



Total controllability for noninstantaneous impulsive conformable fractional evolution system with nonlinear noise and nonlocal conditions

Hamdy M. Ahmed^a

^a Department of Physics and Engineering Mathematics, Higher Institute of Engineering, El-Shorouk Academy, El-Shorouk City, Cairo, Egypt

Abstract. Noninstantaneous impulsive conformable fractional stochastic differential equation with nonlinear noise and nonlocal condition via Rosenblatt process and Poisson jump is studied in this paper. Sufficient conditions for controllability for the considered problem are established. The required results are obtained based on fractional calculus, stochastic analysis, semigroups and Sadovskii's fixed point theorem. In the end paper, an example is provided to illustrate the applicability of the results.

1. Introduction

Stochastic differential equations are the right tool to model the systems with the random effects and external noises (see [1-10]). Stochastic differential equations with impulse arise from many mathematical model of physical phenomenon in the field of technology, biology, physics and economics [11-13]. Recently, a novel definition named conformable fractional derivative is introduced in [14]. This new fractional derivative quickly becomes the subject of many contributions in several areas of science. In short time, many studies and discussion related to conformable fractional derivative have appeared in several areas of applications, for example, Won Sang [15] discussed the fractional Newton mechanics with conformable fractional derivative. Rosales-García et al [16] applied conformable derivative to experimental Newton's law of cooling. Abdellatif et al [17] studied the stability of conformable stochastic systems depending on a parameter. Abdellatif and Mchiri [18] discussed the partial stability of conformable stochastic systems. Ahmed [19] studied the conformable fractional stochastic differential equations with control function. On the other hand, controllability problem is searching for a suitable control function that steers the proposed dynamical model to a desired final state [20-25]. Many authors studied controllability of noninstantaneous impulsive stochastic differential equations, for example, Yan and Yang [26] studied the optimal controllability of non-instantaneous impulsive partial stochastic differential systems with fractional sectorial operators. Balasubramaniam [27] discussed the controllability of semilinear noninstantaneous impulsive ABC neutral fractional differential equations. Malik et al [28] obtained the controllability of Sobolev type fuzzy differential equation with non-instantaneous impulsive condition. Xin et al [29] investigated the controllability of nonlinear ordinary differential equations with non-instantaneous impulses. But, the

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Email address: hamdy_17eg@yahoo.com (Hamdy M. Ahmed)

controllability of noninstantaneous impulsive conformable fractional stochastic differential equation with Rosenblatt process and Poisson jump via nonlocal condition have not yet been considered in the literature, and this fact motivates this work.

The purpose of this paper is to study the controllability of noninstantaneous impulsive conformable fractional stochastic differential equation with Rosenblatt process, Poisson jump and nonlocal condition in the following form

$$\begin{cases} D_{0+}^{\hbar} y(\varrho) = -Ty(\varrho) + \mathfrak{K}(\varrho, y(\varrho)) + Qu(\varrho) + \mathfrak{J}(\varrho, y(\varrho)) \frac{d\omega}{d\varrho} + \sigma(\varrho, y(\varrho)) \frac{dZ_H}{d\varrho} \\ + \int_V h(\varrho, y(\varrho), v) \tilde{N}(d\varrho, dv), \quad \varrho \in (s_i, \varrho_{i+1}], \quad i \in [0, m] \\ y(\varrho) = g_i(\varrho, y(\varrho)), \quad \varrho \in (\varrho_i, s_i], \quad i \in [1, m] \\ y(0) + \psi(y) = y_0, \end{cases} \tag{1}$$

where D_{0+}^{\hbar} is the conformable fractional derivative with order $\frac{1}{2} < \hbar < 1$, $-T$ is the infinitesimal generator of an analytic semigroup of bounded linear operators $\Delta(\varrho)$, $\varrho \geq 0$, on a separable Hilbert space Φ with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$ and the control function $u(\cdot)$ is given in $L_2(J, U)$, the Hilbert space of admissible control functions with U a Hilbert space. The symbol Q stands for a bounded linear from U into Φ and g_i is noninstantaneous impulsive function for all $i = 1, 2, \dots, m$. Let $J = (0, G]$ is the time interval where, ϱ_i, s_i are fixed number satisfying $0 = s_0 < \varrho_1 \leq s_1 \leq \varrho_2 < \dots < s_{m-1} < \varrho_m \leq s_m \leq \varrho_{m+1} = G$. Let Ξ be another separable Hilbert space with inner product $\langle \cdot, \cdot \rangle_{\Xi}$ and norm $\| \cdot \|_{\Xi}$. Suppose $\{\omega(\varrho)\}_{\varrho \geq 0}$ is S -Wiener process defined on $(\Omega, \Upsilon, \{\Upsilon_{\varrho}\}_{\varrho \geq 0}, P)$ with values in Hilbert space Ξ and $\{Z_H(\varrho)\}_{\varrho \geq 0}$ is S -Rosenblatt process with parameter $H \in (\frac{1}{2}, 1)$ defined on $(\Omega, \Upsilon, \{\Upsilon_{\varrho}\}_{\varrho \geq 0}, P)$ with values in Hilbert space Y . We are also employing the same notation $\| \cdot \|$ for the norm in $\Phi, \Xi, \Lambda, L(\Xi, \Phi)$ and $L(\Phi, \Lambda)$ where $L(\Xi, \Lambda)$ and $L(\Phi, \Lambda)$ denote respectively the space of all bounded linear operators from Ξ into Λ and Φ into Λ . The functions $\mathfrak{K}, \mathfrak{J}, \sigma, h, \psi$ and g_i are given functions to be defined later.

2. Preliminaries

In this section, some definitions and results are given which will be used throughout this paper.

