Filomat 37:3 (2023), 925–933 https://doi.org/10.2298/FIL2303925O



Published by Faculty of Sciences and Mathematics, University of Niš, Serbia Available at: http://www.pmf.ni.ac.rs/filomat

On the solvability of a semiperiodic boundary value problem for a pseudohyperbolic equation

N.T. Orumbayeva^a, T.D. Tokmagambetova^a

^aKaragandy University of the name of academician E.A. Buketov

Abstract. The solvability of the boundary value problem for pseudohyperbolic equations of the third order is investigated. For the problem under study, an algorithm for finding an approximate solution is proposed and sufficient conditions for unique solvability are established.

1. Introduction

On $\Omega = [0, X] \times [0, Y]$ we consider the semiperiodic boundary value problem

$$\frac{\partial^3 u}{\partial x^2 \partial y} = A(x, y) \frac{\partial^2 u}{\partial x^2} + C(x, y) \frac{\partial^2 u}{\partial y^2} + f(x, y), \quad (x, y) \in \Omega,$$
(1)

$$u(x, 0) = u(x, Y), \quad x \in [0, X],$$
 (2)

$$u(0, y) = \varphi(y), \quad y \in [0, Y],$$
(3)

$$\frac{\partial u(0,y)}{\partial x} = \psi(y), \quad y \in [0,Y], \tag{4}$$

where $(n \times n)$ - matrix functions A(x, y), C(x, y), *n*-vector functions f(x, y) are continuous on Ω , *n*-vector functions $\varphi(y)$, $\psi(y)$ are continuously differentiable on [0, Y], here

$$||u(x, y)|| = \max_{i=1,n} |u_i(x, y)|, \quad ||A(x, y)|| = \max_{i=1,n} \sum_{j=1}^n |a_{ij}(x, y)|$$

Let $C(\Omega, \mathbb{R}^n)$ be the spaces of functions $u : \Omega \to \mathbb{R}^n$, which are continuous on Ω , with the rate $||u||_0 = \max ||u(x, y)||$.

Keywords. Pseudohyperbolic equation; Boundary value problem; Algorithm; Approximate solution.

²⁰²⁰ Mathematics Subject Classification. Primary 39A10, 39A70; Secondary 47B39, 26D15.

Received: 01 June 2021; Accepted: 27 October 2022

Communicated by Marko Nedeljkov

Research supported by the Science Committee of the Ministry of Education and Science of the Republic of Kazakhstan (Grant No. AP09259780).

Email addresses: orumbayevanurgul@gmail.com (N.T. Orumbayeva), tenggesh.tokmagambetova@gmail.com (T.D. Tokmagambetova)

Boundary value problems for hyperbolic equations of the third order have been investigated by many authors [1-5]. The interest in this type of equations is explained both by the theoretical significance of the results obtained and by their important practical applications [6]. Hyperbolic equations with two independent variables of the third and higher order are used as mathematical models of various processes: unsteady rectilinear flow of an incompressible fluid of the second order [7,8]; Navier-Stokes-Oldroyd fluid flows [9]; vibrations of elastic-viscous thread [10,11]; vibrations of the rod in the presence of relaxation and aftereffect of the simplest type [12]; the phenomenon of flutter of a cantilever wing [13, 14] and others.

In this paper, a semi-periodic boundary value problem for pseudohyperbolic equations of the third order is reduced to an equivalent problem of a family of boundary value problems for ordinary differential equations and functional relations. When solving a family of boundary value problems for ordinary differential equations, the parametrization method is used. [15-19] Application of this approach allowed to establish the coefficients of the unique solvability of the semiperidic problem for pseudhyperbolic equations and to propose new algorithms for finding the approximate solution.

The function
$$u(x, y) \in C(\Omega, \mathbb{R}^n)$$
, with partial derivatives $\frac{\partial^2 u(x, y)}{\partial y^2} \in C(\Omega, \mathbb{R}^n)$, $\frac{\partial^2 u(x, y)}{\partial x^2} \in C(\Omega, \mathbb{R}^n)$,

 $\frac{\partial^3 u(x, y)}{\partial x^2 \partial y} \in C(\Omega, \mathbb{R}^n) \text{ is called the classical solution to the problem (1)-(4), if it satisfies the system (1) with all <math>(x, y) \in \Omega$, and boundary conditions(2)–(4).

