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Metallic shaped contact hypersurfaces of Kaehler manifolds

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Abstract. We study on metallic shaped contact hypersurfaces of Kaehler manifolds. We show that a metallic shaped (κ , μ)-contact metric hypersurface of a Kaehler manifold has constant mean curvature. As a special case, we also consider product shaped Sasakian hypersurfaces of Kaehler manifolds.

1. Introduction

Let F(0) = a, F(1) = b and a, b, p and q be real numbers. Then the generalized secondary Fibonacci sequence is given by the relation

 $F(k+1) = \mathfrak{p}F(k) + \mathfrak{q}F(k-1), \ k \ge 1,$

(see [7]). When $\mathfrak{p} = \mathfrak{q} = 1$, we have the Fibonacci sequence. If the limit $x = \lim_{k \to \infty} \frac{F(k+1)}{F(k)}$ exists, then it is a root of the equation

$$x^2 - \mathfrak{p}x - \mathfrak{q} = 0,\tag{1}$$

(see [6]).

Let p and q be two integers. The positive solution $\sigma_{p,q} = \frac{p+\sqrt{p^2+4q}}{2}$ of the equation (1) is called *member of the metallic means family* (briefly MMF) [6]. The numbers $\sigma_{p,q}$ are called $(\mathfrak{p}, \mathfrak{q})$ -*metallic numbers* [6]. For some special values of p and q, we have some known metallic means. For example: If $\mathfrak{p} = \mathfrak{q} = 1$, then $\sigma_G = \frac{1+\sqrt{5}}{2}$ is the *golden mean*. If $\mathfrak{p} = 2$ and $\mathfrak{q} = 1$, then $\sigma_{\mathcal{A}g} = 1 + \sqrt{2}$ is the *silver mean*. If $\mathfrak{p} = 3$ and $\mathfrak{q} = 1$, then $\sigma_{Br} = \frac{3+\sqrt{13}}{2}$ is the *bronze mean*. If $\mathfrak{p} = 1$ and $\mathfrak{q} = 2$, then $\sigma_{Cu} = 2$ is the *copper mean*. If $\mathfrak{p} = 1$ and $\mathfrak{q} = 3$, then $\sigma_{Ni} = \frac{1+\sqrt{13}}{2}$ is the *nickel mean*.

So MMF is a generalization of the golden mean. The golden mean has many applications in biological growth, constructions of buildings, musics, paintings. The MMF are used in describing fractal geometry, quasiperiodic dynamics (see [7] and [8]).

The notion of a metallic shaped hypersurface was defined by the present author and N. Y. Özgür in [11]. *M* is called a *metallic shaped hypersurface* [11], if the shape operator \mathcal{A} of *M* satisfies

 $\mathcal{A}^2 = \mathfrak{p}\mathcal{A} + \mathfrak{q}I,$

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where *I* is the identity on the tangent bundle of *M* and \mathfrak{p} and \mathfrak{q} are positive integers. The full classification of the metallic shaped hypersurfaces in real space forms and Lorentzian space forms were given in [11] and [12], respectively. If $\mathfrak{p} = \mathfrak{q} = 1$, then the hypersurface is *golden shaped* [4]. The full classification of golden shaped hypersurfaces in real space forms were given by Crâşmăreanu, Hreţcanu and Munteanu in [4]. If $\mathfrak{p} = 2$ and $\mathfrak{q} = 1$, if $\mathfrak{p} = 3$ and $\mathfrak{q} = 1$, if $\mathfrak{p} = 1$ and $\mathfrak{q} = 2$, or if $\mathfrak{p} = 1$ and $\mathfrak{q} = 3$, then the hypersurface is called *silver shaped*, *copper shaped* or *nickel shaped*, respectively [11].

M is called a *product-shaped hypersurface* [4], if the shape operator \mathcal{A} satisfies

 $\mathcal{A}^2 = I.$

Based on these observations, in the present paper, we consider metallic shaped contact hypersurfaces of Kaehler manifolds. It is shown that a metallic shaped (κ , μ)-contact metric hypersurface of a Kaehler manifold has constant mean curvature. As a special case, we also consider product shaped Sasakian hypersurfaces of Kaehler manifolds.

