



F –geodesics on the second order tangent bundle over a Riemannian manifold

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Abstract. Let (M, g) be a Riemannian manifold and T^2M be its second order tangent bundle. In this paper, we deal with certain characterizations of F –geodesics (which generalize both classical geodesics and magnetic curves) on the second order tangent bundle T^2M and the hypersurface $T^2_{1,1}M$ with respect to some natural metrics.

1. Introduction

Magnetic curves represent, in physics, the trajectories of the charged particles moving on a Riemannian manifold under the action of the magnetic fields. A magnetic field F on a Riemannian manifold (M, g) is a closed 2–form and the Lorentz force associated to F is a $(1, 1)$ –tensor field ρ such that

$$F(X, Y) = g(\rho X, Y)$$

for all vector fields X, Y on M . A magnetic trajectory in such a magnetic field is thus modeled by a second order differential equation, that is,

$$\nabla_{\dot{\gamma}} \dot{\gamma} = \rho \dot{\gamma},$$

usually known as the Lorentz equation. Such curves are sometimes called also magnetic geodesics since the Lorentz equation generalizes the equation of geodesics under arc-length parametrization, namely, $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$. Here, ∇ denotes the Levi-Civita connection of the Riemannian metric g .

A smooth curve γ on a Riemannian manifold (M, g) endowed with a $(1, 1)$ –tensor field F and with Levi-Civita connection ∇ is called an F –geodesic if γ satisfies

$$\nabla_{\dot{\gamma}} \dot{\gamma} = F \dot{\gamma}.$$

F –geodesics are strictly related to F –planar curves and extended magnetic curves and hence, geodesics. Note that the notion of F –geodesic is slightly different from F –planar curve (see [12]). Inspired by the

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Lorentz force, the electro-magnetic tensor field, as well as some special forces involved in the Euler-Lagrange equations from Lagrangian mechanics, Bejan and Druță-Romaniuc [2] defined F -geodesics on a manifold with a linear connection. They presented several examples of F -geodesics; for instance, they constructed F -geodesics on the tangent bundle of a manifold by using lifts. Also, they characterized F -geodesics according to some special connections such as Vranceanu connection on foliated manifolds and adapted connections on almost contact manifolds. Finally, they found conditions for a pair of symmetric connections to have the same system of F -geodesics. In this paper, we deal with certain characterizations of F -geodesics on the second order tangent bundle T^2M and the hypersurface $T^2_{1,1}M$.

1.1. Whitney tangent fiber bundle $TM \oplus TM$

Let M be an n -dimensional Riemannian manifold with a Riemannian metric g and TM be its tangent bundle denoted by $\pi : TM \rightarrow M$. We refer to [6, 16] for all the necessary background for the tangent bundle. The Whitney tangent fiber bundle $TM \oplus TM$ is defined by

$$TM \oplus TM = \left\{ (u, \omega) \in TM \times TM; \quad \pi(u) = \pi(\omega) \right\} = \bigcup_{x \in M} T_x M \times T_x M,$$

where π_{\oplus} is denoted by

$$\begin{aligned} \pi_{\oplus} : TM \oplus TM &\rightarrow M \\ (u, \omega) &\mapsto \pi_{\oplus}(u, \omega) = \pi(u) = \pi(\omega). \end{aligned}$$

A local chart $(U, \varphi) = (U, x^i)$ on M induces a chart $(\pi^{-1}(U), \bar{\varphi}) = (\pi^{-1}(U), x^i, y^j)$ on TM and $(\pi_{\oplus}^{-1}(U), \bar{\varphi}) = (\pi_{\oplus}^{-1}(U), x^i, y^j, z^i)$ on $TM \oplus TM$ such

$$\bar{\varphi}(x, u, \omega) = (\varphi(x), \bar{\varphi}_x(u), \bar{\varphi}_x(\omega)) = (\varphi(x), y, z).$$

Let \tilde{X}, \tilde{Y} be vector fields on TM . Then (\tilde{X}, \tilde{Y}) is a vector field on $TM \oplus TM$ if and only if

$$d\pi(\tilde{X}) = d\pi(\tilde{Y}).$$

Relative to the chart $(\pi_{\oplus}^{-1}(U), \bar{\varphi}) = (\pi_{\oplus}^{-1}(U), x^i, y^j, z^i)$, the local frame vector fields given in [5] are

$$\begin{aligned} \frac{\partial}{\partial x^i} &= \left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^i} \right), \\ \frac{\partial}{\partial y^i} &= \left(\frac{\partial}{\partial y^i}, 0 \right), \\ \frac{\partial}{\partial z^i} &= \left(0, \frac{\partial}{\partial z^i} \right). \end{aligned}$$

For any vector field X on M and $f \in C^{\infty}(M)$, we have

$$\begin{aligned} (X^V, 0) &= X^i \frac{\partial}{\partial y^i}, \quad (0, X^V) = X^i \frac{\partial}{\partial z^i}, \\ (X^H, X^H) &= X^i \frac{\partial}{\partial x^i} - \Gamma_{ij}^k X^i y^j \frac{\partial}{\partial y^k} - \Gamma_{ij}^k X^i z^j \frac{\partial}{\partial z^k}, \\ (X^V, 0)(f \circ \pi) &= (0, X^V)(f \circ \pi) = 0, \\ (X^H, X^H)(f \circ \pi) &= X(f) \circ \pi. \end{aligned}$$

If (M, g) is a Riemannian manifold, ∇ its Levi-Civita connection and $\gamma_1, \gamma_2 : 0 \in I \subset \mathbb{R} \rightarrow M$ are two smooth curves, then we have

$$[\gamma_1 \sim \gamma_2] \Leftrightarrow \left[\gamma_1(0) = \gamma_2(0), \quad \frac{d\gamma_1}{dt}(0) = \frac{d\gamma_2}{dt}(0) \quad \text{and} \quad \frac{d^2\gamma_1}{dt^2}(0) = \frac{d^2\gamma_2}{dt^2}(0) \right]$$

$$j_0^2\gamma = \{\bar{\gamma}; \bar{\gamma} \sim \gamma\}.$$

The second order tangent bundle is the natural bundle of 2–jets of differentiable curves defined by

$$T^2M = \{j_0^2\gamma; \gamma : I \rightarrow M, \text{ is a smooth curve at } 0 \in \mathbb{R}\}.$$

The canonical projection P on T^2M is given by

$$\begin{aligned} P : T^2M &\rightarrow M \\ j_0^2\gamma &\mapsto \gamma(0). \end{aligned}$$

A local chart (U, φ) induces a chart $(P^{-1}(U), \phi)$ on T^2M given by

$$\phi(j_0^2\gamma) = (\varphi(\gamma(0)), \frac{d\varphi \circ \gamma}{dt}(0), \frac{d^2\varphi \circ \gamma}{dt^2}(0)).$$

Proposition 1.1. [5] *If $TM \oplus TM$ denotes the Whitney sum, then*

$$S : T^2M \rightarrow TM \oplus TM, \quad j_0^2\gamma \mapsto (\dot{\gamma}(0), (\nabla_{\dot{\gamma}(0)}\dot{\gamma})(0))$$

is a diffeomorphism of natural bundles.

In the induced coordinates, we have

$$S : (x^i, y^j, z^k) \mapsto (x^i, y^j, z^k + y^j y^k \Gamma_{jk}^i).$$

Proposition 1.2. [5] *Let T^2M be a second order tangent bundle endowed with the vectorial structure induced by the diffeomorphism S . For any section $\sigma \in \Gamma(T^2M)$ ($\Gamma(T^2M)$ is the set of all sections from M onto T^2M), if we define two vector fields on M by*

$$X_\sigma = P_1 \circ S \circ \sigma, \quad Y_\sigma = P_2 \circ S \circ \sigma,$$

then $\sigma = S^{-1}(X_\sigma, Y_\sigma)$, where P_1 and P_2 denote the first and the second projection from $TM \oplus TM$ onto TM .