2. Main result

To find the solution, we introduce the function $g(x, y) = \frac{\partial u(x, y)}{\partial x}$, $w(x, y) = \frac{\partial^2 u(x, y)}{\partial y^2}$ and the problem (1)-(4) we write in the form

$$\frac{\partial^2 g}{\partial x \partial y} = A(x, y) \frac{\partial g}{\partial x} + C(x, y)w + f(x, y), \quad (x, y) \in \Omega,$$
(5)

$$g(x,0) = g(x,Y), \quad x \in [0,X],$$
 (6)

$$g(0, y) = \psi(y), \quad y \in [0, Y],$$
(7)

$$u(x,y) = \varphi(y) + \int_{0}^{x} g(\xi_{1},y)d\xi_{1},$$
(8)

$$w(x,y) = \varphi''(y) + \int_0^x \frac{\partial^2 g(\xi_1,y)}{\partial y^2} d\xi_1.$$
(9)

We reintroduce the notation $z(x, y) = \frac{\partial g(x, y)}{\partial x}$ and the problem (5)-(9)reduced to a family of periodic boundary value problems for a system of ordinary differential equations of the form

$$\frac{\partial z}{\partial y} = A(x, y)z + C(x, y)w + f(x, y), \quad (x, y) \in \Omega,$$
(10)

$$z(x,0) = z(x,Y), \quad x \in [0,X],$$
(11)

$$g(x,y) = \psi(y) + \int_{0}^{x} z(\xi,y)d\xi, \quad y \in [0,Y],$$
(12)

$$u(x,y) = \varphi(y) + \psi(y)x + \int_{0}^{x} \int_{0}^{\xi} z(\xi_{1},y)d\xi_{1}d\xi,$$
(13)

$$w(x,y) = \varphi''(y) + \psi''(y)x + \int_{0}^{x} \int_{0}^{\xi} \frac{\partial^2 z(\xi_1, y)}{\partial y^2} d\xi_1 d\xi,$$
(14)

To solve problem (10)-(14) for the step h > 0: Nh = Y we partition $[0, Y) = \bigcup_{r=1}^{N} [(r-1)h, rh), N = 1, 2, ... [2]$. In this case, the area Ω is divided into N parts. By $u_r(x, y), \omega_r(x, y), v_r(x, y), g_r(x, y)$ we denote, respectively, the restrictions of the functions v(x, y), g(x, y), u(x, y), w(x, y) on $\Omega_r = [0, X] \times [(r-1)h, rh), r = \overline{1, N}$. By $\lambda_r(x)$ we denote the value of the function $z_r(x, y)$ at y = (r - 1)h, i.e. $\lambda_r(x) = z_r(x, (r - 1)h)$ and denote $v_r(x, y) = z_r(x, y) - \lambda_r(x), r = \overline{1, N}$. We obtain an equivalent boundary value problem for the unknown functions $\lambda_r(x)$:

$$\frac{\partial v_r}{\partial y} = A(x, y)v_r + A(x, y)\lambda_r(x) + C(x, y)w_r + f(x, y), \quad (x, y) \in \Omega_r, \quad r = \overline{1, N},$$
(15)

$$v_r(x, (r-1)h) = 0, \quad x \in [0, X], \quad r = \overline{1, N},$$
(16)

$$\lambda_1(x) - \lambda_N(x) - \lim_{y \to Y - 0} v_N(x, y) = 0, \quad x \in [0, X],$$
(17)

$$\lambda_s(x) + \lim_{t \to sh \to 0} v_s(x, y) - \lambda_{s+1}(x) = 0, \quad x \in [0, X], \quad s = \overline{1, N - 1}.$$
(18)

$$g(x,y) = \psi(y) + \int_{0}^{x} v_r(\xi,y)d\xi + \int_{0}^{x} \lambda_r(\xi,y)d\xi,$$
(19)

$$u_r(x,y) = \varphi(y) + \psi(y)x + \int_0^x \int_0^{\xi} v_r(\xi_1,y)d\xi_1d\xi + \int_0^x \int_0^{\xi} \lambda_r(\xi_1)d\xi_1d\xi,$$
(20)

927

N.T. Orumbayeva, T.D. Tokmagambetova / Filomat 37:3 (2023), 925-933

$$w_r(x,y) = \varphi''(y) + \psi''(y)x + \int_0^x \int_0^{\xi} \frac{\partial^2 v_r(\xi_1,y)}{\partial y^2} d\xi_1 d\xi,$$
(21)

where $(x, y) \in \Omega_r$, $r = \overline{1, N}$, (18)- the condition of gluing functions in the internal lines of the partition.

