



Explore the study of the fractional differential equation containing the right Hilfer derivative

Belqassim Azzouz^a

^a*Department of Mathematics, Ahmed Zabana University of Relizane, Algeria
Laboratory of Fundamental and Applied Mathematics of Oran (LMFAO),
University of Oran 1, Ahmed Ben Bella, Oran, Algeria*

Abstract. Motivated by the Hilfer fractional derivative, we introduced a new problem involving the right Hilfer fractional operator. We present some important results through the use of lemmas. In this context, we discuss the existence and uniqueness of the solution using the Krasnoselskii fixed point theorem. Finally, we also demonstrate the application of the obtained results with the aid of an example.

1. Introduction

In recent years, the scientific community has focused more attention on fractional differential equations, as they are effective tools in modeling many phenomena in applied sciences and engineering applications such as acoustic control, rheology, polymer physics, porous media, medicine, electrochemistry, proteins, electromagnetics, economics, astrophysics, chemical engineering, signal processing, optics, chaotic dynamics, statistical physics, etc. (For details and examples, one may refer to papers [13, 14, 17, 19, 21] and references cited therein). Over the years, many researchers have been interested in discussing the qualitative analysis of fractional differential equations, including existence and uniqueness, as seen in [1, 6, 10, 11, 15]. Some authors have dedicated their efforts to further qualitative analysis of these kinds of equations. Many related articles on the existence and uniqueness of fractional differential equations under different types can be found, as seen in [2, 4, 5, 7, 9, 16]. Recently, the study of the existence and uniqueness of solutions of fractional integral equations through integral operators such as Caputo, Riemann-Liouville, Hadamard, Katugampola, and Hilfer has gained prominence in both analytical and functional contexts (Abbas et al. 2018). A significant amount of research has been completed so far on fractional differential equations involving Hilfer derivatives with initial and boundary conditions; therefore, it is worth further consideration. In [8], K. M. Furati et al. studied Hilfer fractional differential equations. In 2015, in the same context, J. Wang and Y. Zang investigated the existence of a solution to a nonlocal IVP for Hilfer fractional differential equations. For details, see [24]. In this regard, in [23], the authors considered implicit fractional equations with nonlocal conditions. In [12], S. Harikrishnan et al. studied the existence and stability results

2020 *Mathematics Subject Classification.* Primary 34A08; Secondary 26A33.

Keywords. The Weighted space, The right Riemann-liouville fractional derivative and integral, The right Hilfer fractional derivative, Existence and uniqueness.

Received: 13 August 2025; Accepted: 14 August 2025

Communicated by Maria Alessandra Ragusa

Email address: belqassim.azzouz@univ-relizane.dz (Belqassim Azzouz)

ORCID iD: <https://orcid.org/0009-0009-4132-7812> (Belqassim Azzouz)

for Langevin equations with Hilfer fractional derivatives. Further, in [20], Suphawat et al. studied the nonlocal BVP.

$${}_H\mathfrak{D}_{a+}^{p,\nu}\vartheta(u) = R(u, \vartheta(u)), \quad 1 < p < 2, \quad 0 \leq \nu \leq 1 \quad u \in [a, b],$$

with the integral boundary conditions

$$\vartheta(a) = 0, \quad \vartheta(b) = \sum_{i=1}^m \lambda_i \mathfrak{I}_{a+}^{\gamma_i} \vartheta(\mu_i), \quad \gamma_i > 0 \quad \lambda_i \in \mathbb{R} \quad \mu_i \in [a, b].$$

The Banach contraction mapping principle, Banach fixed point theorem with Hölder inequality, nonlinear contraction, Krasnoselskii's fixed point theorem, and the nonlinear Leray-Schauder alternative are employed to prove the existence of a solution to the integral boundary value problem (BVP).

Recently, Mohamed S. Abdo et al. [18] discussed the existence of a solution for Hilfer fractional differential equations with boundary value conditions

$$\begin{cases} {}^H D_{a+}^{p,\nu} y(s) = R(s, y(s)), & s \in [a, b], \\ \mathfrak{I}_{a+}^{1-\xi} [cy(a^+) + dy(b^-)] = e_i, & c, d, e_i \in \mathbb{R}, \quad \xi = p + \nu(1-p), \end{cases}$$

where ${}^H D_{a+}^{p,\nu}(\cdot)$ is the left Hilfer fractional derivative of order p with $0 < p < 1$ and type ν with $0 \leq \nu \leq 1$, $\mathfrak{I}_{a+}^{1-\xi}(\cdot)$ is the left Riemann-Liouville fractional integral of order $1 - \xi$, $R : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. They obtained several existence results using Schauder's, Schaefer's, and Krasnoselskii's fixed-point theorems.