1.2. Lifts to T^2M

If (U, φ) is a local chart on M , then the diffeomorphism S induces a local chart $((\pi_\oplus \circ S)^{-1}(U), \bar{\varphi} \circ S)$ on T^2M such that

$$\frac{\partial}{\partial x^i} = S_*^{-1} \left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^i} \right), \quad \frac{\partial}{\partial y^j} = S_*^{-1} \left(\frac{\partial}{\partial y^j}, 0 \right), \quad \frac{\partial}{\partial z^k} = S_*^{-1} \left(0, \frac{\partial}{\partial z^k} \right), \tag{1}$$

where $\pi_\oplus : (u, \omega) \in TM \oplus TM \mapsto \pi(u) = \pi(\omega) = x$.

Definition 1.3. [3, 4] *Let (M, g) be a Riemannian manifold, X and F respectively be a vector field and a $(1, 1)$ –tensor field on M . For $\lambda = 0, 1, 2$, the λ -lift of X to T^2M is defined by*

$$\begin{aligned} X^{(0)} &= S_*^{-1}(X^H, X^H), \\ X^{(1)} &= S_*^{-1}(X^V, 0), \\ X^{(2)} &= S_*^{-1}(0, X^V), \\ F^{(0)}(X^{(\lambda)}) &= (FX)^{(\lambda)}, \quad (\lambda = 0, 1, 2) \\ F^{(\lambda)}(X^{(0)}) &= (FX)^{(\lambda)}, \quad (\lambda = 1, 2) \\ F^{(1)}(X^{(\lambda)}) &= 0 = F^{(2)}(X^{(\lambda)}), \quad (\lambda = 1, 2). \end{aligned}$$

From the formulae (1) and Definition 1.3, we obtain the following lemma.

Lemma 1.4. For any vector field X on M and any smooth function $f \in C^\infty(M)$, we have

$$\begin{aligned} X^{(1)} &= X^i \frac{\partial}{\partial y^i}, \\ X^{(2)} &= X^i \frac{\partial}{\partial z^i}, \\ X^{(0)} &= X^i \frac{\partial}{\partial x^i} - \Gamma_{ij}^k X^i y^j \frac{\partial}{\partial y^k} - \Gamma_{ij}^k X^i z^j \frac{\partial}{\partial z^k}, \\ X^{(1)}(f \circ \pi) &= X^{(2)}(f \circ \pi) = 0, \\ X^{(0)}(f \circ \pi) &= X(f) \circ \pi. \end{aligned}$$

From Definition 1.3 and the Lie bracket operations of the horizontal and vertical lifts of any vector field X to the tangent bundle (see [6, 16]), we obtain the following proposition.

Proposition 1.5. [5] Let (M, g) be a Riemannian manifold. If R denotes the Riemannian curvature tensor of (M, g) , then for all vector fields X, Y on M and $p \in T^2M$ we have

1. $[X^{(0)}, Y^{(0)}]_p = [X, Y]_p^{(0)} - (R_x(X, Y)u)_p^{(1)} - (R_x(X, Y)\omega)_p^{(2)},$
2. $[X^{(0)}, Y^{(i)}]_p = (\nabla_X Y)_p^{(i)},$
3. $[X^{(i)}, Y^{(j)}]_p = 0,$

where $(x, u, \omega) = S(p)$ and $i, j = 1, 2$.

Lemma 1.6. Let (M, g) be a Riemannian manifold. For all $x \in M, u = u^i \frac{\partial}{\partial x^i}, \omega = \omega^i \frac{\partial}{\partial x^i} \in T_x M$ and any smooth function $f : \mathbb{R} \rightarrow \mathbb{R}$, we have the following

1. $X^{(0)}(g(Y, u))_p = g(\nabla_X Y, u)_x,$
2. $X^{(0)}(g(Y, \omega))_p = g(\nabla_X Y, \omega)_x,$
3. $X^{(0)}(f(r_1^2))_p = X^{(0)}(f(r_2^2))_p = 0 = X^{(0)}(g(u, u))_p = X^{(0)}(g(\omega, \omega))_p,$
4. $X^{(1)}(g(u, u))_p = 2g(X, u)_x,$
5. $X^{(1)}(g(\omega, \omega))_p = 0 = X^{(2)}(g(u, u))_p,$
6. $X^{(2)}(g(\omega, \omega))_p = 2g(X, \omega)_x,$
7. $X^{(1)}(g(Y, u))_p = g(X, Y)_x = X^{(2)}(g(Y, \omega))_p,$
8. $X^{(1)}(g(Y, \omega))_p = 0 = X^{(2)}(g(Y, u))_p,$
9. $X^{(1)}(f(r_1^2))_p = 2f'(r_1^2)g(X, u),$
10. $X^{(1)}(f(r_2^2))_p = 0 = X^{(2)}(f(r_1^2))_p,$
11. $X^{(2)}(f(r_2^2))_p = 2f'(r_2^2)g(X, \omega),$

where $p = S^{-1}(x, u, \omega), r_1^2 = g(u, u) = |u|^2, r_2^2 = g(\omega, \omega) = |\omega|^2$.

2. F-geodesics on T^2M

Definition 2.1. Let (M, g) be a Riemannian manifold. We define the Sasaki metric G_S on the second order tangent bundle T^2M by

$$G_S = S_*^{-1}(g_S \oplus g_S),$$

where g_S is the Sasaki metric on the tangent bundle of (M, g) (for Sasaki metric, see [15, 16]).

Thus, we obtain the following definition.

Definition 2.2. Let (M, g) be a Riemannian manifold. If $p \in T^2M$, then for all vector fields X, Y on M and $i, j \in \{0, 1, 2\}$ ($i \neq j$), we obtain

- 1 $G_S(X^{(0)}, Y^{(0)})_p = g(X, Y)_x,$
- 2 $G_S(X^{(i)}, Y^{(j)})_p = 0,$ for $i \neq j$
- 3 $G_S(X^{(1)}, Y^{(1)})_p = g(X, Y)_x,$
- 4 $G_S(X^{(2)}, Y^{(2)})_p = g(X, Y)_x,$ where $S(p) = (x, u, \omega) \in T_xM \oplus T_xM$ (also see [13]).

From Lemma 1.6 and Definition 2.2, standard calculations give the following lemma.

Lemma 2.3. *Let (M, g) be a Riemannian manifold and T^2M its second order tangent bundle with the Sasaki metric G_S . Then*

$$\begin{aligned} X^{(0)}(G_S(Y^{(0)}, Z^{(0)}))_p &= X(g(Y, Z))_x, \\ X^{(0)}(G_S(Y^{(1)}, Z^{(1)}))_p &= G_S((\nabla_X Y)^{(1)}, Z^{(1)})_p + G_S(Y^{(1)}, (\nabla_X Z)^{(1)})_p, \\ X^{(0)}(G_S(Y^{(2)}, Z^{(2)}))_p &= G_S((\nabla_X Y)^{(2)}, Z^{(2)})_p + G_S(Y^{(2)}, (\nabla_X Z)^{(2)})_p, \\ X^{(1)}(G_S(Y^{(0)}, Z^{(0)}))_p &= 0 = X^{(2)}(G_S(Y^{(0)}, Z^{(0)}))_p, \\ X^{(1)}(G_S(Y^{(1)}, Z^{(1)}))_p &= 0, \\ X^{(2)}(G_S(Y^{(2)}, Z^{(2)}))_p &= 0, \\ X^{(1)}(G_S(Y^{(2)}, Z^{(2)}))_p &= 0 = X^{(2)}(G_S(Y^{(1)}, Z^{(1)}))_p \end{aligned}$$

for all vector fields X, Y, Z on M and $p \in T^2M$.