Problem (15),(16) for fixed $\lambda_r(x)$, $w_r(x, y)$ is a one-parameter family of Cauchy problems for systems of ordinary differential equations, where $x \in [0, Y]$, which is equivalent to the integral equation

$$v_r(x,y) = \int_{(r-1)h}^{y} A(x,\tau)v_r(x,\tau)d\tau + \int_{(r-1)h}^{y} A(x,\tau)d\tau \cdot \lambda_r(x) + \int_{(r-1)h}^{y} (C(x,\tau)w_r + f(x,\tau))d\tau,$$
(22)

Instead of $v_r(x, \tau)$ we substitute the corresponding right-hand side of (22) and repeating this process v (v = 1, 2, ...) times we obtain

$$v_r(x,y) = D_{vr}(x,y)\lambda_r(x) + F_{vr}(x,y,w_r) + G_{vr}(x,y,v_r), \quad r = \overline{1,N},$$
(23)

where

$$\begin{aligned} D_{\nu r}(x,y) &= \sum_{j=0}^{\nu-1} \int_{(r-1)h}^{y} A(x,\tau_1) d\tau_1 \dots \int_{(r-1)h}^{\tau_j} A(x,\tau_{j+1}) d\tau_{j+1} \dots d\tau_1, \\ F_{\nu r}(x,y,w_r) &= \int_{(r-1)h}^{y} \left[C(x,\tau_1) w_r(x,\tau_1) + f(x,\tau_1) \right] d\tau_1 \\ &+ \sum_{j=1}^{\nu-1} \int_{(r-1)h}^{y} A(x,\tau_1) \dots \int_{(r-1)h}^{\tau_{j-1}} A(x,\tau_j) \int_{(r-1)h}^{\tau_j} \left[C(x,\tau_{j+1}) w_r(x,\tau_{j+1}) + f(x,\tau_{j+1}) \right] d\tau_{j+1} d\tau_j \dots d\tau_1, \end{aligned}$$

$$G_{\nu r}(x, y, v_r) = \int_{(r-1)h}^{y} A(x, \tau_1) \dots \int_{(r-1)h}^{\tau_{\nu-2}} A(x, \tau_{\nu-1}) \int_{(r-1)h}^{\tau_{\nu-1}} A(x, \tau_{\nu}) v_r(x, \tau_{\nu}) d\tau_{\nu} d\tau_{\nu-1} \dots d\tau_1,$$

 $\tau_0 = y, r = \overline{1, N}$. Passing to the limit as $y \to rh - 0$ in (23) we have

$$\lim_{y \to rh-0} v_r(x, y) = D_{vr}(x, rh)\lambda_r(x) + F_{vr}(x, rh, w_r) + G_{vr}(x, rh, v_r),$$

 $x \in [0, \omega], r = \overline{1, N}$. Substituting in (17),(18) instead of $\lim_{y \to rh-0} v_r(x, y), r = \overline{1, N}$, the corresponding to them right-hand sides for the unknown functions $\lambda_r(x), r = \overline{1, N}$, we obtain the system of functional equations:

$$Q_{\nu}(x,h)\lambda(x) = -F_{\nu}(x,h,w) - G_{\nu}(x,h,v),$$
(24)

928

where

$$Q_{\nu}(x,h) = \begin{bmatrix} I & 0 & \dots & 0 & -[I+D_{\nu N}(x,Nh)] \\ I+D_{\nu 1}(x,h) & -I & \dots & 0 & 0 \\ 0 & I+D_{\nu 2}(x,2h) & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & I+D_{\nu,N-1}(x,(N-1)h) & -I \end{bmatrix},$$

$$F_{\nu}(x,h,w) = (-F_{\nu N}(x,Nh,w_N), F_{\nu 1}(x,h,w_1), \dots, F_{\nu,N-1}(x,(N-1)h,w_{N-1}))$$

$$G_{\nu}(x,h,v) = (-G_{\nu N}(x,Nh,v_N), G_{\nu 1}(x,h,v_1), \dots, G_{\nu,N-1}(x,(N-1)h,v_{N-1})),$$

and *I* is the unit matrix of dimension of *n*.