Definition 2.1 (see [14]). Let $0 < \hbar \leq 1$. The conformable fractional derivative of order \hbar of a function $f(\cdot)$ for $\varrho > 0$ is defined as follows

$$\frac{d^{\hbar} f(\varrho)}{d\varrho^{\hbar}} = \lim_{v \rightarrow 0} \frac{f(\varrho + v\varrho^{1-\hbar}) - f(\varrho)}{v}.$$

For $\varrho = 0$, we adopt the following definition:

$$\frac{d^{\hbar} f(0)}{d\varrho^{\hbar}} = \lim_{\varrho \rightarrow 0^+} \frac{d^{\hbar} f(\varrho)}{d\varrho^{\hbar}}.$$

The fractional integral $I^{\hbar}(\cdot)$ associated with the conformable fractional derivative is defined by

$$I^{\hbar}(f)(\varrho) = \int_0^{\varrho} s^{\hbar-1} f(s) ds.$$

Let (Ω, Υ, P) be a complete probability space equipped with a normal filtration $\Upsilon_{\varrho}, \varrho \in [0, G]$ where Υ_{ϱ} is the σ -algebra generated by random variables $\{\omega(s), Z_H(s), s \in [0, G]\}$ and all P -null sets. Let $(V, \Phi, \rho(dv))$ be a σ -finite measurable space. Given stationary Poisson point process $(p_{\varrho})_{\varrho \geq 0}$, which is defined on (Ω, η, P) with values in V and with characteristic measure ρ . We will denote by $N(\varrho, dv)$ be the counting measure of p_{ϱ} such that $\tilde{N}(\varrho, \Theta) := E(N(\varrho, \Theta)) = \varrho\rho(\Theta)$ for $\Theta \in \Psi$. Define $\tilde{N}(\varrho, dv) := N(\varrho, dv) - \varrho\lambda(dv)$, the Poisson martingale measure generated by p_{ϱ} .

Fix a time interval $[0, G]$ and let $\{Z_H(\varrho), \varrho \in [0, G]\}$ represents one-dimensional Rosenblatt process with parameter $H \in (1/2, 1)$. The Rosenblatt process with parameter $H > \frac{1}{2}$ can be written as

$$Z_H(\varrho) = \zeta(H) \int_0^{\varrho} \int_0^{\varrho} \left[\int_{y_1 \vee y_2}^{\varrho} \frac{\partial K^H}{\partial v}(v, y_1) \frac{\partial K^H}{\partial v}(v, y_2) \right] dB(y_1) dB(y_2)$$

where $K^H(\varrho, s)$ is given by

$$K_H(\varrho, s) = c_H s^{\frac{1}{2}-H} \int_s^\varrho (v-s)^{H-\frac{3}{2}} v^{H-\frac{1}{2}} dv, \text{ for } s < \varrho,$$

with $c_H = \sqrt{\frac{H(2H-1)}{\beta(2-2H, H-\frac{1}{2})}}$ and $\beta(\cdot, \cdot)$ denotes the Beta function, $K_H(\varrho, s) = 0$ when $\varrho \leq s$,

$\{B(\varrho), \varrho \in [0, G]\}$ is a Brownian motion, $H' = \frac{H+1}{2}$ and $\zeta(H) = \frac{1}{H+1} \sqrt{\frac{H}{2H-1}}$ is a normalizing constant. The covariance of the Rosenblatt process $Z_H(\varrho), \varrho \in [0, G]$ satisfy

$$E(Z_H(\varrho)Z_H(s)) = \frac{1}{2}(s^{2H} + \varrho^{2H} - |s - \varrho|^{2H}).$$

Let $S \in L(\Phi, \Phi)$ be an operator defined by $Se_n = \lambda_n e_n$ with finite trace $Tr(S) = \sum_{n=1}^\infty \lambda_n < \infty$ where $\lambda_n \geq 0$ ($n = 1, 2, \dots$) are non-negative real numbers and $\{e_n\}$ ($n = 1, 2, \dots$) is a complete orthonormal basis in Φ .

We define the infinite dimensional S-Rosenblatt process on Φ as

$$Z_H(\varrho) = Z_S(\varrho) = \sum_{n=1}^\infty \sqrt{\lambda_n} e_n z_n(\varrho)$$

where $(z_n)_{n \geq 0}$ is a family of real, independent Rosenblatt process.

In order to define Wiener integrals with respect to the S-Rosenblatt process, we introduce the space $L_2^0 := L_2^0(\Phi, \Lambda)$ of all S-Hilbert Schmidt operators $\chi : \Phi \rightarrow \Lambda$. We recall that $\chi \in L(\Phi, \Lambda)$ is called a S-Hilbert-Schmidt operator, if

$$\|\chi\|_{L_2^0}^2 := \sum_{n=1}^\infty \|\sqrt{\lambda_n} \chi e_n\|^2 < \infty$$

and that the space L_2^0 equipped with the inner product $\langle \vartheta, \chi \rangle_{L_2^0} = \sum_{n=1}^\infty \langle \vartheta e_n, \chi e_n \rangle$ is a separable Hilbert space. Let $\phi(s); s \in [0, G]$ be a function with values in $L_2^0(\Phi, \Lambda)$, the Wiener integral of ϕ with respect to Z_S is defined by

$$\int_0^\varrho \phi(s) dZ_S(s) = \sum_{n=1}^\infty \int_0^\varrho \sqrt{\lambda_n} K_H^*(\phi e_n)(y_1, y_2) dB(y_1) dB(y_2)$$

where

$$K_H^*(\vartheta)(y_1, y_2) = \int_{y_1 \vee y_2}^G \vartheta(r) \frac{\partial K}{\partial r}(r, y_1, y_2) dr.$$

For more details (see [30]).

Lemma 2.1 (see [31]). If $\chi : [0, G] \rightarrow L_2^0(\Phi, \Lambda)$ satisfies $\int_0^G \|\chi(s)\|_{L_2^0}^2 ds < \infty$ then the above sum in (2.2) is well defined as Λ -valued random variable and we have

$$E \left\| \int_0^\varrho \chi(s) dZ_H(s) \right\|^2 \leq 2H \varrho^{2H-1} \int_0^\varrho \|\chi(s)\|_{L_2^0}^2 ds.$$

We suppose that $0 \in \rho(T)$, the resolvent set of T , and $\|\Delta(\varrho)\| \leq M$ for some constant $M \geq 1$ and every $\varrho \geq 0$. The collection of all strongly-measurable, square-integrable, X -valued random variables, denoted by $L_2(\Omega, \Lambda)$, is a Banach space equipped with norm

$$\|y(\cdot)\|_{L_2(\Omega, \Lambda)} = (E \|y(\cdot, \omega)\|^2)^{\frac{1}{2}},$$

where the expectation, E is defined by $E(y) = \int_\Omega y(\omega) dP$.