Proposition 2.4. [5] *Let (M, g) be a Riemannian manifold and T^2M be its second order tangent bundle equipped with the Sasaki metric G_S . If $\widetilde{\nabla}$ denotes the Levi-Civita connection of T^2M , then for $p \in T^2M$ and vector fields X, Y on M we have*

1. $(\widetilde{\nabla}_{X^{(0)}} Y^{(0)})_p = (\nabla_X Y)^{(0)} - \frac{1}{2}(R(X, Y)u)^{(1)} - \frac{1}{2}(R(X, Y)\omega)^{(2)},$
2. $(\widetilde{\nabla}_{X^{(0)}} Y^{(1)})_p = (\nabla_X Y)^{(1)} + \frac{1}{2}(R(u, Y)X)^{(0)},$
3. $(\widetilde{\nabla}_{X^{(0)}} Y^{(2)})_p = (\nabla_X Y)^{(2)} + \frac{1}{2}(R(\omega, Y)X)^{(0)},$
4. $(\widetilde{\nabla}_{X^{(1)}} Y^{(0)})_p = \frac{1}{2}(R(u, X)Y)^{(0)},$
5. $(\widetilde{\nabla}_{X^{(2)}} Y^{(0)})_p = \frac{1}{2}(R(\omega, X)Y)^{(0)},$
6. $(\widetilde{\nabla}_{X^{(i)}} Y^{(j)})_p = 0 \quad i, j = 1, 2,$

where $S(p) = (x, u, \omega)$, ∇ and R denote the Levi-Civita connection and the Riemannian curvature tensor of (M, g) , respectively.

Definition 2.5. *Let M be a smooth manifold, F be a $(1,1)$ -tensor field on M , $\widetilde{\nabla}$ be a linear connection on M and $\gamma : I \rightarrow M$ be a smooth curve. Then*

1. γ is said to be a magnetic curve with respect to $(F, \widetilde{\nabla})$, if γ satisfies : $\widetilde{\nabla}_{\dot{\gamma}} \dot{\gamma}(t) = F \dot{\gamma}(t)$ ([1, 7]),
2. γ is said to be an F -planar curve with respect to $\widetilde{\nabla}$ if γ satisfies : $\widetilde{\nabla}_{\dot{\gamma}} \dot{\gamma}(t) = \varrho_1(t)\dot{\gamma}(t) + \varrho_2(t)F \dot{\gamma}(t)$ ([11, 12]),

where ϱ_1, ϱ_2 are some smooth real functions.

Definition 2.6. [2] Let M be a smooth manifold, F be a $(1,1)$ -tensor field on M , $\bar{\nabla}$ be a linear connection, and $\gamma : I \rightarrow M$ be a smooth curve. We say that γ is an F -geodesic with respect to $\bar{\nabla}$ if $\gamma(u)$ satisfies

$$\bar{\nabla}_{\dot{\gamma}(u)}\dot{\gamma}(u) = F(\dot{\gamma}(u)). \tag{2}$$

If t is another parameter for the same curve $\gamma(u)$ then the relation (2) becomes

$$\bar{\nabla}_{\dot{\gamma}(t)}\dot{\gamma}(t) = \alpha(t)\dot{\gamma}(t) + \beta(t)F(\dot{\gamma}(t)), \tag{3}$$

where α and β are some functions on the curve $\gamma(t)$.

A curve $\gamma(t)$ satisfying the relation (3) describes an F -geodesic up to a reparameterization.

One can easily see that an F -geodesic is an F -planar curve, but in general an F -planar curve is not always an F -geodesic.

Definition 2.7. Let (M, g) be a Riemannian manifold and $x : I \rightarrow M$ be a curve on M . We define a curve $C : I \rightarrow T^2M$ by $C(t) = S^{-1}(x(t), y(t), z(t))$ for all $t \in I$, where $y(t) \in T_{x(t)}M$, i.e., $y(t), z(t)$ are vector fields along $x(t)$.

(1) The curve $C(t) = S^{-1}(x(t), \dot{x}(t), \dot{x}(t))$ is called a natural lift of the curve $x(t)$.

(2) The curve $C(t) = S^{-1}(x(t), y(t), z(t))$ is said to be a horizontal lift of the curve $x(t)$ if and only if $\nabla_{\dot{x}}y = 0$ and $\nabla_{\dot{x}}z = 0$.

Lemma 2.8 ([14]). Let (M, g) be a Riemannian manifold. If X, Y are vector fields on M and $(x, u) \in TM$ such that $X_x = u$, then we have

$$d_x X(Y_x) = Y_{(x,u)}^H + (\nabla_Y X)_{(x,u)}^V.$$

Lemma 2.9. Let (M, g) be a Riemannian manifold. If Z is a vector field on M and $\sigma \in \Gamma(T^2M)$ then for all $x \in M$, we have

$$d_x \sigma(Z_x) = Z_p^{(0)} + (\nabla_Z X_\sigma)_p^{(1)} + (\nabla_Z Y_\sigma)_p^{(2)},$$

where $p = \sigma(x)$.

Proof. Using Lemma 2.8, it follows that

$$\begin{aligned} d_x \sigma(Z) &= dS^{-1}(dX_\sigma(Z), dY_\sigma(Z))_{S(p)} \\ &= dS^{-1}(Z^H, Z^H)_{S(p)} + dS^{-1}((\nabla_Z X_\sigma)^V, (\nabla_Z Y_\sigma)^V)_{S(p)} \\ &= Z_p^{(0)} + (\nabla_Z X_\sigma)_p^{(1)} + (\nabla_Z Y_\sigma)_p^{(2)}. \end{aligned}$$

□

Lemma 2.10. Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Sasaki metric and let $x : I \rightarrow M$ be a curve on M . If $C : t \in I \rightarrow C(t) = S^{-1}(x(t), y(t), z(t))$ is a curve on T^2M such that $y(t), z(t)$ are vector fields along $x(t)$ (i.e., $y(t), z(t) \in T_{x(t)}M$), then

$$\dot{C} = \dot{x}^{(0)} + (\nabla_{\dot{x}}y)^{(1)} + (\nabla_{\dot{x}}z)^{(2)},$$

where $\dot{x} = \frac{dx}{dt}$ and $\dot{C} = \frac{dC}{dt}$.

Proof. If Y, Z are vector fields such $Y(x(t)) = y(t)$ and $Z(x(t)) = z(t)$, then we have

$$\dot{C}(t) = dC(t) = d\sigma(\dot{x}(t)),$$

where $\sigma = S^{-1}(Y, Z)$. Using Lemma 2.9 we obtain

$$\dot{C}(t) = d\sigma(\dot{x}(t)) = \dot{x}^{(0)} + (\nabla_{\dot{x}}y)^{(1)} + (\nabla_{\dot{x}}z)^{(2)}. \tag{4}$$

□

Theorem 2.11. *Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$ and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on T^2M such that $y(t), z(t)$ are vector fields along $x(t)$. Then we have*

$$\tilde{\nabla}_{\dot{C}}\dot{C} = \left[\nabla_{\dot{x}}\dot{x} + R(y, \nabla_{\dot{x}}y)\dot{x} + R(z, \nabla_{\dot{x}}z)\dot{x} \right]^{(0)} + \left[\nabla_{\dot{x}}\nabla_{\dot{x}}y \right]^{(1)} + \left[\nabla_{\dot{x}}\nabla_{\dot{x}}z \right]^{(2)}. \tag{5}$$

Proof. The proof follows immediately from Proposition 2.4 and the formula (4).