2. Contact Metric Manifolds

Let $M = (M^{2n+1}, \varphi, \xi, \eta, g)$ be a contact metric manifold with an almost contact metric structure (φ, ξ, η, g) . A contact metric manifold $M = (M^{2n+1}, \varphi, \xi, \eta, g)$ is called a *Sasakian manifold*, if it is normal (see [1], [5]).

The (κ, μ) -nullity distribution of a contact metric manifold $M = (M^{2n+1}, \varphi, \xi, \eta, g)$ for the pair $(\kappa, \mu) \in \mathbb{R}^2$ is a distribution

$$\mathcal{N}(\kappa,\mu): p \to \mathcal{N}_p(\kappa,\mu) = \left\{ W \in T_p M : R(U,V)W = \kappa \left(g(V,W)U - g(U,W)V \right) + \mu(g(V,W)hU - g(U,W)hV) \right\},$$

where *R* is the curvature tensor of the contact metric manifold *M* (see [2]) and *h* is a (1, 1)-tensor field defined by $hU = \frac{1}{2} (\mathcal{L}_{\xi} \varphi) U$ where \mathcal{L}_{ξ} denotes Lie differentiation in the direction of ξ , where $U, V, W \in TM$. For a contact metric manifold, it is clear that $trh = trh\varphi = 0$.

If the characteristic vector field ξ belongs to the (κ , μ)-nullity distribution, then

$$R(U, V)\xi = \kappa \left(\eta(V)U - \eta(U)V\right) + \mu(\eta(V)hU - \eta(U)hV),$$

where $\kappa \leq 1$. If $\kappa = 1$, then $M = (M^{2n+1}, \varphi, \xi, \eta, g)$ is Sasakian. If the characteristic vector field ξ belongs to the (κ, μ) -nullity distribution, then the contact metric manifold is called a (κ, μ) -contact metric manifold [2].

3. Hypersurfaces of Kaehler Manifolds

Let *M* be a (2n + 1)-dimensional orientable hypersurface isometrically embedded into a (2n + 2)dimensional Kaehler manifold $\widetilde{M} = (\widetilde{M}^{2n+2}, g, J)$ with almost complex structure *J* and Kaehlerian metric *g*. Let *v* be the unit normal vector field to *M*. Then the Gauss and Weingarten formulas are given by

$$\nabla_U V = D_U V + \sigma(U, V)v, \tag{2}$$

$$\widetilde{\nabla}_{U}v = -\mathcal{A}U,\tag{3}$$

where \mathcal{A} is the shape operator of M and \mathcal{A} and σ are related with $g(\mathcal{A}U, V) = \sigma(U, V), U, V \in TM$ [3]. Since v is the unit normal vector field, Jv is tangent to M. Setting

$$Jv = \xi, \tag{4}$$

$$JX = \varphi X - \eta(X)v,\tag{5}$$

where φ is a (1, 1)-tensor field, η is a 1-form and $X \in TM$.

From (4) by differentiation along *M*, and by the use of (2) and (3), we have

 $D_X \xi = -\varphi \mathcal{A} X.$

Hence because of (4) and (5), (η, ξ, φ, g) defines an almost contact metric structure on *M*. From (5), by differentiation along *M*, and by using of (2) and (3), we find

$$(D_X \varphi) Y = \sigma(X, Y) \xi - \eta(Y) \mathcal{A} X,$$

(see [13]).

We suppose that the almost contact metric structure induced on M is a contact metric structure. Such a hypersurface is called a *contact hypersurface of the Kaehler manifold* \widetilde{M} [13]. By easy calculations, we have the following formulas (see [13]):

$$\mathcal{A}\xi = (tr(\mathcal{A}) - 2n)\xi \tag{6}$$

and

$$\mathcal{A}X = X + hX + (tr(\mathcal{A}) - 2n - 1)\eta(X)\xi.$$
(7)

From [13], we know that a contact hypersurface of a Kaehler manifold is a Hopf hypersurface. Because of this reason, to study on a contact hypersurface of a Kaehler manifold is more interesting than other real hypersurfaces of a Kaehler manifold (see [13]). For more details about hypersurfaces of Kaehler manifolds, we refer to [9], [10] and [14].