For finding a system of three functions { $\lambda_r(x)$, $v_r(x, y)$, $w_r(x, y)$, $r = \overline{1, N}$, we have a closed system consisting of equations (24), (23) and (21).

Assuming the invertibility of the matrix $Q_{\nu}(x, h)$ for all $x \in [0, X]$, from equation (24), where $v_r(x, y) = 0$, $w_r(x, y) = \varphi''(t)$, we find $\lambda^{(0)}(x) = (\lambda_1^{(0)}(x), \lambda_2^{(0)}(x), \dots, \lambda_N^{(0)}(x))'$:

$$\lambda^{(0)}(x) = -[Q_{\nu}(x,h)]^{-1} \{ F_{\nu}(x,h,\ddot{\varphi}) + G_{\nu}(x,h,0) \}.$$

Using equation (23), at $\lambda_r(x) = \lambda_r^{(0)}(x)$ we find the functions $\{v_r^{(0)}(x, y)\}, r = \overline{1, N}$, i.e.

$$v_r^{(0)}(x,y) = D_{\nu r}(x,y)\lambda_r^{(0)}(x) + F_{\nu r}(x,y,\dot{\phi}) + G_{\nu r}(x,y,0)$$

. The functions $g_r^{(0)}(x, y), u_r^{(0)}(x, y), w_r^{(0)}(x, y), r = \overline{1, N}$, are defined from the relations

$$g_r^{(0)}(x,y) = \psi(y) + \int_0^x v_r^{(0)}(\xi,y)d\xi + \int_0^x \lambda_r^{(0)}(\xi,y)d\xi,$$

$$u_r^{(0)}(x,y) = \varphi(y) + \psi(y)x + \int_0^x \int_0^{\xi} v_r^{(0)}(\xi_1,y)d\xi_1d\xi + \int_0^x \int_0^{\xi} \lambda_r^{(0)}(\xi_1)d\xi_1d\xi$$

$$w_r^{(0)}(x,y) = \varphi''(y) + \psi''(y)x + \int_0^x \int_0^\xi \frac{\partial v_r^{(0)}(\xi_1,y)}{\partial y^2} d\xi_1 d\xi_2$$

where $(x, y) \in \Omega_r$, $r = \overline{1, N}$.

For the initial approximation of problem (15)-(21) we take the system $\{\lambda_r^{(0)}(x), v_r^{(0)}(x, t), w_r^{(0)}(x, y), r = \overline{1, N}\}$ and construct successive approximations on the following algorithm :

Step 1. A) Assuming that $w_r(x, y) = w_r^{(0)}(x, y), r = \overline{1, N}$, we find the first approximations of $\lambda_r(x), \widetilde{v_r}(x, y), r = \overline{1, N}$, by solving the problem (15)-(18). Taking $\lambda_r^{(1,0)}(x) = \lambda_r^{(0)}(x), \quad v_r^{(1,0)}(x, y) = v_r^{(0)}(x, y)$, we find the system of couples $\{\lambda_r^{(1)}(x), v_r^{(1)}(x, y)\}, r = \overline{1, N}$, as the limit of the sequence $\lambda_r^{(1,m)}(x), v_r^{(1,m)}(x, y)$, defined in the following way:

Step 1.1. Assuming the invertibility of the matrix $Q_{\nu}(x, h), x \in [0, X]$, from equation (24), where $v_r(x, y) = v_r^{(1,0)}(x, y)$, we find $\lambda^{(1,1)}(x) = (\lambda_1^{(1,1)}(x), \lambda_2^{(1,1)}(x), \dots, \lambda_N^{(1,1)}(x))'$:

$$\lambda^{(1,1)}(x) = -[Q_{\nu}(x,h)]^{-1} \{ F_{\nu}(x,h,w^{(0)} + G_{\nu}(x,h,v^{(1,0)}) \}.$$