□

Theorem 2.12. *Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$. A curve $C(t) = S^{-1}(x(t), y(t), z(t))$ on T^2M is an $F^{(0)}$ -planar curve if and only if*

$$\begin{aligned} \nabla_{\dot{x}}\dot{x} &= -R(y, \nabla_{\dot{x}}y)\dot{x} - R(z, \nabla_{\dot{x}}z)\dot{x} + \varrho_1(t)\dot{x} + \varrho_2(t)F(\dot{x}), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}y &= \varrho_1(t)\nabla_{\dot{x}}y + \varrho_2(t)F(\nabla_{\dot{x}}y), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}z &= \varrho_1(t)\nabla_{\dot{x}}z + \varrho_2(t)F(\nabla_{\dot{x}}z). \end{aligned}$$

Proof. From the formula (4), we have

$$\begin{aligned} \tilde{\nabla}_{\dot{C}}\dot{C} &= \varrho_1(t)\dot{C} + \varrho_2(t)F^{(0)}(\dot{C}) \\ &= \varrho_1(t)\left[\dot{x}^{(0)} + (\nabla_{\dot{x}}y)^{(1)} + (\nabla_{\dot{x}}z)^{(2)}\right] \\ &\quad + \varrho_2(t)\left[F^{(0)}\dot{x}^{(0)} + F^{(0)}(\nabla_{\dot{x}}y)^{(1)} + F^{(0)}(\nabla_{\dot{x}}z)^{(2)}\right] \\ &= \left[\varrho_1(t)\dot{x} + \varrho_2(t)F\dot{x}\right]^{(0)} + \left[\varrho_1(t)\nabla_{\dot{x}}y + \varrho_2(t)F\nabla_{\dot{x}}y\right]^{(1)} \\ &\quad + \left[\varrho_1(t)\nabla_{\dot{x}}z + \varrho_2(t)F\nabla_{\dot{x}}z\right]^{(2)}. \end{aligned}$$

Using the formula (5), the result immediately follows. □

In the particular case when $\varrho_1 = 0$ and $\varrho_2 = 1$ in the Theorem 2.12, we obtain the following result.

Theorem 2.13. *Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$. A curve $C(t) = S^{-1}(x(t), y(t), z(t))$ on T^2M is an $F^{(0)}$ -geodesic if and only if*

$$\begin{aligned} \nabla_{\dot{x}}\dot{x} &= -R(y, \nabla_{\dot{x}}y)\dot{x} - R(z, \nabla_{\dot{x}}z)\dot{x} + F(\dot{x}), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}y &= F(\nabla_{\dot{x}}y), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}z &= F(\nabla_{\dot{x}}z). \end{aligned}$$

Using Theorem 2.12 and Theorem 2.13, we obtain the following corollaries.

Corollary 2.14. *Let (M, g) be a locally flat Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$. Then a curve $C(t) = S^{-1}(x(t), y(t), z(t))$ on T^2M is an $F^{(0)}$ -geodesic if and only if*

$$\begin{aligned} \nabla_{\dot{x}}\dot{x} &= F(\dot{x}), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}y &= F(\nabla_{\dot{x}}y), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}z &= F(\nabla_{\dot{x}}z). \end{aligned}$$

Corollary 2.15. Let (M, g) be a locally flat Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$. Then a curve $C(t) = S^{-1}(x(t), y(t), z(t))$ on T^2M is an $F^{(0)}$ -geodesic up to a reparameterization (resp., $F^{(0)}$ -planar curve) if and only if

$$\begin{aligned} \nabla_{\dot{x}}\dot{x} &= \varrho_1(t)\dot{x} + \varrho_2(t)F(\dot{x}), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}y &= \varrho_1(t)\nabla_{\dot{x}}y + \varrho_2(t)F(\nabla_{\dot{x}}y), \\ \nabla_{\dot{x}}\nabla_{\dot{x}}z &= \varrho_1(t)\nabla_{\dot{x}}z + \varrho_2(t)F(\nabla_{\dot{x}}z). \end{aligned}$$

Proposition 2.16. Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\tilde{\nabla}$. If $C(t) = S^{-1}(x(t), y(t), z(t))$ is a horizontal lift of a curve $x(t)$, then $C(t)$ is an $F^{(0)}$ -planar curve (resp., $F^{(0)}$ -geodesic) if and only if $x(t)$ is an F -planar curve (resp., F -geodesic).

Proof. From the formulas (4) and (5), we have

$$\begin{aligned} \dot{C}(t) &= (\dot{x})^{(0)}(t) \\ \tilde{\nabla}_C\dot{C} &= \tilde{\nabla}_{(\dot{x})^0}\dot{x}^{(0)} = (\nabla_{\dot{x}}\dot{x})^{(0)}. \end{aligned}$$

Let $C(t)$ be an $F^{(0)}$ -planar curve. Then

$$\begin{aligned} \tilde{\nabla}_C\dot{C} &= \varrho_1(t)\dot{C} + \varrho_2(t)F^{(0)}(\dot{C}) \\ &= \varrho_1(t)\dot{x}^{(0)} + \varrho_2(t)F^{(0)}(\dot{x}^{(0)}) \\ &= [\varrho_1(t)\dot{x} + \varrho_2(t)F(\dot{x})]^{(0)} \\ &= (\nabla_{\dot{x}}\dot{x})^{(0)}. \end{aligned}$$

Hence, $C(t)$ is an $F^{(0)}$ -planar curve if and only if $x(t)$ is an F -planar curve. In the case of $\varrho_1 = 0$ and $\varrho_2 = 1$, we get that $C(t)$ is an $F^{(0)}$ -geodesic if and only if $x(t)$ is an F -geodesic.

□

Remark 2.17. If $C(t) = S^{-1}(x(t), y(t), z(t))$ is the horizontal lift of the curve $x(t)$, then we have

$$\begin{aligned} [\nabla_{\dot{x}}y = 0] &\Leftrightarrow \left[\frac{dy^k}{dt} + \Gamma_{ij}^k y^j \frac{dx^i}{dt} = 0 \right] \Leftrightarrow [y(t) = e^{-\int A(t)dt} \cdot \bar{K}], \\ [\nabla_{\dot{x}}z = 0] &\Leftrightarrow \left[\frac{dz^k}{dt} + \Gamma_{ij}^k z^j \frac{dx^i}{dt} = 0 \right] \Leftrightarrow [z(t) = e^{-\int A(t)dt} \cdot \bar{K}], \end{aligned}$$

where $K, \bar{K} \in \mathbb{R}^n$ and $A(t) = [a_{ki}]$, $a_{ki} = \sum_{j=1}^n \Gamma_{ij}^k \frac{dx^j}{dt}$. Therefore, $C(t)$ is an $F^{(0)}$ -geodesic (resp. $F^{(0)}$ -planar curve) if and only if $\nabla_{\dot{x}}\dot{x} = F(\dot{x})$ (resp. $\nabla_{\dot{x}}\dot{x} = \varrho_1(t)\dot{x} + \varrho_2(t)F(\dot{x})$).

Using Remark 2.17, we can construct an infinity of examples of F -geodesics (resp. F -planar curve) on (T^2M, G_S) .