4. Main Results

Let M be a contact hypersurface of a Kaehler manifold \widetilde{M} . Similar to the definition of a metallic shaped hypersurface in a real space form given in [11], we can define the metallic shaped contact hypersurface of a Kaehler manifold as follows:

Definition 4.1. Let M be a contact hypersurface in a Kaehler manifold M. Then M is called metallic shaped, if the shape operator \mathcal{A} of M satisfies the condition

$$\mathcal{A}^2 X = \mathfrak{p} \mathcal{A} X + \mathfrak{q} X \tag{8}$$

for any vector field X in TM, which is not parallel to the characteristic vector field ξ , where \mathfrak{p} and \mathfrak{q} are positive integers.

From (7), we have

$$\mathcal{A}^2 X = \mathcal{A}(\mathcal{A}X) = \mathcal{A}X + \mathcal{A}hX + (tr(\mathcal{A}) - 2n - 1)\eta(X)\mathcal{A}\xi.$$

Then using (6) and (7), we get

$$\mathcal{A}^{2}X = X + 2hX + h^{2}X + (tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1)\eta(X)\xi.$$
(9)

Since *M* is a metallic shaped contact hypersurface, from (7), (8) and (9), it follows that

 $(1 - p - q)X + (2 - p)hX + h^{2}X + (tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1 - p)\eta(X)\xi = 0.$

Contracting the last equation, we find

$$(1 - p - q)(2n + 1) + trh^{2} + (tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1 - p) = 0.$$
(10)

Then we can state the following Lemma:

Lemma 4.2. Let *M* be a metallic shaped contact hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} . Then the condition (10) is satisfied on *M*.

Now assume that *M* is a non-Sasakian (κ , μ)-contact metric hypersurface of a Kaehler manifold \widetilde{M}^{2n+2} . From [2], we know that for an (2n + 1)-dimensional (κ , μ)-contact metric manifold, we have $h^2 = (\kappa - 1) \varphi^2$, which implies $trh^2 = 2n (1 - \kappa)$. So substituting $trh^2 = 2n (1 - \kappa)$ in (10), we get

$$(1 - p - q)(2n + 1) + 2n(1 - \kappa) + (tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1 - p) = 0$$

or equivalently

$$(tr\mathcal{A})^2 - (4n + \mathfrak{p})tr\mathcal{A} + 4n^2 + 2n(2 - \kappa - \mathfrak{q}) - \mathfrak{q} = 0.$$
⁽¹¹⁾

This gives us

$$tr(\mathcal{A}) = \frac{(4n+\mathfrak{p}) \mp \sqrt{\mathfrak{p}^2 + 8n(\mathfrak{p}+\mathfrak{q}+\kappa-2) + 4\mathfrak{q}}}{2},$$

which is a constant, since \mathfrak{p} and \mathfrak{q} are positive integers.

Then we can state the following result:

Theorem 4.3. Let *M* be a metallic shaped (κ, μ) -contact metric hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} . Then *M* has constant mean curvature $H = \frac{(4n+p)+\sqrt{p^2+8n(p+q+\kappa-2)+4q}}{2(2n+1)}$ or $H = \frac{(4n+p)-\sqrt{p^2+8n(p+q+\kappa-2)+4q}}{2(2n+1)}$.

If *M* is a Sasakian hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} , then $\kappa = 1$. So we have the following corollary:

Corollary 4.4. Let *M* be a metallic shaped Sasakian hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} . Then *M* has constant mean curvature $H = \frac{(4n+p)+\sqrt{p^2+8n(p+q-1)+4q}}{2(2n+1)}$ or $H = \frac{(4n+p)-\sqrt{p^2+8n(p+q-1)+4q}}{2(2n+1)}$.

If *M* is a Sasakian hypersurface with unit mean curvature in a Kaehler manifold \widetilde{M}^{2n+2} , then from (11), we have

 $(1 - \mathfrak{p} - \mathfrak{q})(2n + 1) = 0,$

which is impossible, since \mathfrak{p} and \mathfrak{q} are positive integers.

Hence we obtain the following result:

Theorem 4.5. There does not exist a metallic shaped Sasakian hypersurface with unit mean curvature in a Kaehler manifold \widetilde{M}^{2n+2} .