Substituting the found $\lambda_r^{(1,1)}(x)$, $r = \overline{1, N}$, in (23) we find

$$v_r^{(1,1)}(x,y) = D_{vr}(x,y)\lambda_r^{(1,1)}(x) + F_{vr}(x,y,w^{(0)}) + G_{vr}(x,y,v^{(1,0)}).$$

Step 1.2. From equation (24), where $v_r(x, y) = v_r^{(1,1)}(x, y)$, we define

$$\lambda^{(1,2)}(x) = -[Q_{\nu}(x,h)]^{-1} \{ F_{\nu}(x,h,w^{(0)}) + G_{\nu}(x,h,v^{(1,1)}) \}.$$

Using as expression (20) again, we find the functions $\{v_r^{(1,2)}(x, y)\}, r = \overline{1, N},$

$$v_r^{(1,2)}(x,y) = D_{\nu r}(x,y)\lambda_r^{(1,2)}(x) + F_{\nu r}(x,y,w^{(0)}) + G_{\nu r}(x,y,v^{(1,1)})$$

On step (1, m) we obtain the system of couples $\{\lambda_r^{(1,m)}(x), v_r^{(1,m)}(x, y)\}, r = \overline{1, N}$. Suppose that the solution of problem (15)-(18) is a sequence of systems of couples

$$g_r^{(1,m)}(x,y)\}, \{\lambda_r^{(1,m)}(x), v_r^{(1,m)}(x,y)\}$$

which are defined for $x \in [0, X]$, $(x, y) \in \Omega_r$ respectively, and converge as $m \to \infty$ to continuous functions $\lambda_r^{(1)}(x), v_r^{(1)}(x, y), r = \overline{1, N}$.

B) The functions $g_r^{(1)}(x, y), w_r^{(1)}(x, y), u_r^{(1)}(x, y), r = \overline{1, N}$, are defined from the relations

$$g_r^{(1)}(x,y) = \psi(y) + \int_0^x v_r^{(1)}(\xi,y)d\xi + \int_0^x \lambda_r^{(1)}(\xi,y)d\xi,$$
$$u_r^{(1)}(x,y) = \varphi(y) + \psi(y)x + \int_0^x \int_0^\xi v_r^{(1)}(\xi_1,y)d\xi_1d\xi + \int_0^x \int_0^\xi \lambda_r^{(1)}(\xi_1)d\xi_1d\xi,$$

$$w_r^{(1)}(x,y) = \varphi''(y) + \psi''(y)x + \int_0^x \int_0^\xi \frac{\partial v_r^{(1)}(\xi_1,y)}{\partial y} d\xi_1 d\xi_1$$

where $(x, y) \in \Omega_r, r = \overline{1, N}$.

Step 2. A) Assuming that $w_r(x, y) = w_r^{(1)}(x, y), r = \overline{1, N}$, we find the second approximations of $\lambda_r(x), v_r(x, y), r = \overline{1, N}$, by solving problem (15)-(18). Taking

$$\lambda_r^{(2,0)}(x) = \lambda_r^{(1)}(x), \quad v_r^{(2,0)}(x,y) = v_r^{(1)}(x,y),$$

we find the system of couples $\{\lambda_r^{(2)}(x), v_r^{(2)}(x, y)\}, r = \overline{1, N}$, as the limit of the sequence $\lambda_r^{(2,m)}(x), v_r^{(2,m)}(x, y)$, defined in the following way:

Step 2.1. Assuming the invertibility of the matrix $Q_{\nu}(x,h)$ from equation (24), where $v_r(x,y) = v_r^{(2,0)}(x,y)$, we find $\lambda^{(2,1)}(x) = (\lambda_1^{(2,1)}(x), \lambda_2^{(2,1)}(x), ..., \lambda_N^{(2,1)}(x))'$:

$$\lambda^{(2,1)}(x) = -[Q_{\nu}(x,h)]^{-1} \{ F_{\nu}(x,h,w^{(1)}) + G_{\nu}(x,h,v^{(2,0)}) \}.$$

Substituting the found $\lambda_r^{(2,1)}(x)$, $r = \overline{1, N}$, in (23) we find

$$v_r^{(2,1)}(x,y) = D_{vr}(x,y)\lambda_r^{(2,1)}(x) + F_{vr}(x,y,w^{(1)}) + G_{vr}(x,y,v^{(2,0)}).$$