Let $C(J, L_2(\Omega, \Lambda))$ be the Banach space of all continuous maps from J into $L_2(\Omega, \Lambda)$ satisfying the condition

$$\sup_{\varrho \in J} E \| y(\varrho) \|^2 < \infty.$$

Define $\bar{C} = \{y : y(\varrho) \in C(J, L_2(\Omega, \Lambda))\}$, with norm $\| \cdot \|_{\bar{C}}$ defined by

$$\| \cdot \|_{\bar{C}} = (\sup_{\varrho \in J} E |y(\varrho)|^2)^{\frac{1}{2}}.$$

Obviously, \bar{C} is a Banach space.

We impose the following conditions on data of the problem:

(H1) $\mathfrak{K} : J \times \Lambda \rightarrow \Lambda$ is a continuous function, and there exists $M_1, M_2 > 0$ such that the function \mathfrak{K} satisfies the Lipschitz condition:

$$E \| \mathfrak{K}(\varrho_1, y) - \mathfrak{K}(\varrho_2, x) \|^2 \leq M_1(|\varrho_1 - \varrho_2| + E \| y - x \|^2),$$

for $0 \leq \varrho_1, \varrho_2 \leq G, y, x \in \Lambda$, and the inequality

$$E \| \mathfrak{K}(\varrho, y) \|^2 \leq M_2(E \| y \|^2 + 1) \tag{2}$$

holds for $(\varrho, y) \in J \times \Lambda$.

(H2) The function $\mathfrak{J} : J \times \Lambda \rightarrow L(\Xi, \Lambda)$ satisfies the following conditions:

(i) for each $\varrho \in J$, the function $\mathfrak{J}(\varrho, \cdot) : \Lambda \rightarrow L(\Xi, \Lambda)$ is continuous and for each $y \in \Lambda$; the function $\mathfrak{J}(\cdot, y) : J \rightarrow L(\Xi, \Lambda)$ is Υ_ϱ -measurable;

(ii) for each positive number $d \in N$, there is a positive function $h_d(\cdot) : (0, G] \rightarrow R^+$ such that

$$\sup_{\|y\|^2 \leq d} E \| \mathfrak{J}(\varrho, y) \|^2 \leq h_d(\varrho),$$

the function $s \rightarrow h_d(s) \in L^1((0, G], R^+)$ and there exists a $\Lambda_2 > 0$ such that

$$\liminf_{d \rightarrow \infty} \frac{\int_0^\varrho h_d(s) ds}{d} = \Lambda_2 < \infty, \quad \varrho \in (0, G].$$

(H3) The function $\sigma : J \times \Lambda \rightarrow L_2^0(\Phi, \Lambda)$ satisfies the following conditions:

(i) for each $\varrho \in J$, the function $\sigma(\varrho, \cdot) : \Lambda \rightarrow L_2^0(\Phi, \Lambda)$ is continuous and for each $y \in \Lambda$; the function $\sigma(\cdot, y) : J \rightarrow L_2^0(\Phi, \Lambda)$ is Υ_ϱ -measurable;

(ii) for each positive number $d \in N$, there is a positive function $\bar{h}_d(\cdot) : (0, G] \rightarrow R^+$ such that

$$\sup_{\|x\|^2 \leq d} E \| \sigma(\varrho, y) \|^2_{L_2^0} \leq \bar{h}_d(\varrho),$$

the function $s \rightarrow \bar{h}_d(s) \in L^1((0, G], R^+)$ and there exists a $\Lambda_3 > 0$ such that

$$\liminf_{d \rightarrow \infty} \frac{\int_0^\varrho \bar{h}_d(s) ds}{d} = \Lambda_3 < \infty, \quad \varrho \in (0, G],$$

(H4) The function $h : J \times \Lambda \times V \rightarrow \Lambda$ satisfies the following two conditions:

(i) The function $h(\varrho, \cdot, \cdot) : \Lambda \times V \rightarrow \Lambda$ is continuous.

(ii) for each positive number $d \in N$, there is a positive function $\chi_d(\cdot) : J \rightarrow R^+$ such that

$$\sup_{\|x\|^2 \leq d} \int_V E \| h(\varrho, y, v) \|^2 \lambda(dv) \leq \chi_d(\varrho),$$

the function $s \rightarrow \chi_d(s) \in L^1((0, G], R^+)$, and there exists a $\Lambda_4 > 0$ such that

$$\liminf_{d \rightarrow \infty} \frac{\int_0^\varrho \chi_d(s) ds}{d} = \Lambda_4 < \infty, \quad \varrho \in (0, G].$$

(H5) The function $g_i : (Q_i, s_i] \times \Lambda \rightarrow \Lambda$ is continuous and satisfies the following two conditions:

(i) There exist a constant $M_3 > 0$, such that

$$E \|g_i(\varrho, y)\|^2 \leq M_3(E\|y\|^2 + 1), \quad \forall y \in \Lambda; \varrho \in (Q_i, s_i], i = 1, 2, \dots, m.$$

(ii) There exist a constant $M_4 > 0$, such that

$$E \|g_i(\varrho, y) - g_i(\varrho, x)\|^2 \leq M_4 E \|y - x\|^2, \quad \forall y, x \in \Lambda; \varrho \in (Q_i, s_i], i = 1, 2, \dots, m.$$

(H6) The function $\psi : C(J, \Lambda) \rightarrow \Lambda$ satisfies the following two conditions:

(i) There exist a constant $M_5 > 0$, such that

$$E \|\psi(y)\|^2 \leq M_5(E\|y\|^2 + 1), \quad \forall y \in \Lambda.$$

(ii) There exist a constant $M_6 > 0$, such that

$$E \|\psi(y) - \psi(x)\|^2 \leq M_6 E \|y - x\|^2, \quad \forall y, x \in \Lambda.$$