Now assume that *M* is a metallic shaped (κ , μ)-contact metric hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} . From the Gauss equation, we have

$$\overline{Ric}(X,Y) - \widetilde{g}(\overline{R}(v,X)Y,v) = Ric(X,Y) + g(\mathcal{A}X,\mathcal{A}Y) - tr(\mathcal{A})g(\mathcal{A}X,Y),$$

where *Ric* and *Ric* denote the Ricci tensors of *M* and M^{2n+2} , respectively. By a contraction from the last equation, we have

$$\widetilde{scal} - 2\widetilde{Ric}(v,v) = scal + ||\mathcal{A}||^2 - (tr(\mathcal{A}))^2,$$
(12)

where *scal* and *scal* denote the scalar curvatures of *M* and \widetilde{M}^{2n+2} , respectively. Now assume that \widetilde{M}^{2n+2} is an Kaehler Einstein manifold. So we can write $\widetilde{Ric}(X, Y) = \lambda \widetilde{g}(X, Y)$ for some constant λ . By a contraction, the scalar curvature of \widetilde{M}^{2n+2} is $\widetilde{scal} = (2n + 2)\lambda$. On the other hand by equation (8), we have $||\mathcal{A}||^2 = ptr(\mathcal{A}) + (2n + 1)q$. Hence the equation (12) turns into

$$2n\lambda = scal + \mathfrak{p}tr(\mathcal{A}) + (2n+1)\mathfrak{q} - (tr(\mathcal{A}))^2.$$
⁽¹³⁾

So from Theorem 4.3, since $tr(\mathcal{A})$ is a constant for a metallic shaped (κ, μ)-contact metric hypersurface in a Kaehler manifold \widetilde{M}^{2n+2} , the equation (13) gives us the scalar curvature *scal* of *M* is a constant.

Then we can state the following theorem:

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Theorem 4.6. Let *M* be a metallic shaped (κ , μ)-contact metric hypersurface in an Kaehler Einstein manifold \widetilde{M}^{2n+2} . Then *M* has constant scalar curvature.

Complex manifolds with a Ricci-flat Kaehler metric are called *Calabi-Yau manifolds* [15]. A Calabi-Yau manifold is not a complex space-form, if it is not flat [15].

Now assume that M is a metallic shaped (κ , μ)-contact metric hypersurface in a Calabi-Yau manifold \widetilde{M}^{2n+2} . Then from (12), we have

$$scal + ||\mathcal{A}||^2 - (tr(\mathcal{A}))^2 = 0.$$
 (14)

Since for a metallic shaped (κ , μ)-contact metric hypersurface of a Kaehler manifold, $tr(\mathcal{A})$ and $||A||^2$ are constants, from (14), the scalar curvature *scal* of *M* is also a constant.

So we have the following result:

Corollary 4.7. Let *M* be a metallic shaped (κ , μ)-contact metric hypersurface in a Calabi-Yau manifold \widetilde{M}^{2n+2} . Then *M* has constant scalar curvature.

If the second fundamental form of a contact metric hypersurface *M* of a Kaehler manifold is a linear combination of the metric tensor and $\eta \otimes \eta$, then *M* is called a *C-umbilical hypersurface* [13].

Now assume that *M* is a product-shaped hypersurface in a Kaehler manifold \widetilde{M} . Then its shape operator satisfies the condition $\mathcal{A}^2 = I$. Hence from (10), we have

 $trh^{2} + (tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1) = 0.$

If *M* is Sasakian, then $(tr(\mathcal{A}) - 2n - 1)(tr(\mathcal{A}) - 2n + 1) = 0$. Since $tr(\mathcal{A})$ is a constant, the last equation gives us either $tr(\mathcal{A}) = 2n + 1$ or $tr(\mathcal{A}) = 2n - 1$. If $tr(\mathcal{A}) = 2n + 1$, then it has unit mean curvature and moreover from (7), it is totally umbilical. If *M* is 3-dimensional and \widetilde{M} is a 4-dimensional Calabi-Yau manifold, then \widetilde{M} is flat at each point of *M* (see the proof of Theorem 2 in [13]). If $tr(\mathcal{A}) = 2n - 1$, then from (7), $\mathcal{A}X = X - 2\eta(X)\xi$. Hence *M* is *C*-umbilical.

Thus we obtain the following theorem:

Theorem 4.8. Let *M* be a Sasakian hypersurface in a Kaehler manifold \widetilde{M} . Then *M* is product shaped if and only if either *M* is totally umbilical with unit mean curvature (if *M* is 3-dimensional and \widetilde{M} is a 4-dimensional Calabi-Yau manifold, then \widetilde{M} is flat at each point of *M*) or *M* is a C-umbilical hypersurface whose shape operator \mathcal{A} is of the form $\mathcal{A} = I - 2\eta \otimes \xi$.

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