930

Step 2.2. From equation(24), where $v_r(x, y) = v_r^{(2,1)}(x, y)$, we define

$$\lambda^{(2,2)}(x) = -[Q_{\nu}(x,h)]^{-1} \{ F_{\nu}(x,h,w^{(1)}) + G_{\nu}(x,h,v^{(2,1)}) \}.$$

Using the expression (23), we find the functions $\{v_r^{(2,2)}(x, y)\}, r = \overline{1, N}$:

$$v_r^{(2,2)}(x,y) = D_{\nu r}(x,y)\lambda_r^{(2,2)}(x) + F_{\nu r}(x,y,w^{(1)}) + G_{\nu r}(x,y,v^{(2,1)}).$$

On step (2, *m*) we obtain the system of couples $\{\lambda_r^{(2,m)}(x), v_r^{(2,m)}(x, y)\}$, where $(x, y) \in \Omega_r, r = \overline{1, N}$.

Suppose that the solution of problem (15)-(18) is a sequence of systems of couples $\{\lambda_r^{(2,m)}(x), v_r^{(2,m)}(x, y)\}$ which as $m \to \infty$ converges to $\{\lambda_r^{(2)}(x), v_r^{(2)}(x, y)\}, r = \overline{1, N}$. B) The functions $g_r^{(2)}(x, y), u_r^{(2)}(x, y), w_r^{(2)}(x, y), r = \overline{1, N}$, are defined from the relations

$$g_r^{(2)}(x,y) = \psi(y) + \int_0^x v_r^{(2)}(\xi,y)d\xi + \int_0^x \lambda_r^{(2)}(\xi,y)d\xi,$$

$$w_r^{(2)}(x,y) = \varphi''(y) + \psi''(y)x + \int_0^x \int_0^\xi \frac{\partial v_r^{(2)}(\xi_1,y)}{\partial y} d\xi_1 d\xi_2$$

where $(x, y) \in \Omega_r$, $r = \overline{1, N}$. Continuing the process, at the *k*-th step we obtain the system $\{\lambda_r^{(k)}(x), v_r^{(k)}(x, y), v_r^{(k$ $w_r^{(k)}(x, y), u_r^{(k)}(x, y)\}, g_r^{(k)}(x, y)\}, r = \overline{1, N}.$

The conditions of the following statement ensure the feasibility and convergence of the proposed algorithm, as well as the unique solvability of problem (15)-(21).

Theorem 1. Let for some $0 \le \mu < 1$, h > 0: $Nh = Y, N = 1, 2, ..., and v, v \in \mathbb{N}$, $(nN \times nN)$ the matrix $Q_v(x, h)$ *be invertible for all* $x \in [0, X]$ *let the following inequalities be satisfied*

1)
$$\|[Q_{\nu}(x,h)]^{-1}\| \le \gamma_{\nu}(x,h); 2) q_{\nu}(x,h) = \left\{1 + \gamma_{\nu}(x,h) \sum_{j=1}^{\nu} \frac{(\alpha(x)h)^{j}}{j!}\right\} \frac{(\alpha(x)h)^{\nu}}{\nu!} \le \mu.$$

Then there exists a unique solution (λ_r^*, v_r^*) to problem (15)-(21) and the following estimates are valid

$$\max\left\{\max_{r=\overline{1,N}} \|\lambda_{r}^{*}(x) - \lambda_{r}^{(k)}(x)\| + \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh)} \|v_{r}^{*}(x,y) - v_{r}^{(k)}(x,y)\|, \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh)} \|\frac{\partial^{2}v_{r}^{*}(x,y)}{\partial y^{2}} - \frac{\partial^{2}v_{r}^{(k)}(x,y)}{\partial y^{2}}\right\|,$$

$$\int_{0}^{x} \left(\max_{r=\overline{1,N}} \|\lambda_{r}^{*}(x_{1}) - \lambda_{r}^{(k)}(x_{1})\| + \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh)} \|v_{r}^{*}(x_{1},y) - v_{r}^{(k)}(x_{1},y)\|\right) dx_{1}\right\} \leq x$$

$$\leq \frac{\beta_{\nu}(x,h)\int_{0}\beta_{\nu}(\xi,h)d\xi}{(k-1)!} \left(e^{\int_{0}^{x}\beta_{\nu}(\xi,h)d\xi}\int_{0}^{x}\max\left\{\chi_{\nu}(\xi,h),\phi_{\nu}(\xi,h)\right\}d\xi\max\left\{\left[\max_{y\in[0,T]}\|\varphi''(y)\|+\|f\|_{0}\right],\left[\max_{t\in[0,T]}\|\varphi'''(y)\|+\|f'\|_{0}\right]\right\},$$