Definition 2.2. An Y_ϱ -adapted stochastic process $y(\varrho) : J \rightarrow \Lambda$ is said to be a mild solution of problem (1) if the following stochastic integral equation is verified:

$$y(\varrho) = \begin{cases} \Delta\left(\frac{\varrho^h}{h}\right)[y_0 - \psi(y)] + \int_0^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) [\mathfrak{X}(s, y(s)) + Qu(s)] ds \\ + \int_0^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \mathfrak{Y}(s, y(s)) d\omega(s) + \int_0^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \sigma(s, y(s)) dZ_H(s) \\ + \int_0^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \int_V h(s, y(s), v) \tilde{N}(ds, dv), \quad \varrho \in (0, \varrho_1] \\ g_i(\varrho, y(\varrho)), \quad \varrho \in (Q_i, s_i], i = 1, 2, \dots, m, \\ \Delta\left(\frac{\varrho^h - s_i^h}{h}\right) g_i(s_i, y(s_i)) + \int_{s_i}^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) [\mathfrak{X}(s, y(s)) + Qu(s)] ds \\ + \int_{s_i}^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \mathfrak{Y}(s, y(s)) d\omega(s) + \int_{s_i}^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \sigma(s, y(s)) dZ_H(s) \\ + \int_{s_i}^\varrho s^{\hbar-1} \Delta\left(\frac{\varrho^h - s^h}{h}\right) \int_V h(s, y(s), v) \tilde{N}(ds, dv), \quad \varrho \in (s_i, \varrho_{i+1}], i = 1, 2, \dots, m. \end{cases}$$

3. Main result

In this section, we study the controllability for the system (1).

Definition 3.1. The system (1) is said to be controllable on J , if for every $y_0, y_1 \in \Lambda$, there exists a control $u \in L^2(J, U)$ such that the mild solution $y(\varrho)$ of the system (1) satisfies $y(G) = y_1$, where y_1 and G are the preassigned terminal state and time respectively.

To establish the result, we need the following additional hypothesis

(H7) The linear operator Π from U into Λ defined by

$$\Pi u = \int_0^G s^{\hbar-1} \Delta\left(\frac{G^h - s^h}{h}\right) Qu(s) ds$$

has an inverse operator Π^{-1} which takes values in $L^2(J, U) \setminus \ker \Pi$, where the kernel space of Π is defined by $\ker \Pi = \{y \in L^2(J, U) : \Pi y = 0\}$ and there exist positive constant M_Q, M_Π such that $\|Q\|^2 = M_Q, \|\Pi^{-1}\|^2 = M_\Pi$.

Theorem 3.1. If the assumptions (H1)-(H7) are satisfied. Then, the system (1) is controllable on J provided that

$$36 \left\{ 1 + \frac{M_\Pi M_Q M^2 G^{2\hbar-1}}{2\hbar-1} \right\} \left\{ M_5 + M_3(M^2 + 1) + \frac{M^2 G^{2\hbar-1} M_2}{2\hbar-1} + \frac{Tr(S) M^2 G^{2\hbar-1}}{2\hbar-1} \Lambda_2 \right. \\ \left. + \frac{2HM^2 G^{2\hbar+2\hbar-2}}{2\hbar-1} \Lambda_3 + \frac{M^2 G^{2\hbar-1}}{2\hbar-1} \Lambda_4 \right\} < 1. \tag{3}$$

and

$$\ell_1 = 4M_6 + \frac{4M^2M_1G^{2h-1}}{2h-1} + M_4(1 + 4M^2) < 1. \tag{4}$$

Proof. Consider the map \bar{U} on \bar{C} defined by

$$(\bar{U}y)(\varrho) = \begin{cases} \Delta\left(\frac{\varrho^h}{h}\right)[y_0 - \psi(y)] + \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)[\mathfrak{R}(s, y(s)) + Qu(s)] ds \\ + \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{I}(s, y(s))d\omega(s) + \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\sigma(s, y(s))dZ_H(s) \\ + \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\int_V h(s, y(s), v)\tilde{N}(ds, dv), \varrho \in (0, \varrho_1] \\ g_i(\varrho, y(\varrho)), \varrho \in (\varrho_i, s_i], i = 1, 2, \dots, m, \\ \Delta\left(\frac{\varrho^h-s_i^h}{h}\right)g_i(s_i, y(s_i)) + \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)[\mathfrak{R}(s, y(s)) + Qu(s)] ds \\ + \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{I}(s, y(s))d\omega(s) + \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\sigma(s, y(s))dZ_H(s) \\ + \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\int_V h(s, y(s), v)\tilde{N}(ds, dv), \varrho \in (s_i, \varrho_{i+1}], i = 1, 2, \dots, m. \end{cases}$$

where

$$u(\varrho) = \begin{cases} \Pi^{-1}\{y_1 - \Delta\left(\frac{\varrho^h}{h}\right)[y_0 - \psi(y)] - \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{R}(s, y(s))ds \\ - \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{I}(s, y(s))d\omega(s) - \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\sigma(s, y(s))dZ_H(s) \\ - \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\int_V h(s, y(s), v)\tilde{N}(ds, dv)\}(\varrho), \varrho \in (0, \varrho_1] \\ \Pi^{-1}\{y_1 - \Delta\left(\frac{\varrho^h-s_i^h}{h}\right)g_i(s_i, y(s_i)) - \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{R}(s, y(s))ds \\ - \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{I}(s, y(s))d\omega(s) - \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\sigma(s, y(s))dZ_H(s) \\ - \int_{s_i}^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\int_V h(s, y(s), v)\tilde{N}(ds, dv)\}(\varrho), \varrho \in (s_i, \varrho_{i+1}], i = 1, 2, \dots, m. \end{cases}$$

It will be shown that the operator \bar{U} from \bar{C} into itself has a fixed point.

For each positive integer d , set $\varphi_d = \{y \in \bar{C}, \|y\|_{\bar{C}}^2 \leq d\}$.

We claim that there exists a positive number d such that $\bar{U}(\varphi_d) \subset \varphi_d$. If it is not true, then for each positive number d , there is a function $y_d(\cdot) \in \varphi_d$, but $\bar{U}(y_d) \notin \varphi_d$, that is $\|(\bar{U}y_d)(\varrho)\|_{\bar{C}}^2 > d$ for some $\varrho = \varrho(d) \in J$, where $\varrho(d)$ denotes that ϱ is dependent of d .