Example 2.18. Let \mathbb{R}^n be equipped with the Riemannian metric $g = ds^2$ and $B \in \mathcal{M}_{n \times n}(\mathbb{R})$. If $F = B$ is an invertible matrix, then $C(t) = S^{-1}(B^{-1} \exp(B t) K_1 + K_2, \text{const.}, \text{const.})$, $K_1, K_2 \in \mathbb{R}^n$, is an $F^{(0)}$ -geodesic.

Example 2.19. Let \mathbb{R} be equipped with the Riemannian metric $g = e^x dx^2$ and $F = a \in \mathbb{R}^*$. Then the Christoffel symbol of the Levi-Civita connection is given by

$$\Gamma_{11}^1 = \frac{1}{2} g^{11} \left(\frac{\partial g_{11}}{\partial x^1} + \frac{\partial g_{11}}{\partial x^1} - \frac{\partial g_{11}}{\partial x^1} \right) = \frac{1}{2}$$

and $C(t) = S^{-1}(x(t), y(t), z(t)) = S^{-1} \left(2 \ln \left(\frac{K_1 e^{at} + a K_2}{2a} \right), \frac{2a K_3}{K_1 e^{at} + a K_2}, \frac{2a K_4}{K_1 e^{at} + a K_2} \right)$, $K_1, \dots, K_4 \in \mathbb{R}$, is an $F^{(0)}$ -geodesic such that $\nabla_{\dot{x}}y = 0$ and $\nabla_{\dot{x}}z = 0$.

Example 2.20. Let \mathbb{R} be equipped with the Riemannian metric $g = e^x dx^2$, $F = a \in \mathbb{R}^*$, $\rho_1(t) = \frac{1}{t}$, $\rho_2(t) = 1$. Then we have $\Gamma_{11}^1 = \frac{1}{2}$ and $x(t)$ is an F -planar curve if and only if it satisfies the following differential equation

$$x'' + \frac{1}{2}x'^2 = \frac{at + 1}{t}x'.$$

A solution of the previous equation is given by

$$x(t) = 2 \ln \frac{K_1 e^{at}(at - 1) + K_2}{2a^2}.$$

So, from Remark 2.17 we obtain

$$\begin{aligned} y(t) &= \frac{2a^2 K_3}{K_1 e^{at}(at - 1) + K_2}, \\ z(t) &= \frac{2a^2 K_4}{K_1 e^{at}(at - 1) + K_2}, \end{aligned}$$

where $K_1, \dots, K_4 \in \mathbb{R}$. Then $C(t) = S^{-1}(x(t), y(t), z(t))$, is an $F^{(0)}$ -planar curve such that $\nabla_{\dot{x}}y = 0$ and $\nabla_{\dot{x}}z = 0$.

Example 2.21. Let $(\mathbb{R} \setminus \{0\})^2$ be equipped with the Riemannian metric h defined by

$$h_{11} = x^2, \quad h_{22} = y^2, \quad h_{12} = 0$$

and $F = \begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}$. Then the Christoffel symbols of the Levi-Civita connection are given by

$$\Gamma_{11}^1 = \frac{1}{x}, \quad \Gamma_{22}^2 = \frac{1}{y}, \quad \Gamma_{ij}^k = 0 \quad \forall (i, j, k) \in \{1, 2\}^3 \setminus \{(1, 1), (2, 2)\}.$$

Let $C(t) = S^{-1}(x(t), y(t), z(t))$ be the horizontal lift of the curve $x(t) = (x_1(t), x_2(t))$. From Remark 2.17, we have

$$\begin{aligned} A(t) &= \begin{pmatrix} \frac{x_1'(t)}{x_1(t)} & 0 \\ 0 & \frac{x_2'(t)}{x_2(t)} \end{pmatrix}, \\ y(t) &= \left(\frac{k_1}{x_1(t)}, \frac{k_2}{x_2(t)} \right) \text{ and } z(t) = \left(\frac{k_3}{x_1(t)}, \frac{k_4}{x_2(t)} \right), \end{aligned}$$

where $k_1, k_2, k_3, k_4 \in \mathbb{R}$. $x(t) = (x_1(t), x_2(t))$ is an F -geodesic if and only if it satisfies the following differential equations

$$\begin{cases} x_1'' + \frac{1}{x_1}x_1'^2 = a x_1' \\ x_2'' + \frac{1}{x_2}x_2'^2 = 0 \end{cases}$$

whose solution is given by

$$x(t) = (x_1(t), x_2(t)) = \left(\exp \sqrt{\frac{a}{2}} t, \sqrt{2k_5 t + k_6} \right),$$

where $k_5, k_6 \in \mathbb{R}$. Therefore, $C(t) = S^{-1} \left(x_1(t), x_2(t), \frac{k_1}{x_1(t)}, \frac{k_2}{x_2(t)}, \frac{k_3}{x_1(t)}, \frac{k_4}{x_2(t)} \right)$ is an F -geodesic such that $\nabla_{\dot{x}}y = 0$ and $\nabla_{\dot{x}}z = 0$.

Proposition 2.22. Let (M, g) be a Riemannian manifold equipped with the Levi-Civita connection ∇ and let (T^2M, G_S) be its second order tangent bundle equipped with the Levi-Civita connection $\widetilde{\nabla}$. Let F be a $(1,1)$ -tensor field on M . If $C(t) = S^{-1}(x(t), y(t), z(t))$ is the horizontal lift of a curve $x(t)$, then we have

1. An integral curve of any vector field X on M is an F -geodesic with respect to ∇ if and only if the integral curve of $X^{(0)}$ is an $F^{(0)}$ -geodesic with respect to $\widetilde{\nabla}$.
2. An integral curve of any vector field X on M is an F -geodesic up to a reparameterization, with respect to ∇ if and only if the integral curve of $X^{(0)}$ is an $F^{(0)}$ -geodesic up to a reparameterization, with respect to $\widetilde{\nabla}$.
3. $C(t)$ is an $F^{(0)}$ -geodesic with respect to $\widetilde{\nabla}$ if and only if the curve $x(t)$ is an F -geodesic with respect to ∇ .
4. $C(t)$ is an $F^{(0)}$ -geodesic up to a reparameterization with respect to $\widetilde{\nabla}$ if and only if the curve $x(t)$ is an F -geodesic up to a reparameterization with respect to ∇ .

Proof. Let γ be an F -geodesic up to a reparameterization with respect to Levi-Civita connection ∇ on M . Then the relation (3) is satisfied and we obtain

$$\widetilde{\nabla}_{\dot{\gamma}^{(0)}} \dot{\gamma}^{(0)} = (\nabla_{\dot{\gamma}} \dot{\gamma})^0 = \alpha \circ P \dot{\gamma}(t)^{(0)} + \beta \circ P F^{(0)} \dot{\gamma}(t)^{(0)},$$

where P is the canonical projection on T^2M . In the case of $\alpha = 0$ and $\beta = 1$, one can easily obtain (1). \square

Remark 2.23. The Proposition 2.22 remains true, if we replace $\widetilde{\nabla}$ by $\nabla^{(0)}$, where $\nabla^{(0)}$ is defined by

$$\begin{aligned} \nabla_{X^{(0)}}^{(0)} Y^{(\lambda)} &= (\nabla_X Y)^{(\lambda)}, \\ \nabla_{X^{(i)}}^{(0)} Y^{(\lambda)} &= 0 \end{aligned}$$

for $i = 1, 2$ and $\lambda = 0, 1, 2$.