Motivated by the aforementioned works, this paper considers the following boundary value problem for a class of right Hilfer fractional differential equations

$$(\mathbb{P}\tau) \begin{cases} {}_H\mathfrak{D}_{b-}^{p,\nu}\vartheta(u) = R(u, \vartheta(u), \vartheta(\tau u)), & 0 < \tau < 1, \quad u \in [a, b], \\ \mathfrak{I}_{b-}^{1-\gamma}\vartheta(b) = \sum_{i=1}^m \lambda_i \vartheta(\mu_i) + \vartheta_b, & \gamma = p + \nu - \nu p, \quad \mu_i \in [a, b], \end{cases}$$

where ${}_H\mathfrak{D}_{b-}^{p,\nu}(\cdot)$ represents the right Hilfer fractional derivative of order p with $0 < p < 1$ and type ν with $0 \leq \nu \leq 1$, $\mathfrak{I}_{b-}^{1-\gamma}(\cdot)$ is the right Riemann-Liouville fractional integral of order $1 - \gamma$, $R : [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function, μ_i ($i = 0, 1, \dots, m$) are prefixed points satisfying $a < \mu_1 < \dots < \mu_m < b$, λ_i is real numbers and ϑ_b is a constant.

The rest of the paper is organized as follows: In Section 2, essential definitions and useful lemmas are provided. In Section 3, we discuss the suitable conditions for the existence and uniqueness of the solution to (1.1) – (1.2). Section 4 focuses on an application to illustrate the results.

2. An auxiliary results

In this section, we present some background material for the forthcoming analysis. Interested readers can refer to [3, 14, 22].

Definition 2.1. Let $u, w \in \mathbb{C}$, such that $\operatorname{Re}(u) > 0$, $\operatorname{Re}(w) > 0$. Then,

a) The gamma function Γ is given as

$$\Gamma(u) = \int_0^\infty t^{u-1} e^{-t} dt, \quad \text{where } \Gamma(u+1) = u\Gamma(u).$$

b) The beta function β is defined as follows

$$\beta(u, w) = \int_0^1 t^{u-1} (1-t)^{w-1} dt, \quad \text{so that } \beta(u, w) = \frac{\Gamma(u)\Gamma(w)}{\Gamma(u+w)}.$$

Definition 2.2. Let $\mathfrak{S} \in L^1[a, b]$. Then, the right Riemann-Liouville fractional integral of order $p > 0$ is defined by

$$\mathfrak{I}_{b-}^p \mathfrak{S}(u) = \frac{1}{\Gamma(p)} \int_u^b (t-u)^{p-1} \mathfrak{S}(t) dt.$$

Definition 2.3. Let $u \in [a, b]$, $q \in \mathbb{N}$ such that $q = [p]$ and $\mathfrak{S} \in C[a, b]$. Then, the right Riemann-Liouville fractional derivative of order p is defined by

$${}_{RL}\mathfrak{D}_{b-}^p \mathfrak{S}(u) = \left(-\frac{d}{du}\right)^q \mathfrak{I}_{b-}^{q-p} \mathfrak{S}(u).$$

Definition 2.4. Let $p > 0$, $q \in \mathbb{N}$, $q-1 < p \leq q$, $\gamma = p + v(q-p)$, $v \in [0, 1]$, $u \in [a, b]$ and $\mathfrak{S} \in C^q[a, b]$. Then, the right Hilfer fractional derivative of order p and type v is determined as

$${}_H\mathfrak{D}_{b-}^{p,v} \mathfrak{S}(u) = \mathfrak{I}_{b-}^{v(q-p)} \left(-\frac{d}{du}\right)^q \mathfrak{I}_{b-}^{(1-v)(q-p)} \mathfrak{S}(u).$$