 $\max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh]} \|w_r^*(x,y) - w_r^{(k)}(x,y)\| \leq \int_0^\infty \max\left\{\max_{r=\overline{1,N}} \|\lambda_r^*(\xi) - \lambda_r^{(k)}(\xi)\| + \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh]} \|v_r^*(\xi,t) - v_r^{(k)}(\xi,y)\|, w_r^{(k)}(\xi,y)\| \leq \int_0^\infty \max\left\{\max_{r=\overline{1,N}} \|\lambda_r^*(\xi) - \lambda_r^{(k)}(\xi)\| + \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh]} \|v_r^*(\xi,t) - v_r^{(k)}(\xi,y)\| + \max_{r=\overline{1,N}} \sup_{y \in [(r-1)h,rh]} \|v_r^*(\xi,$

N.T. Orumbayeva, T.D. Tokmagambetova / Filomat 37:3 (2023), 925–933

$$\begin{split} \max_{r=1,N} \sup_{y \in [(r-1)h,rh)} \left\| \frac{\partial^2 v_r^*(\xi,y)}{\partial y^2} - \frac{\partial^2 v_r^{(k)}(\xi,y)}{\partial y^2} \right\| \right\} d\xi, \quad k = 1, 2, \dots \\ where \ \alpha(x) &= \max_{y \in [0,T]} \|A(x,y)\|, \sigma(x) = \max_{y \in [0,T]} \|C(x,y)\|, \delta_{\nu}(x,h) = \left\{ 1 + \gamma_{\nu}(x,h) \sum_{j=1}^{\nu} \frac{(\alpha(x)h)^j}{j!} \right\} h \sum_{j=0}^{\nu-1} \frac{(\alpha(x)h)^j}{j!} \\ \theta_{\nu}(x,h) &= \left\{ 1 + \gamma_{\nu}(x,h) \sum_{j=0}^{\nu} \frac{(\alpha(x)h)^j}{j!} \right\} h \sum_{j=0}^{\nu-1} \frac{(\alpha(x)h)^j}{j!}, \\ \rho_{\nu}(x,h) &= \int_{0}^{x} \int_{0}^{\xi} \left[\alpha'(\xi_1) \max\{\sigma(\xi_1), 1\} \gamma_{\nu}(\xi_1,h)h \sum_{j=0}^{\nu-1} \frac{(\alpha(x)h)^j}{j!} + \max\{\sigma'(\xi_1), 1\} \right] d\xi_1 d\xi \\ \beta_{\nu}(x,h) &= \max\left\{ \left[\frac{\delta_{\nu}(x,h)\sigma(x)}{1-q_{\nu}(x,h)} + \left[\frac{\delta_{\nu}(x,h)}{1-q_{\nu}(x,h)} \frac{(\alpha(x)h)^{\nu}}{\nu!} + h \sum_{j=0}^{\nu-1} \frac{(\alpha(x)h)^j}{j!} \right] \gamma_{\nu}(x,h) \right] \sigma(x), \\ \int_{0}^{x} \left[\alpha(\xi) \left(1 + \delta_{\nu}(\xi,h) \right) + 1 \right] (\xi)\sigma(\xi) d\xi \right\}, \\ \chi_{\nu}(x,h) &= \left[\frac{\delta_{\nu}(x,h)}{1-q_{\nu}(x,h)} \left[1 + \gamma_{\nu}(x,h) \frac{(\alpha(x)h)^{\nu}}{\nu!} \right] + \gamma_{\nu}(x,h) d\nu(x,h) \right] + \gamma_{\nu}(x,h) \frac{(\alpha(x)h)^{\nu}}{j!} \right] \delta_{\nu}(x,h), \\ \varphi_{\nu}(x,h) &= \int_{0}^{x} \int_{0}^{\xi} \left\{ \alpha(\xi_1)(1 + \delta_{\nu}(\xi_1,h)) + 1 \right\} \sigma(\xi_1)\rho_{\nu}(\xi_1,h) d\xi_1 d\xi. \end{split}$$

The proof of Theorem 1 is similar to the proof of Theorem 1 from [1]. By virtue of the equivalence of problems (1)-(4) and (15)-(21) from Theorem 1 follows

Theorem 2. Let the assumptions of Theorem 1 be satisfied. Then problem (1)-(4) as a unique solution $u^*(x, y)$ and the evaluation is performed.