From (H1)-(H7), we have,

for $\varrho \in (0, \varrho_1]$

$$\begin{aligned} \|\bar{U}y_d\|_{\bar{C}}^2 &\leq 36 \sup_{\varrho \in J} \left\{ E\|\Delta\left(\frac{\varrho^h}{h}\right)[y_0 - \psi(y)]\|^2 + E\left\|\int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{R}(s, y(s))ds\right\|^2 \right. \\ &\quad + E\left\|\int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)Qu(s)ds\right\|^2 \\ &\quad + E\left\|\int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\mathfrak{I}(s, y(s))d\omega(s)\right\|^2 \\ &\quad + E\left\|\int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\sigma(s, y(s))dZ_H(s)\right\|^2 \\ &\quad \left. + \int_0^\varrho s^{h-1}\Delta\left(\frac{\varrho^h-s^h}{h}\right)\int_V h(s, y(s), v)\tilde{N}(ds, dv)\right\} \end{aligned}$$

$$\begin{aligned} \leq & 36 \left\{ 1 + \frac{M_{\Pi} M_Q M^2 G^{2h-1}}{2h-1} \right\} \left\{ M^2 [E \|y_0\|^2 + M_5(d+1)] \right. \\ & + \frac{M^2 G^{2h-1} M_1(d+1)}{2h-1} + \frac{Tr(S) M^2 G^{2h-1}}{2h-1} \int_0^G h_d(s) ds \\ & + \frac{2HM^2 G^{2H+2h-2}}{2h-1} \int_0^G \bar{h}_d(s) ds + \frac{M^2 G^{2h-1}}{2h-1} \int_0^G \chi_d(s) ds \left. \right\} \\ & + \frac{36 M_{\Pi} M_Q M^2 G^{2h-1} E \|y_1\|^2}{2h-1}. \end{aligned} \tag{5}$$

From (H5), we have for $\varrho \in (\varrho_i, s_i]$

$$\| \bar{\mathcal{U}} y_d \|_{\mathcal{C}}^2 \leq \sup_{\varrho \in J} E \|g_i(\varrho, y(\varrho))\|^2 \leq M_3(d+1). \tag{6}$$

From (H1)-(H7), we have, for $\varrho \in (s_i, \varrho_{i+1}]$

$$\begin{aligned} \| \bar{\mathcal{U}} y_d \|_{\mathcal{C}}^2 & \leq 36 \sup_{\varrho \in J} \left\{ E \left\| \Delta \left(\frac{\varrho^h - s_i^h}{h} \right) g_i(s_i, y(s_i)) \right\|^2 \right. \\ & + E \left\| \int_{s_i}^{\varrho} s^{h-1} \Delta \left(\frac{\varrho^h - s^h}{h} \right) \mathfrak{R}(s, y(s)) ds \right\|^2 + E \left\| \int_{s_i}^{\varrho} s^{h-1} \Delta \left(\frac{\varrho^h - s^h}{h} \right) Qu(s) ds \right\|^2 \\ & + E \left\| \int_0^{\varrho} s^{h-1} \Delta \left(\frac{\varrho^h - s^h}{h} \right) \int_{s_i}^s \mathfrak{I}(\tau, y(\tau)) d\omega(\tau) ds \right\|^2 \\ & + E \left\| \int_{s_i}^{\varrho} s^{h-1} \Delta \left(\frac{\varrho^h - s^h}{h} \right) \sigma(s, y(s)) dZ_H(s) \right\|^2 \\ & + \left. \int_{s_i}^{\varrho} s^{h-1} \Delta \left(\frac{\varrho^h - s^h}{h} \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv) \right\|^2 \left. \right\} \\ & \leq 36 \left\{ 1 + \frac{M_{\Pi} M_Q M^2 G^{2h-1}}{2h-1} \right\} \left\{ M^2 M_3(d+1) \right. \\ & + \frac{M^2 G^{2h-1} M_2(d+1)}{2h-1} + \frac{Tr(S) M^2 G^{2h-1}}{2h-1} \int_{s_i}^G h_d(s) ds \\ & + \frac{2HM^2 G^{2H+2h-2}}{2h-1} \int_{s_i}^G \bar{h}_d(s) ds + \frac{M^2 G^{2h-1}}{2h-1} \int_{s_i}^G \chi_d(s) ds \left. \right\} \\ & + \frac{36 M_{\Pi} M_Q M^2 G^{2h-1} E \|y_1\|^2}{2h-1}. \end{aligned} \tag{7}$$

Combining (5), (6), (7) in the inequality $d \leq \|(\bar{\mathcal{U}} y_d)(t)\|_{\mathcal{C}}^2$ then dividing both sides of the inequality by d and taking the lower limit $d \rightarrow +\infty$, we get

$$\begin{aligned} & 36 \left\{ 1 + \frac{M_{\Pi} M_Q M^2 G^{2h-1}}{2h-1} \right\} \left\{ M_5 + M_3(M^2 + 1) + \frac{M^2 G^{2h-1} M_2}{2h-1} + \frac{Tr(S) M^2 G^{2h-1}}{2h-1} \Lambda_2 \right. \\ & \left. + \frac{2HM^2 G^{2H+2h-2}}{2h-1} \Lambda_3 + \frac{M^2 G^{2h-1}}{2h-1} \Lambda_4 \right\} \geq 1. \end{aligned}$$

This contradicts (3). Hence for positive d , $\bar{\mathcal{U}}(\varphi_d) \subset \varphi_d$.

Next we will show that the operator $\bar{\mathcal{U}}$ has a fixed point on φ_d , which implies that equation (1) has a mild solution. We decompose $\bar{\mathcal{U}}$ as $\bar{\mathcal{U}} = \bar{\mathcal{U}}_1 + \bar{\mathcal{U}}_2$, where the operators $\bar{\mathcal{U}}_1$ and $\bar{\mathcal{U}}_2$ are defined on φ_d , respectively, by

$$(\mathfrak{U}_1 y)(\varrho) = \begin{cases} \Delta\left(\frac{\varrho^{\hbar}}{\hbar}\right)[y_0 - \psi(y)] + \int_0^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) \mathfrak{R}(s, y(s)) ds, & \varrho \in (0, \varrho_1] \\ g_i(\varrho, y(\varrho)), & \varrho \in (\varrho_i, s_i], \quad i = 1, 2, \dots, m, \\ \Delta\left(\frac{\varrho^{\hbar}-s_i^{\hbar}}{\hbar}\right) g_i(s_i, y(s_i)) + \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) \mathfrak{R}(s, y(s)) ds, & \varrho \in (s_i, \varrho_{i+1}], \quad i = 1, 2, \dots, m. \end{cases}$$

$$(\mathfrak{U}_2 y)(\varrho) = \begin{cases} \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) Qu(s) ds \\ + \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) \mathfrak{J}(s, y(s)) d\omega(s) + \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) \sigma(s, y(s)) dZ_H(s) \\ + \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) \int_V h(s, y(s), v) \tilde{N}(ds, dv), & \varrho \in (s_i, \varrho_{i+1}], \quad i = 0, 1, \dots, m. \\ 0, & \text{otherwise.} \end{cases}$$