Now, we consider the weighted space of continuous function

$$C_{1-\gamma}[a, b] = \left\{ \mathfrak{S} : [a, b[\longrightarrow \mathbb{R}, (b-u)^{1-\gamma} \mathfrak{S}(u) \in C[a, b] \right\} \text{ where } 0 < \gamma \leq 1,$$

with the norm

$$\|\mathfrak{S}\|_{C_{1-\gamma}[a, b]} = \max_{u \in [a, b]} |(b-u)^{1-\gamma} \mathfrak{S}(u)|,$$

and

$$C_{1-\gamma}^q[a, b] = \left\{ \mathfrak{S} : [a, b[\longrightarrow \mathbb{R}, \left(-\frac{d}{du}\right)^{q-1} \mathfrak{S}(u) \in C[a, b] \text{ and } \left(-\frac{d}{du}\right)^q \mathfrak{S}(u) \in C_{1-\gamma}[a, b] \right\},$$

we also introduce the spaces

$$C_{1-\gamma}^{p,v}[a, b] = \left\{ \mathfrak{S} : [a, b[\longrightarrow \mathbb{R}, \mathfrak{S} \in C_{1-\gamma}[a, b] \text{ and } {}_H\mathfrak{D}_{b-}^{p,v} \mathfrak{S} \in C_{1-\gamma}[a, b] \right\},$$

and

$$C_{1-\gamma}^\gamma[a, b] = \left\{ \mathfrak{S} : [a, b[\longrightarrow \mathbb{R}, \mathfrak{S} \in C_{1-\gamma}[a, b] \text{ and } {}_{RL}\mathfrak{D}_{b-}^\gamma \mathfrak{S} \in C_{1-\gamma}[a, b] \right\}.$$

Lemma 2.5. Let $\mathfrak{k}_1, \mathfrak{k}_2 > 0$. Then we have the following semigroup property

$$\mathfrak{I}_{b-}^{\mathfrak{k}_1} \mathfrak{I}_{b-}^{\mathfrak{k}_2} = \mathfrak{I}_{b-}^{\mathfrak{k}_1 + \mathfrak{k}_2}.$$

Lemma 2.6. Let $p > 0$, $q \in \mathbb{N}$ such that $q = [p]$. Then,

$$(1) {}_{RL}\mathfrak{D}_{b-}^p \mathfrak{I}_{b-}^p \mathfrak{S}(u) = \mathfrak{S}(u). \text{ If } \mathfrak{S} \in C_{q-\gamma}[a, b]$$

$$(2) \left(-\frac{d}{du}\right)^q \mathfrak{I}_{b-}^q \mathfrak{S}(u) = \mathfrak{S}(u). \text{ If } \mathfrak{S} \in C[a, b].$$

Lemma 2.7. Let $p \in \mathbb{R}_+$ with $p < 1$, $v \in [0, 1]$ and $\gamma = p + v - vp$. If $\mathfrak{S} \in C_{1-\gamma}^\gamma[a, b]$, Then,

$${}_{RL}\mathfrak{D}_{b-}^\gamma \mathfrak{I}_{b-}^p \mathfrak{S}(u) = {}_{RL}\mathfrak{D}_{b-}^{v-vp} \mathfrak{S}(u).$$

and

$$\mathfrak{I}_{b-}^\gamma {}_{RL}\mathfrak{D}_{b-}^\gamma \mathfrak{S}(u) = \mathfrak{I}_{b-}^p {}_H\mathfrak{D}_{b-}^{p,v} \mathfrak{S}(u).$$

Proposition 2.8. Let $\mathfrak{l} > 0$, and let $\gamma \in \mathbb{R}$ such that $\gamma > -1$. Then fractional integral and derivative of a power function are given by

$$\mathfrak{I}_{b-}^{\mathfrak{l}} (b-u)^{\gamma} = \frac{\Gamma(\gamma+1)}{\Gamma(\gamma+1+\mathfrak{l})} (b-u)^{\gamma+\mathfrak{l}}.$$

and

$${}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} (b-u)^{\gamma} = \frac{\Gamma(\gamma+1)}{\Gamma(\gamma+1-\mathfrak{l})} (b-u)^{\gamma-\mathfrak{l}}.$$

Moreover, If $0 < \mathfrak{l} < 1$, then

$${}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} (b-u)^{\mathfrak{l}} = 0$$