Definition 2.24. Let (M, g) be a Riemannian manifold. We can define a natural diagonal metric G on the second tangent bundle T^2M of (M, g) by

$$\begin{cases} G_p(X^{(0)}, Y^{(0)}) = b_1 g_x(X, Y) + d_1 g_x(X, u) g_x(Y, u) + c_1 g_x(X, \omega) g_x(Y, \omega), \\ G_p(X^{(1)}, Y^{(1)}) = b_2 g_x(X, Y) + d_2 g_x(X, u) g_x(Y, u), \\ G_p(X^{(2)}, Y^{(2)}) = b_3 g_x(X, Y) + d_3 g_x(X, u) g_x(Y, u), \\ G_p(X^{(i)}, Y^{(j)}) = 0, \quad i \neq j = 0, 1, 2 \end{cases} \tag{6}$$

where $p = S^{-1}(x, u, \omega)$, d_1, b_2, d_2 (resp. c_1, b_3, d_3) are smooth functions depending on $r_1 = g(u, u)$ (resp $r_2 = g(\omega, \omega)$) and b_1 is a smooth function depending on (r_1, r_2) , such that $b_1, b_2, b_3 > 0$ and $b_1 + r_1 d_1, b_2 + r_1 d_2, b_3 + r_2 d_3 > 0$.

The Levi-Civita connection of G denoted by $\widehat{\nabla}$ has the following expressions on the horizontal and respectively on the vertical distributions of $T(T^2M)$

$$\begin{aligned} \widehat{\nabla}_{X^{(0)}} Y^{(0)} &= (\nabla_X Y)^{(0)} - \frac{d_1}{2b_1} [g(X, u)Y^{(1)} + g(Y, u)X^{(1)}] - \frac{\partial_1 b_1}{b_2 + r_1 d_2} g(X, Y)u^{(1)} \\ &\quad - \frac{b_2 d'_1 - d_1 d_2}{b_2(b_2 + r_1 d_2)} g(X, u)g(Y, u)u^{(1)} - \frac{1}{2} (R(X, Y)u)^{(1)} \\ &\quad - \frac{c_1}{2b_1} [g(X, \omega)Y^{(2)} + g(Y, \omega)X^{(2)}] - \frac{\partial_2 b_1}{b_3 + r_2 d_3} g(X, Y)\omega^{(2)} \\ &\quad - \frac{b_3 c'_1 - c_1 d_3}{b_3(b_3 + r_2 d_3)} g(X, \omega)g(Y, \omega)\omega^{(2)} - \frac{1}{2} (R(X, Y)\omega)^{(2)}, \end{aligned} \tag{7}$$

$$\begin{aligned} \widehat{\nabla}_{X^{(1)}} Y^{(1)} &= \frac{b'_2}{b_2} [g(X, u)Y^{(1)} + g(Y, u)X^{(1)}] - \frac{b'_2 - d_2}{b_2 + r_1 d_2} g(X, Y)u^{(1)} \\ &\quad + \frac{b_2 d'_2 - b'_2 d_2}{b_2(b_2 + r_1 d_2)} g(X, u)g(Y, u)u^{(1)}, \\ \widehat{\nabla}_{X^{(2)}} Y^{(2)} &= \frac{b'_3}{b_3} [g(X, \omega)Y^{(2)} + g(Y, \omega)X^{(2)}] - \frac{b'_3 - d_3}{b_3 + r_2 d_3} g(X, Y)\omega^{(2)} \\ &\quad + \frac{b_3 d'_3 - b'_3 d_3}{b_3(b_3 + r_2 d_3)} g(X, \omega)g(Y, \omega)\omega^{(2)}, \end{aligned}$$

where $\partial_1 b_1 = \frac{\partial b_1}{\partial r_1}$ and $\partial_2 b_1 = \frac{\partial b_1}{\partial r_2}$.

Proposition 2.25. *Let (M, g) be a Riemannian manifold, (T^2M, G) be its second order tangent bundle and let F be a $(1,1)$ -tensor field on M . If $C(t) = S^{-1}(x(t), y(t), z(t))$ is the horizontal lift of a curve $x(t)$, then we have*

- (i) *An integral curve of any vector field X on M is an F -geodesic with respect to the Levi-Civita connection ∇ of g if and only if the integral curve of the horizontal lift $X^{(0)}$ is an $F^{(0)}$ -geodesic with respect to the Levi-Civita connection $\widehat{\nabla}$ of G defined by (6), provided $b_1 = \text{const.}$ and $d_1 = c_1 = 0$.*
- (ii) *The curve $C(t)$ is an $F^{(0)}$ -geodesic with respect to the Levi-Civita connection $\widehat{\nabla}$ if and only if the curve $x(t)$ is an F -geodesic with respect to the Levi-Civita connection ∇ , provided $b_1 = \text{const.}$ and $d_1 = c_1 = 0$.*
- (iii) *The above assertions (i) and (ii) remain true, if instead of an F -geodesic (resp., $F^{(0)}$ -geodesic), we take an F -geodesic up to a reparameterization (resp. an $F^{(0)}$ -geodesic up to a reparameterization).*

Proof. Let γ be an F -geodesic up to a reparameterization with respect to ∇ , i.e.,

$$\nabla_{\dot{\gamma}} \dot{\gamma} = \alpha \dot{\gamma} + \beta F\dot{\gamma}, \tag{8}$$

where α and β are some smooth functions on the curve. For $X = Y = \dot{\gamma}$ the relation (7) becomes

$$\begin{aligned} \widehat{\nabla}_{\dot{\gamma}^{(0)}} \dot{\gamma}^{(0)} &= (\nabla_{\dot{\gamma}} \dot{\gamma})^{(0)} - \frac{d_1}{b_1} g(\dot{\gamma}, u)\dot{\gamma}^{(1)} - \frac{\partial_1 b_1}{b_2 + r_1 d_2} g(\dot{\gamma}, \dot{\gamma})u^{(1)} \\ &\quad - \frac{b_2 d'_1 - d_1 d_2}{b_2(b_2 + r_1 d_2)} g(\dot{\gamma}, u)^2 u^{(1)} - \frac{c_1}{b_1} g(\dot{\gamma}, \omega)\dot{\gamma}^{(2)} \\ &\quad - \frac{\partial_2 b_1}{b_3 + r_2 d_3} g(\dot{\gamma}, \dot{\gamma})\omega^{(2)} - \frac{b_3 c'_1 - c_1 d_3}{b_3(b_3 + r_2 d_3)} g(\dot{\gamma}, \omega)^2 \omega^{(2)}. \end{aligned}$$

Using the formula (8), we have that $\widehat{\nabla}_{\dot{\gamma}^{(0)}} \dot{\gamma}^{(0)} = \alpha \circ P \dot{\gamma}^{(0)} + \beta \circ P F^{(0)} \dot{\gamma}^{(0)}$ if and only if

$$\begin{aligned} 0 &= -\frac{d_1}{b_1} g(\dot{\gamma}, u)\dot{\gamma}^{(1)} - \frac{\partial_1 b_1}{b_2 + r_1 d_2} g(\dot{\gamma}, \dot{\gamma})u^{(1)} \\ &\quad - \frac{b_2 d'_1 - d_1 d_2}{b_2(b_2 + r_1 d_2)} g(\dot{\gamma}, u)^2 u^{(1)} - \frac{c_1}{b_1} g(\dot{\gamma}, \omega)\dot{\gamma}^{(2)} \\ &\quad - \frac{\partial_2 b_1}{b_3 + r_2 d_3} g(\dot{\gamma}, \dot{\gamma})\omega^{(2)} - \frac{b_3 c'_1 - c_1 d_3}{b_3(b_3 + r_2 d_3)} g(\dot{\gamma}, \omega)^2 \omega^{(2)}. \end{aligned}$$