 \leq

Acknowledgement: We thank the referee for some general advices, which have improved the final version of the paper. The first author was supported by Ministry of Education and Science of the Republic of Kazakhstan Grant AP09259780.

References

- T. D. Djuraev and J. Popelek, On classification and reduction to the canonical form with partial derivatives of the third order. Differential Equations, 10 (1991), 1734-1745.
- [2] O. S. Zikirov, Local and nonlocal boundary value problems for hyperbolic equations of the third order. Contemporary mathematics and its applicationser, 68 (2011), 101-120.
- [3] V. A. Sevastyanov, Riemann's method for a three-dimensional hyperbolic equation of the third order. Bulletin of higher educational institutions, 5 (1997), 69-73.
- [4] A. I. Kozhanov and N. R. Pinigina. A mixed problem for some classes of nonlinear third-order equations, Math. USSR-Sb.,46:4 (1983), 507-525.
- [5] A. I. Kozhanov and N. R. Pinigina. Boundary-Value Problems for Some Higher-Order Nonclassical Differential Equations. Math. Notes, 101:3 (2017), 467–474.
- [6] R. Kurant, Partial Differential Equations. World, 1964, 831.
- [7] K. Trusdell, Initial Course in Rational Continuum Mechanics. World, 1975, 592.
- [8] B. B. Coleman, F. J. Daffin and V. J. Mizel. Instability, uniqueness and nonexistence theorems for the equation Ut = uxx uxtx on a strip. Arch. RationalMech. Anal.. 19 (1965), 100-116
- [9] A. P. Oskolkov. On some model nonstationary systems in the theory of non-Newtonian fluids. Proceedings of the Mathematical Institute of the USSR Academy of Sciences, 127 (1975), 32-57.
- [10] A. N. Gerasimov. Elastic aftereffect and internal friction. Applied Mathematics and Mechanics, 4 (1937), 493-536.
- [11] A. N. Gerasimov. Foundations of the theory of deformation of elastic-viscous bodies. Applied Mathematics and Mechanics, 1938
- [12] A. Y. Ishlinsky. Longitudinal vibrations in the presence of a linear aftereffect and relaxation law. Applied Mathematics and Mechanics, 1 (1940), 79-92.
- [13] M. B. Keldysh. Selected Works. Mechanics. The science, 1985, 568.
- [14] V. I. Korzyuk, O. A. Konopelko, E. S. Cheb. Boundary value problems for fourth-order equations of hyperbolic and mixed types. Contemporary mathematics. Fundamental directions, 36 (2010), 87-111.
- [15] D. S. Dzhumabaev, Criteria for the unique solvability of a linear boundary-value problem for an ordinary differential equation, Zh. Vychisl. Mat. Mat. Fiz., 29:1 (1989), 50–66.
- [16] N. T. Orumbayeva. On solvability of non-linear semi-periodic boundary-value problem for system of hyperbolic equations. Russian Mathematic, 9 (2016), 23-37. DOI: 10.3103/S1066369X16090036.
- [17] A. T. Assanova, N. B. Iskakova and N. T. Orumbayeva. On the well-posedness of periodic problems for the system of hyperbolicequations with finite time delay, Mathematical Methods in the Applied Sciences 4(2) (2020) 881–902. DOI: 10.1002/mma.5970.
- [18] N. T. Orumbayeva and A.B. Keldibekova. On one solution of a periodic boundary-valueproblem for a third-order pseudoparabolic equation. Lobachevskii Journal of Mathematics, 41 (2020), 1857–1865. DOI: 10.1134/S1995080220090218.
- [19] N. T. Orumbayeva and A. B. Keldibekova. On the solvability of the duo-periodic problem for the hyperbolic equation system with a mixed derivative. Bulletinof the Karaganda University, 1:93 (2019), 59–71. DOI: 10.31489/2019M1/59-71