For $\varrho \in J$, we will show that \mathfrak{U}_1 verifies a contraction condition while \mathfrak{U}_2 is a compact operator. To prove that \mathfrak{U}_1 satisfies a contraction condition, we take $y_1, y_2 \in \wp_d$, then for each $\varrho \in J$ and by conditions (H1), (H5) and (H6) we have for $\varrho \in (0, \varrho_1]$

$$\begin{aligned} E \| (\mathfrak{U}_1 y_1)(\varrho) - (\mathfrak{U}_1 y_2)(\varrho) \|^2 &\leq 4 \left\{ E \| \psi(y_1) - \psi(y_2) \| \right. \\ &\quad \left. + E \left\| \int_0^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) [\mathfrak{R}(s, y_1(s)) - \mathfrak{R}(s, y_2(s))] ds \right\|^2 \right\} \\ &\leq \left\{ 4M_6 + \frac{4M^2 M_1 G^{2\hbar-1}}{2\hbar-1} \right\} E \| y_1(\varrho) - y_2(\varrho) \|^2, \end{aligned} \tag{8}$$

for $\varrho \in (\varrho_i, s_i]$

$$\begin{aligned} E \| (\mathfrak{U}_1 y_1)(\varrho) - (\mathfrak{U}_1 y_2)(\varrho) \|^2 &\leq E \| g_i(\varrho, y_1(\varrho)) - g_i(\varrho, y_2(\varrho)) \|^2 \\ &\leq M_4 E \| y_1(\varrho) - y_2(\varrho) \|^2 \end{aligned} \tag{9}$$

and for $\varrho \in (s_i, \varrho_{i+1}]$

$$\begin{aligned} E \| (\mathfrak{U}_1 y_1)(\varrho) - (\mathfrak{U}_1 y_2)(\varrho) \|^2 &\leq 4E \left\| \Delta\left(\frac{\varrho^{\hbar}-s_i^{\hbar}}{\hbar}\right) (g_i(s_i, y_1(s_i)) - g_i(s_i, y_2(s_i))) \right\|^2 \\ &\quad + 4E \left\| \int_{s_i}^{\varrho} s^{\hbar-1} \Delta\left(\frac{\varrho^{\hbar}-s^{\hbar}}{\hbar}\right) [\mathfrak{R}(s, y_1(s)) - \mathfrak{R}(s, y_2(s))] ds \right\|^2 \\ &\leq \left[4M^2 M_4 + \frac{4M^2 M_1 G^{2\hbar-1}}{2\hbar-1} \right] E \| y_1(\varrho) - y_2(\varrho) \|^2. \end{aligned} \tag{10}$$

Combining (8), (9) and (10), we get

$$\begin{aligned} E \| (\mathfrak{U}_1 y_1)(\varrho) - (\mathfrak{U}_1 y_2)(\varrho) \|^2 &\leq \left[4M_6 + \frac{4M^2 M_1 G^{2\hbar-1}}{2\hbar-1} + M_4(1 + 4M^2) \right] E \| y_1(\varrho) - y_2(\varrho) \|^2 \\ &\leq \ell_1 E \| y_1(\varrho) - y_2(\varrho) \|^2, \end{aligned}$$

therefore,

$$\sup_{\varrho \in J} E \| (\mathfrak{U}_1 y_1)(\varrho) - (\mathfrak{U}_1 y_2)(\varrho) \|^2 \leq \ell_1 \sup_{\varrho \in J} E \| y_1(\varrho) - y_2(\varrho) \|^2$$

hence,

$$\| \mathcal{U}_1 y_1 - \mathcal{U}_1 y_2 \|_{\mathcal{C}}^2 \leq \ell_1 \| y_1 - y_2 \|_{\mathcal{C}}^2 .$$

Thus, \mathcal{U}_1 is a contraction.

To prove that \mathcal{U}_2 is compact, first we prove that \mathcal{U}_2 is continuous on \wp_d .

Let $\{y_n\} \subset \wp_d$ with $y_n \rightarrow \Lambda$ in \wp_q and rewrite $u(t) = u(t, y)$ the control function defined above. Then for each $s \in J$, $y_n(s) \rightarrow y(s)$, and by H2(i), H3(i) and H4(i), we have

$\mathfrak{J}(s, y_n(s)) \rightarrow \mathfrak{J}(s, y(s))$, as $n \rightarrow \infty$,

$\sigma(s, y_n(s)) \rightarrow \sigma(s, y(s))$, as $n \rightarrow \infty$ and

$h(s, y_n(s), v) \rightarrow h(s, y(s), v)$, as $n \rightarrow \infty$.

By the dominated convergence theorem, we have,

$$\begin{aligned} \| \mathcal{U}_2 y_n - \mathcal{U}_2 y \|_{\mathcal{C}}^2 &= \sup_{\rho \in J} \left\{ E \left\| \int_{s_i}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) Q(u(s, y_n) - u(s, y)) ds \right. \right. \\ &+ \int_{s_i}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) [\mathfrak{J}(s, y_n(s)) - \mathfrak{J}(s, y(s))] d\omega(s) \\ &+ \int_{s_i}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) [\sigma(s, y_n(s)) - \sigma(s, y(s))] dZ_H(s) \\ &\left. \left. + \int_{s_i}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \int_V [h(s, y_n(s), v) - h(s, y(s), v)] \tilde{N}(ds, dv) \right\|^2 \right\} \rightarrow 0, \end{aligned}$$

as $n \rightarrow \infty$, that is continuous.

Next we prove that the family $\{\mathcal{U}_2 y : y \in \wp_d\}$ is an equicontinuous family of functions.