Then, we get $d_1 = c_1 = \partial_1 b_1 = \partial_2 b_1 = 0$. If we replace $\gamma(t)$ by $x(t)$, from the formula (4) we have $\dot{C}(t) = (x(t))^{(0)}$. Similarly, the item (iii) can be proved. In the particular case of $\alpha = 0$ and $\beta = 1$, we deduce that the items (i) and (ii) are also true. \square

3. F -Geodesics of the hypersurface $T^2_{1,1}M$

Let $T^2_{1,1}M$ be the hypersurface in T^2M defined by

$$T^2_{1,1}M = \{p = S^{-1}(x, u, w) \in T^2M, |u| = |w| = 1\}. \tag{9}$$

The unit normal vector fields to $T^2_{1,1}M$ are given by

$$\begin{aligned} \mathcal{U} : T^2M &\rightarrow T(T^2M) \\ p = S^{-1}(x, u, w) &\mapsto \mathcal{U}_p = (u)^{(1)} \end{aligned} \tag{10}$$

$$\begin{aligned} \mathcal{W} : T^2M &\rightarrow T(T^2M) \\ p = S^{-1}(x, u, w) &\mapsto \mathcal{W}_p = (w)^{(2)}. \end{aligned} \tag{11}$$

Indeed, for $p = S^{-1}(x, u, w) \in T^2_{1,1}M$, we have

$$\begin{aligned} G_S(\mathcal{U}, \mathcal{U})_p &= g(u, u) = 1, \\ G_S(\mathcal{W}, \mathcal{W})_p &= g(w, w) = 1, \\ G_S(\mathcal{U}, \mathcal{W})_p &= 0. \end{aligned}$$

On the other hand, if we set

$$\begin{aligned} F_1 : T^2M &\rightarrow \mathbb{R}, \quad p = S^{-1}(x, u, w) \mapsto g(u, u), \\ F_2 : T^2M &\rightarrow \mathbb{R}, \quad p = S^{-1}(x, u, w) \mapsto g(w, w), \\ F : T^2M &\rightarrow \mathbb{R}^2, \quad p \mapsto (F_1(p), F_2(p)), \end{aligned}$$

then the hypersurface $T^2_{1,1}M$ is given by

$$T^2_{1,1}M = \{p = S^{-1}(x, u, w) \in T^2M, (F_1(p), F_2(p)) = (1, 1)\},$$

where $grad_{G_S}(F_1)$ and $grad_{G_S}(F_2)$ are vector fields normal to $T^2_{1,1}M$. From Lemma 1.6, for any vector field X on M , we get

$$\begin{aligned} G_S(X^{(0)}, grad_{G_S}(F_1)) &= X^{(0)}(F_1) = X^{(0)}(g(u, u)) \\ &= 0 = G_S(X^{(0)}, \mathcal{U}), \\ G_S(X^{(1)}, grad_{G_S}(F_1)) &= X^{(1)}(F_1) = X^{(1)}(g(u, u)) \\ &= 2g(X, u) = 2G_S(X^{(1)}, \mathcal{U}), \\ G_S(X^{(2)}, grad_{G_S}(F_1)) &= X^{(2)}(F_1) = X^{(2)}(g(u, u)) \\ &= 0 = 2G_S(X^{(2)}, \mathcal{U}). \end{aligned}$$

So $\mathcal{U} = \frac{1}{2}grad_{G_S}(F_1)$. By the same way, we obtain $\mathcal{W} = \frac{1}{2}grad_{G_S}(F_2)$, therefore \mathcal{U} and \mathcal{W} are vector fields orthonormal to $T^2_{1,1}M$. If B (resp. $\ddot{\nabla}$) denotes the second fundamental form (resp. the Levi-Civita connection on $T^2_{1,1}M$), then we have

$$B(\tilde{X}, \tilde{Y}) = G_S(\tilde{\nabla}_{\tilde{X}}\tilde{Y}, \mathcal{U})\mathcal{U} + G_S(\tilde{\nabla}_{\tilde{X}}\tilde{Y}, \mathcal{W})\mathcal{W}, \tag{12}$$

$$\ddot{\nabla}_{\tilde{X}}\tilde{Y} = \tilde{\nabla}_{\tilde{X}}\tilde{Y} - \rho_1(\tilde{X}, \tilde{Y})\mathcal{U} - \rho_2(\tilde{X}, \tilde{Y})\mathcal{W} \tag{13}$$

for all vector fields \tilde{X}, \tilde{Y} on $T^2_{1,1}M$.

Subsequently, we denote $x' = \dot{x}$, $x'' = \nabla_{\dot{x}}\dot{x}$, $y' = \nabla_{\dot{x}}y$ and $y'' = \nabla_{\dot{x}}\nabla_{\dot{x}}y$, $z' = \nabla_{\dot{x}}z$ and $z'' = \nabla_{\dot{x}}\nabla_{\dot{x}}z$.

Lemma 3.1. Let (M, g) be a Riemannian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the Sasaki metric and $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t), z(t)$ are vector fields along $x(t)$. Then, we have

- (1) $g(y, y) = 1 = g(z, z),$
- (2) $g(y', y) = 0 = g(z', z),$
- (3) $g(y'', y) = -|y'|^2 = -g(y', y'),$
- (4) $g(z'', z) = -|z'|^2 = -g(z', z').$

As $T^2_{1,1}M$ is the hypersurface in T^2M , a curve on $T^2_{1,1}M$ is a geodesic if and only if its second covariant derivative in T^2M is collinear to the unit normal vectors $(y)^{(1)}$ and $(z)^{(2)}$. From Theorem 2.13, the formula (12) and Lemma 3.1, we obtain the following lemma.

Lemma 3.2. Let (M, g) be a Riemannian manifold and (T^2M, G_S) be its second order tangent bundle equipped with the Sasaki metric and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. Then, C is an $F^{(0)}$ -geodesic on $T^2_{1,1}M$ if and only if

$$x'' = -[R(y, y') + R(z, z')]x' + F(x'), \tag{14}$$

$$y'' = F(y') + \rho_1 y, \tag{15}$$

$$z'' = F(z') + \rho_2 z, \tag{16}$$

where ρ_1, ρ_2 are some functions.

Definition 3.3. Let (M, F) be an almost complex manifold. A Riemannian metric g on M such that $g(FX, FY) = g(X, Y)$ or equivalently $g(FX, Y) = -g(X, FY)$ for any vector fields X, Y is called an almost Hermitian metric. The triple (M, F, g) is called an almost Hermitian manifold [9]. Also, for any vector field X , it follows that

$$g(X, FX) = 0. \tag{17}$$

Lemma 3.4. Let (M, F, g) be an almost Hermitian manifold and (T^2M, G_S) be its second order tangent bundle equipped with the Sasaki metric and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. If we put $c_1 = |y'|, \mu_1 = g(y', Fy), c_2 = |z'|, \mu_2 = g(z', Fz)$, then we have

- $\rho_1 = \mu_1 - c_1^2,$
- $\rho_2 = \mu_2 - c_2^2,$
- $c'_1 = 0 = c'_2,$
- $\mu'_1 = 0 = \mu'_2.$

Proof. From the formula (15), we obtain

$$y'' = \rho_1 y + F(y')$$

$$\begin{aligned} g(y'', y) &= g(F(y'), y) + \rho_1 g(y, y) \\ -|y'|^2 &= -\mu_1 + \rho_1. \end{aligned}$$

Using Lemma 3.1 (2) and the formula (17), we have

$$\begin{aligned} \frac{1}{2}(c_1^2)' &= g(y'', y') \\ &= \rho_1 g(y, y') + g(F(y'), y') \\ &= \rho_1 g(y, y') \\ &= 0. \end{aligned}$$

By Lemma 3.1 (2), Definition 3.3 and the formula (17), we obtain

$$\begin{aligned} \mu'_1 &= g(y'', F(y)) + g(y', F(y')) \\ &= g(y'', F(y)) \\ &= \rho_1 g(y, F(y)) + g(Fy', Fy) \\ &= 0. \end{aligned}$$

Similarly, we can obtain the other formulae. \square

Using Lemma 3.2 and Lemma 3.4, we get the following theorem.

