s)u_1(s). \tag{71}$$

Using (70) by direct calculations, we obtain

$$\int_{0}^{b} d\mathbf{m}(s) u_{1}(s) = i(e^{-i\lambda b} - 1) M_{12}(\lambda) e^{i\lambda \tau} + \lambda e^{-i\lambda b} M_{22}(\lambda) e^{i\lambda \tau}; \quad \int_{0}^{\tau} d\mathbf{m}(s) u_{1}(s) = i(1 - e^{i\lambda \tau}) M_{12}(\lambda). \tag{72}$$

By (63), (71), (72), so that

$$Y_{1} = \begin{pmatrix} M_{12}(\lambda)e^{i\lambda\tau} \\ M_{22}(\lambda) - \lambda^{-1} \end{pmatrix} - 2^{-1}i \begin{pmatrix} i(e^{-i\lambda b} - 1)M_{12}(\lambda)e^{i\lambda\tau} + \lambda e^{-i\lambda b}M_{22}(\lambda)e^{i\lambda\tau} \\ i(e^{-i\lambda b} - 1)M_{12}(\lambda)e^{i\lambda\tau} + \lambda e^{-i\lambda b}M_{22}(\lambda)e^{i\lambda\tau} \end{pmatrix} + 2^{-1}i \begin{pmatrix} 0 \\ \lambda M_{22}(\lambda) \end{pmatrix} + i \begin{pmatrix} 0 \\ i(1 - e^{i\lambda\tau})M_{12}(\lambda) \end{pmatrix}.$$

The equality $Y_1 = 0$ is equivalent to two equalities

$$\begin{cases} M_{12}(\lambda)e^{i\lambda\tau} + 2^{-1}(e^{-i\lambda b} - 1)M_{12}(\lambda)e^{i\lambda\tau} - 2^{-1}\lambda ie^{-i\lambda b}M_{22}(\lambda)e^{i\lambda\tau} = 0, \\ M_{22}(\lambda) - \lambda^{-1} + 2^{-1}(e^{-i\lambda b} - 1)M_{12}(\lambda)e^{i\lambda\tau} - 2^{-1}\lambda ie^{-i\lambda b}M_{22}(\lambda)e^{i\lambda\tau} + 2^{-1}\lambda iM_{22}(\lambda) - (1 - e^{i\lambda\tau})M_{12}(\lambda) = 0. \end{cases}$$
(73)

Solving the system of equations (73), we get

$$M_{12}(\lambda) = \frac{2ie^{-i\lambda b}}{2(e^{-i\lambda b} + 1) - i\lambda(e^{-i\lambda b} - 1)}; \quad M_{22}(\lambda) = \frac{2(e^{-i\lambda b} + 1)}{\lambda(2(e^{-i\lambda b} + 1) - i\lambda(e^{-i\lambda b} - 1))}. \tag{74}$$

To find $M_{11}(\lambda)$, $M_{21}(\lambda)$, we take the function $f_2(t) = \mathfrak{X}_{[0,\tau)}(t)$, i.e., $f_2(t) = 1$ if $t < \tau$ and $f_2(t) = 0$ if $t \ge \tau$ (by $\{Y_2, Y_2'\}$ denote the corresponding pair of boundary values). It follows from (65) that $x_1 = i\lambda^{-1}(1 - e^{i\lambda\tau})$, $x_2 = 0$. We denote $y_2 = R_\lambda f_2$. Using (68), we obtain

$$y_{2}(t) = v_{1}(t,\lambda)M_{11}(\lambda)x_{1} + v_{2}(t,\lambda)M_{21}(\lambda)x_{1} - \mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{t}e^{i\lambda s}f_{2}(s)ds + 2^{-1}\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{b}e^{i\lambda s}f_{2}(s)ds. \tag{75}$$

The equality $f_2(t) = \mathfrak{X}_{[0,\tau)}(t)$ implies

$$-\mathfrak{X}_{[0,b]\setminus\{\tau\}}e^{-i\lambda t}i\int_{0}^{t}e^{i\lambda s}f_{2}(s)ds = \begin{cases} \lambda^{-1}(e^{-i\lambda t}-1) & \text{for } t<\tau, \\ 0 & \text{for } t=\tau, \\ \lambda^{-1}e^{-i\lambda t}(1-e^{i\lambda\tau}) & \text{for } t>\tau; \end{cases}$$

$$(76)$$

$$2^{-1} \mathfrak{X}_{[0,b] \setminus \{\tau\}} e^{-i\lambda t} i \int_0^b e^{i\lambda s} f_2(s) ds = \begin{cases} 2^{-1} i e^{-i\lambda t} x_1 & \text{for } t \neq \tau, \\ 0 & \text{for } t = \tau. \end{cases}$$
 (77)