Let $\epsilon > 0$ small, $s_i < \rho_\alpha < \rho_\beta \leq \rho_{i+1}$, then

$$\begin{aligned} &E \| (\mathcal{U}_2 y)(\rho_\beta) - (\mathcal{U}_2 y)(\rho_\alpha) \|^2 \\ &\leq E \left\| \int_{s_i}^{\rho_\alpha - \epsilon} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) Qu(s) ds \right\|^2 \\ &+ \left\| \int_{\rho_\alpha - \epsilon}^{\rho_\alpha} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) Qu(s) ds \right\|^2 \\ &+ \left\| \int_{\rho_\alpha}^{\rho_\beta} s^{\hbar-1} \Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) Qu(s) ds \right\|^2 \\ &+ E \left\| \int_{s_i}^{\rho_\alpha - \epsilon} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \mathfrak{J}(s, y(s)) d\omega(s) \right\|^2 \\ &+ \left\| \int_{\rho_\alpha - \epsilon}^{\rho_\alpha} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \mathfrak{J}(s, y(s)) d\omega(s) \right\|^2 \\ &+ \left\| \int_{\rho_\alpha}^{\rho_\beta} s^{\hbar-1} \Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) \mathfrak{J}(s, y(s)) d\omega(s) \right\|^2 \end{aligned}$$

$$\begin{aligned}
 &+E \left\| \int_{s_i}^{\rho_\alpha - \epsilon} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \sigma(s, y(s)) dZ_H(s) \right\|^2 \\
 &+ \left\| \int_{\rho_\alpha - \epsilon}^{\rho_\alpha} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \sigma(s, y(s)) dZ_H(s) \right\|^2 \\
 &+ \left\| \int_{\rho_\alpha}^{\rho_\beta} s^{\hbar-1} \Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) \sigma(s, y(s)) dZ_H(s) \right\|^2 \\
 &+E \left\| \int_{s_i}^{\rho_\alpha - \epsilon} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv) \right\|^2 \\
 &+ \left\| \int_{\rho_\alpha - \epsilon}^{\rho_\alpha} s^{\hbar-1} \left(\Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) - \Delta \left(\frac{\rho_\alpha^{\hbar} - s^{\hbar}}{\hbar} \right) \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv) \right\|^2 \\
 &+ \left\| \int_{\rho_\alpha}^{\rho_\beta} s^{\hbar-1} \Delta \left(\frac{\rho_\beta^{\hbar} - s^{\hbar}}{\hbar} \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv) \right\|^2 .
 \end{aligned}$$

We see that $E \left\| (\mathfrak{U}_2 y)(\rho_\beta) - (\mathfrak{U}_2 y)(\rho_\alpha) \right\|^2$ tends to zero independently of $y \in \wp_d$ as $\rho_\beta \rightarrow \rho_\alpha$, and with ϵ sufficiently small, since the compactness of $\Delta(\rho)$ for $\rho > 0$ implies the continuity in the uniform operator topology (see [28]). Similarly, we can prove that the function $\mathfrak{U}_2 y$, $y \in \wp_d$ are equicontinuous at $\rho = 0$. Hence \mathfrak{U}_2 maps \wp_d into a family of equicontinuous functions.

It remains to prove that $\mu(\rho) = \{(\mathfrak{U}_2 y)(\rho) : y \in \wp_d\}$ is relatively compact in \wp_d . Obviously, $\mu(0)$ is relatively compact in \wp_d .

Let $s_i < \rho \leq \rho_{i+1}$ be fixed and let ϵ be a given real number satisfying $s_i < \epsilon < \rho$, for $y \in \wp_d$, we define

$$\begin{aligned}
 (\mathfrak{U}_2^\epsilon y)(\rho) &= \int_{s_i}^{\rho - \epsilon} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) Qu(s) ds + \int_{s_i}^{\rho - \epsilon} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \mathfrak{F}(s, y(s)) d\omega(s) \\
 &+ \int_{s_i}^{\rho - \epsilon} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \sigma(s, y(s)) dZ_H(s) \\
 &+ \int_{s_i}^{\rho - \epsilon} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv), \quad \rho \in (s_i, \rho_{i+1}], \quad i = 1, 2, \dots, m.
 \end{aligned}$$

Since $u(s)$ is bounded and $\Delta(\rho)$ is a compact operator, then the set $\mu^\epsilon(\rho) = \{(\mathfrak{U}_2^\epsilon y)(\rho) : y \in \wp_d\}$ is relatively compact in Λ for every ϵ , $s_i < \epsilon < \rho$.

Moreover, for every $y \in \wp_d$, we have

$$\begin{aligned}
 E \left\| \mathfrak{U}_2 y - \mathfrak{U}_2^\epsilon y \right\|_{\mathbb{C}}^2 &\leq 16 \sup_{\rho \in J} \left\{ E \left\| \int_{\rho - \epsilon}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) Qu(s) ds \right\|^2 \right. \\
 &+ E \left\| \int_{\rho - \epsilon}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \mathfrak{F}(s, y(s)) d\omega(s) \right\|^2 \\
 &+ E \left\| \int_{\rho - \epsilon}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \sigma(s, y(s)) dZ_H(s) \right\|^2 \\
 &\left. + E \left\| \int_{\rho - \epsilon}^{\rho} s^{\hbar-1} \Delta \left(\frac{\rho^{\hbar} - s^{\hbar}}{\hbar} \right) \int_V h(s, y(s), v) \tilde{N}(ds, dv) \right\|^2 \right\}.
 \end{aligned}$$

We see that for each $y \in \wp_d$, $\left\| \mathfrak{U}_2 y - \mathfrak{U}_2^\epsilon y \right\|_{\mathbb{C}}^2 \rightarrow 0$ as $\epsilon \rightarrow 0^+$. Therefore, there are relative compact sets arbitrary close to the set $\mu(\rho) = \{(\mathfrak{U}_2 y)(\rho) : y \in \wp_d\}$, hence the set $\mu(\rho)$ is also relatively compact in \wp_d .

Thus, by Arzela-Ascoli theorem \mathfrak{U}_2 is a compact operator. These arguments enable us to conclude that $\mathfrak{U} = \mathfrak{U}_1 + \mathfrak{U}_2$ is a condensing map on \wp_d , and by the fixed point theorem of Sadovskii there exists a fixed point $y(\cdot)$ for \mathfrak{U} on \wp_d . Thus, the system (1) is controllable on J .