Theorem 3.5. *Let (M, F, g) be an almost Hermitian manifold and (T^2M, G_S) be its second order tangent bundle equipped with the Sasaki metric and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. If we put $c_1 = |y'|$, $\mu_1 = g(y', Fy)$, $c_2 = |z'|$, $\mu_2 = g(z', Fz)$, then the curve $C(t) = S^{-1}(x(t), y(t), z(t))$ is an $F^{(0)}$ -geodesic on $T^2_{1,1}M$ if and only if*

$$\begin{aligned} c_1 &= \text{const.}, \quad \mu_1 = \text{const.} \quad \text{and} \quad \rho_1 = \mu_1 - c_1^2 = \text{const.}, \\ c_2 &= \text{const.}, \quad \mu_2 = \text{const.} \quad \text{and} \quad \rho_2 = \mu_2 - c_2^2 = \text{const.}, \\ x'' &= -[R(y, y') + R(z, z')]x' + F(x'), \\ y'' &= F(y') + (\mu_1 - c_1^2)y, \\ z'' &= F(z') + (\mu_2 - c_2^2)z. \end{aligned}$$

From Theorem 2.12 and Lemma 3.1, we obtain the following lemma.

Lemma 3.6. *Let (M, g) be a Riemannian manifold, (T^2M, G_S) its second order tangent bundle equipped with the Sasaki metric and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. Then, C is an $F^{(0)}$ -planar curve on $T^2_{1,1}M$ if and only if*

$$\begin{aligned} x'' &= -[R(y, y') + R(z, z')]x' + \eta_1 x' + \eta_2 F(x'), \\ y'' &= \eta_1 y' + \eta_2 F(y') + \rho_1 y, \\ z'' &= \eta_1 z' + \eta_2 F(z') + \rho_2 z, \end{aligned}$$

where η_1, η_2 are smooth functions on \mathbb{R} and ρ_1, ρ_2 are some functions.

Now, we will determine the functions ρ_1 and ρ_2 .

Lemma 3.7. *Let (M, g, F) be an almost Hermitian manifold, (T^2M, G_S) its second order tangent bundle equipped with the diagonal lift Sasaki metric and $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T^2_{1,1}M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. If we put $c_1 = |y'|$, $\mu_1 = g(y', Fy)$, $c_2 = |z'|$, $\mu_2 = g(z', Fz)$, then we have*

$$\begin{aligned} c_1 &= K_1 \exp\left(\int \eta_1 dt\right), & c_2 &= K_3 \exp\left(\int \eta_1 dt\right), \\ \mu_1 &= K_2 \exp\left(\int \eta_1 dt\right), & \mu_2 &= K_4 \exp\left(\int \eta_1 dt\right), \\ \rho_1 &= \eta_2 \mu_1 - c_1^2 = \eta_2 K_2 \exp\left(\int \eta_1 dt\right) - K_1^2 \exp\left(2 \int \eta_1 dt\right), \\ \rho_2 &= \eta_2 \mu_2 - c_2^2 = \eta_2 K_3 \exp\left(\int \eta_1 dt\right) - K_4^2 \exp\left(2 \int \eta_1 dt\right), \end{aligned}$$

where η_1, η_2 are smooth functions on \mathbb{R} .

Proof. From the formula (15), we obtain

$$y'' = \rho_1 y + \eta_1 y' + \eta_2 F(y'),$$

$$\begin{aligned} g(y'', y) &= \eta_1 g(y', y) + \eta_2 g(F(y'), y) + \rho_1 g(y, y), \\ -|y'|^2 &= -\eta_2 \mu_1 + \rho_1. \end{aligned}$$

Then $\rho_1 = \eta_2 \mu_1 - c_1^2$.

Using the formula (17), we get

$$\begin{aligned} \frac{1}{2}(c_1^2)' &= g(y'', y') \\ &= \rho_1 g(y, y') + \eta_1 g(y', y') + \eta_2 g(F(y'), y') \\ &= \eta_1 g(y', y') \\ &= \eta_1 c_1^2, \end{aligned}$$

from which we get $c_1 = K_1 \exp\left(\int \eta_1 dt\right)$.

On the other hand, we have

$$\begin{aligned} \mu_1' &= g(y'', Fy) + g(y', F(y')) \\ &= g(y'', Fy) \\ &= \rho_1 g(y, Fy) + \eta_1 g(y', Fy) + \eta_2 g(Fy', Fy) \\ &= \eta_1 g(y', Fy) \\ &= \eta_1 \mu_1, \end{aligned}$$

from which we get $\mu_1 = K_2 \exp\left(\int \eta_1 dt\right)$.

By the same way, we obtain the other formulas. \square

Using Lemma 3.6 and Lemma 3.7, we obtain the following theorem.

Theorem 3.8. *Let (M, g, F) be an almost Hermitian manifold and let (T^2M, G_S) be its second order tangent bundle equipped with the diagonal lift Sasaki metric and let $C(t) = S^{-1}(x(t), y(t), z(t))$ be a curve on $T_{1,1}^2M$ such that $y(t)$ and $z(t)$ are vector fields along $x(t)$. If we put $c_1 = |y'|$, $\mu_1 = g(y', Fy)$, $c_2 = |z'|$, $\mu_2 = g(z', Fz)$, then the curve $C(t) = S^{-1}(x(t), y(t), z(t))$ is an $F^{(0)}$ -planar curve on $T_{1,1}^2M$ if and only if*

$$\begin{aligned} c_1 &= K_1 \exp\left(\int \eta_1 dt\right), & c_2 &= K_3 \exp\left(\int \eta_1 dt\right), \\ \mu_1 &= K_2 \exp\left(\int \eta_1 dt\right), & \mu_2 &= K_4 \exp\left(\int \eta_1 dt\right), \\ \rho_1 &= \eta_2 \mu_1 - c_1^2 = \eta_2 K_2 \exp\left(\int \eta_1 dt\right) - K_1^2 \exp\left(2 \int \eta_1 dt\right), \\ \rho_2 &= \eta_2 \mu_2 - c_2^2 = \eta_2 K_3 \exp\left(\int \eta_1 dt\right) - K_4^2 \exp\left(2 \int \eta_1 dt\right), \end{aligned}$$

$$\begin{aligned} x'' &= -[R(y, y') + R(z, z')]x' + \varrho_1(t)x' + \varrho_2(t)F(x'), \\ y'' &= \varrho_1(t)y' + \varrho_2(t)F(y') + (\eta_2 \mu_1 - c_1^2)y, \\ z'' &= \varrho_1(t)z' + \varrho_2(t)F(z') + (\eta_2 \mu_2 - c_2^2)z. \end{aligned}$$

Remark 3.9. 1) The Theorem 3.8 remains true if $F^{(0)}$ -planar curve is replaced by $F^{(0)}$ -geodesic up to reparameterization.

2) In the case of $\eta_1 = 0$ and $\eta_2 = 1$ we obtain Theorem 3.5.

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