By (62), (75)-(77), it follows that

$$y_2(t) = \mathfrak{X}_{[0,b]\setminus\{\tau\}}(M_{11}(\lambda)x_1 + 2^{-1}ix_1) + \mathfrak{X}_{\{\tau\}}(t)e^{-i\lambda\tau}M_{21}(\lambda)x_1 - \mathfrak{X}_{[0,b]\setminus\{\tau\}}(t)i\int_0^t d\mathbf{m}(s)u_2(s), \tag{78}$$

where $u_2 = L_0^* y_2 = \lambda y_2 + f_2$. Equalities (57), (58), (75)-(77) imply that $u_2(t) = u_{21}(t) + u_{22}(t) + u_{23}(t) + u_{24}(t)$, where

$$u_{21}(t) = \mathfrak{X}_{[0,b] \setminus \{\tau\}} \lambda e^{-i\lambda t} M_{11}(\lambda) x_1; \quad u_{22}(t) = \begin{cases} 0 & \text{for } t < \tau, \\ \lambda e^{-i\lambda \tau} M_{21}(\lambda) x_1 & \text{for } t = \tau, \\ -\lambda^2 i e^{-i\lambda t} M_{21}(\lambda) x_1 & \text{for } t > \tau; \end{cases}$$
(79)

$$u_{23}(t) = \begin{cases} e^{-i\lambda t} & \text{for } t < \tau, \\ 0 & \text{for } t = \tau, \\ e^{-i\lambda t} (1 - e^{i\lambda \tau}) & \text{for } t > \tau; \end{cases} \qquad u_{24}(t) = \begin{cases} 2^{-1} \lambda i e^{-i\lambda t} x_1 & \text{for } t \neq \tau, \\ 0 & \text{for } t = \tau. \end{cases}$$
(80)

Using (79), (80), and equality $x_1 = i\lambda^{-1}(1 - e^{i\lambda\tau})$, by direct calculations, we obtain

$$\int_{0}^{b} d\mathbf{m}(s) u_{2}(s) = i(e^{-i\lambda b} - 1) M_{11}(\lambda) x_{1} + \lambda e^{-i\lambda b} M_{21}(\lambda) x_{1} + i\lambda^{-1} (e^{-i\lambda \tau} - 1) + (e^{-i\lambda b} - e^{-i\lambda \tau}) x_{1} - 2^{-1} (e^{-i\lambda b} - 1) x_{1}, \quad (81)$$

$$\int_0^{\tau} d\mathbf{m}(s) u_2(s) = i(e^{-i\lambda\tau} - 1) M_{11} x_1 + i\lambda^{-1} (e^{-i\lambda\tau} - 1) - 2^{-1} (e^{-i\lambda\tau} - 1) x_1.$$
(82)

By (63), (78), so that

$$Y_{2} = \begin{pmatrix} M_{11}(\lambda)x_{1} + 2^{-1}ix_{1} \\ e^{-i\lambda\tau}M_{21}(\lambda)x_{1} \end{pmatrix} - 2^{-1}i\begin{pmatrix} \int_{0}^{b}d\mathbf{m}(s)u_{2}(s) \\ \int_{0}^{b}d\mathbf{m}(s)u_{2}(s) \end{pmatrix} + 2^{-1}i\begin{pmatrix} 0 \\ \lambda e^{-i\lambda\tau}M_{21}(\lambda)x_{1} \end{pmatrix} + i\begin{pmatrix} 0 \\ \int_{0}^{\tau}d\mathbf{m}(s)u_{2}(s) \end{pmatrix},$$

where the integrals $\int_0^b d\mathbf{m}(s)u_2(s)$, $\int_0^\tau d\mathbf{m}(s)u_2(s)$ are calculated by formulas (81), (82), respectively. The equality $Y_2=0$ is equivalent to two equalities

$$\begin{cases} M_{11}(\lambda)x_1 + 2^{-1}ix_1 - 2^{-1}i\int_0^b d\mathbf{m}(s)u_2(s) = 0, \\ e^{-i\lambda\tau}M_{21}(\lambda)x_1 - 2^{-1}i\int_0^b d\mathbf{m}(s)u_2(s) + 2^{-1}\lambda i e^{-i\lambda\tau}M_{21}(\lambda)x_1 + i\int_0^\tau d\mathbf{m}(s)u_2(s) = 0. \end{cases}$$
(83)

Solving the system of equations (83), we obtain

$$M_{11}(\lambda) = i \frac{(2 - i\lambda)e^{-i\lambda b} - (2 + i\lambda)}{2((2 - i\lambda)e^{-i\lambda b} + (2 + i\lambda))}; \quad M_{21}(\lambda) = i \frac{-2}{(2 - i\lambda)e^{-i\lambda b} + (2 + i\lambda)}.$$
(84)

Thus the matrix $M(\lambda)$ (64) is calculated by equalities (84), (74).

Remark 6.1. It follows from (84), (74) that

$$M_{11}(i) = \frac{3e^b - 1}{2(3e^b + 1)}i; \quad M_{21}(i) = \frac{-2}{3e^b + 1}i; \quad M_{12}(i) = \frac{2e^b}{3e^b + 1}i; \quad M_{22}(i) = \frac{-2(e^b + 1)}{3e^b + 1}i.$$

Suppose that $f_1(t) = \mathfrak{X}_{\{\tau\}}(t)$. Then $x_1 = x_1(f_1, i) = 0$, $x_2 = x_2(f_1, i) = e^{-\tau}$ (see (59), (65), (66)). We denote $\widetilde{x} = \operatorname{col}(x_1, x_2)$. Therefore, $(M(i)\widetilde{x}, \widetilde{x}) = M_{22}(i)e^{-2\tau}$. Thus, $\operatorname{Im}(M(i)\widetilde{x}, \widetilde{x}) = \operatorname{Im}M_{22}(i)e^{-2\tau} = -2(e^b + 1)e^{-2\tau}/(3e^b + 1) < 0$.

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