4. Example

In this section, we present an example to illustrate our main result. Let us consider the following noninstantaneous impulsive conformable fractional stochastic differential equation with Rosenblatt process and nonlocal condition:

$$\begin{cases} D_{0+}^{\frac{3}{4}} y(\varrho, z) + \frac{\partial^2}{\partial z^2} y(\varrho, z) = 3^{-\varrho} y(\varrho, z) + \eta(\varrho, z) + e^{-\varrho} y(\varrho, z) \frac{d\omega(\varrho)}{d\varrho} \\ + \frac{\sin \varrho}{1 + \sin \varrho} y(\varrho, z) \frac{dZ_H(\varrho)}{d\varrho} + \int_V \bar{h}(\varrho, y(\varrho, z), v) \tilde{N}(d\varrho, dv), \quad \varrho \in (0, \frac{2}{3}] \cup (\frac{4}{3}, 2], \quad 0 \leq z \leq \pi, \\ y(\varrho, 0) = y(\varrho, \pi) = 0, \quad \varrho \in (0, 2], \\ y(\varrho, z) = \frac{2}{5} e^{-(\varrho - \frac{1}{4})} \frac{|y(\varrho, z)|}{1 + |y(\varrho, z)|}, \quad \varrho \in (\frac{2}{3}, \frac{4}{3}], \quad 0 \leq z \leq \pi, \\ y(0, z) + \sum_{i=1}^2 c_i y(\varrho_i, z) = y_0(z), \quad 0 \leq z \leq \pi, \end{cases} \tag{11}$$

where $D_{0+}^{\frac{3}{4}}$ is conformable fractional derivative of order $\hbar = \frac{3}{4}$, ω is a Wiener process and Z_H is a Rosenblatt process with Hurst parameter $H \in (\frac{1}{2}, 1)$.

Let $\Lambda = \Phi = \Xi = U = L_2([0, \pi])$ and T be defined by $Tm = -(\frac{\partial^2}{\partial z^2})m$ with domain $D(T) = \{\xi \in \Lambda : \xi, \frac{d\xi}{dz} \text{ are absolutely continuous, and } (\frac{d^2}{dz^2})\xi \in \Lambda, \xi(0) = \xi(\pi) = 0\}$.

Then $-T$ generates a strongly continuous semigroup $\Delta(\cdot)$ which is compact, analytic, and self-adjoint. Furthermore, $-T$ has discrete spectrum with eigenvalues n^2 , $n \in \mathbb{N}$ and the corresponding normalized eigenfunctions given by

$$e_n = \sqrt{\frac{2}{\pi}} \sin ny, \quad n = 1, 2, \dots$$

In addition $(e_n)_{n \in \mathbb{N}}$ is a complete orthonormal basis in Λ . Then

$$-T\xi = \sum_{n=1}^{\infty} n^2 \langle \xi, e_n \rangle e_n, \quad \xi \in D(T).$$

Furthermore, $-T$ is the infinitesimal generator of an analytic semigroup of bounded linear operator, $\{\Delta(\varrho)\}_{\varrho \geq 0}$ on Λ and is given by

$$\Delta(\varrho)\xi = \sum_{n=1}^{\infty} e^{-n^2 \varrho} \langle \xi, e_n \rangle e_n, \quad \xi \in \Lambda, \quad \varrho \geq 0.$$

with $\|\Delta(\varrho)\| \leq e^{-\varrho} \leq 1$.

We define the bounded operator $Q : U \rightarrow \Lambda$ by $Q = I$.

In order to define the operator $S : \Phi \rightarrow \Phi$, we choose a sequence $\{\lambda_n\}_{n \in \mathbb{N}} \subset \mathbb{R}^+$, set $Se_n = \lambda_n e_n$, and assume that

$$Tr(S) = \sum_{n=1}^{\infty} \sqrt{\lambda_n} < \infty.$$

We define $\mathfrak{K} : J \times \Lambda \rightarrow \Lambda$, $\mathfrak{J} : J \times \Lambda \rightarrow L(\Xi, \Lambda)$, $\sigma : J \times \Lambda \rightarrow L_2^0(Y, X)$, $h : J \times \Lambda \times V \rightarrow \Lambda$, $g_1 : (\frac{2}{3}, \frac{4}{3}] \times \Lambda \rightarrow \Lambda$ and $\psi : C(J, \Lambda) \rightarrow \Lambda$ by

$\mathfrak{K}(\varrho, y) = e^{-\varrho} y(\varrho, z)$, $\mathfrak{J}(\varrho, y)(z) = e^{-\varrho} y(\varrho, z)$, $\sigma(\varrho, y)(z) = \frac{\sin \varrho}{1 + \sin \varrho} y(\varrho, z)$, $h = \bar{h}(\varrho, y(\varrho, z), v)$, $g_1(\varrho, y(\varrho)) = \frac{2}{5} e^{-(\varrho - \frac{1}{4})} \frac{|y(\varrho, z)|}{1 + |y(\varrho, z)|}$ and $\psi = \sum_{i=1}^2 c_i y(\varrho_i, z)$, respectively and $J = (0, 2]$. Then \mathfrak{K} , \mathfrak{J} , σ , h , g_1 and ψ satisfy (H1)-(H6),

$$\begin{aligned} & 36 \left\{ 1 + \frac{M_{\Pi} M_Q M^2 G^{2\hbar-1}}{2\hbar-1} \right\} \left\{ M_5 + M_3(M^2 + 1) + \frac{M^2 G^{2\hbar-1} M_2}{2\hbar-1} + \frac{Tr(S) M^2 G^{2\hbar-1}}{2\hbar-1} \Lambda_2 \right. \\ & \left. + \frac{2HM^2 G^{2H+2\hbar-2}}{2\hbar-1} \Lambda_3 + \frac{M^2 G^{2\hbar-1}}{2\hbar-1} \Lambda_4 \right\} < 1 \end{aligned}$$

and

$$4M_6 + \frac{4M^2M_1G^{2\hbar-1}}{2\hbar-1} + M_4(1+4M^2) < 1.$$

Hence, according to Theorem 3.1, the system (11) is controllable on $J = (0, 2]$.

Conclusion

In this article, By using Sadovskii's fixed point theorem, fractional calculus and stochastic analysis, we studied the controllability of noninstantaneous impulsive conformable fractional stochastic differential equation with nonlinear noise and nonlocal condition via Rosenblatt process and Poisson jump. In the end paper, an example was provided to illustrate the applicability of the results.

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