Lemma 2.9. Let $\mathfrak{l}, \sigma \in \mathbb{R}_+$ with $\sigma < 1$ and $q = [\mathfrak{l}]$. If $\mathfrak{S} \in C_{\sigma}[a, b]$ and $\mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S} \in C_{\sigma}^q[a, b]$. Then,

$$\mathfrak{I}_{b-}^{\mathfrak{l}} \left[{}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u) \right] = (-1)^{q+1} \left[\mathfrak{S}(u) - \sum_{i=1}^q \frac{(b-u)^{\mathfrak{l}-i}}{\Gamma(\mathfrak{l}-i+1)} \left[\left(\frac{d}{du} \right)^{q-i} \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(u) \right]_{u=b} \right].$$

Proof. First, by the lemma 2.6-(2). Taking $q = 1$, we have

$$\left(-\frac{d}{du} \right) \mathfrak{I}_{b-}^1 \mathfrak{S}(u) = \mathfrak{S}(u). \quad (1)$$

Using the equation (1) with $\mathfrak{S}(u)$ replaced by $\mathfrak{I}_{b-}^{\mathfrak{l}} {}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u)$, we have

$$\mathfrak{I}_{b-}^{\mathfrak{l}} \left({}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u) \right) = \left(-\frac{d}{du} \right) \mathfrak{I}_{b-}^1 \left[\mathfrak{I}_{b-}^{\mathfrak{l}} \left({}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u) \right) \right]. \quad (2)$$

From the relation (2) and the definition of the right Riemann-liouville fractional integrals, and derivative, we have

$$\begin{aligned} \mathfrak{I}_{b-}^{\mathfrak{l}} \left({}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u) \right) &= \left(-\frac{d}{du} \right) \left[\mathfrak{I}_{b-}^{1+\mathfrak{l}} \left({}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(u) \right) \right] \\ &= \left(-\frac{d}{du} \right) \left[\frac{1}{\Gamma(\mathfrak{l}+1)} \int_u^b (t-u)^{\mathfrak{l}} {}_{RL}\mathfrak{D}_{b-}^{\mathfrak{l}} \mathfrak{S}(t) dt \right] \\ &= \left(-\frac{d}{du} \right) \left[\frac{(-1)^q}{\Gamma(\mathfrak{l}+1)} \int_u^b (t-u)^{\mathfrak{l}} \left(\frac{d}{dt} \right)^q \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(t) dt \right]. \end{aligned} \quad (3)$$

Integration by parts the relation

$$\begin{aligned} \frac{1}{\Gamma(\mathfrak{l}+1)} \int_u^b (t-u)^{\mathfrak{l}} \left(\frac{d}{dt} \right)^q \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(t) dt \\ &= \frac{1}{\Gamma(\mathfrak{l}+1)} \int_u^b (t-u)^{\mathfrak{l}} \frac{d}{dt} \left[\left(\frac{d}{dt} \right)^{q-1} \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(t) \right] dt \\ &= \frac{1}{\Gamma(\mathfrak{l}+1)} (b-u)^{\mathfrak{l}} \left[\left(\frac{d}{dt} \right)^{q-1} \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(t) \right]_{t=b} \\ &\quad - \frac{1}{\Gamma(\mathfrak{l})} \int_u^b (t-u)^{\mathfrak{l}-1} \frac{d}{dt} \left[\left(\frac{d}{dt} \right)^{q-2} \mathfrak{I}_{b-}^{q-\mathfrak{l}} \mathfrak{S}(t) \right] dt. \end{aligned} \quad (4)$$

Repeating the proces of integration by parts n^{th} step, we have

$$(4) = \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+2)} (b-t)^{(l-j+1)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \\ - \frac{1}{\Gamma(l-(q-1))} \int_u^b (t-u)^{l-q} \left(\frac{d}{dt} \right)^{q-q} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) dt.$$

Now, consider using the definition of right Riemann-liouville fractional integrale, its semi groupe property, we have

$$(4) = \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+2)} (b-u)^{(l-j+1)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \\ - \frac{1}{\Gamma(l+1-q)} \int_u^b (t-u)^{(l+1-q-1)} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) dt. \\ = \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+2)} (b-u)^{(l-j+1)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \\ - \mathfrak{I}_{b-}^{l+1-q} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(u) \\ = \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+2)} (b-u)^{(l-j+1)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \\ - \int_u^b \mathfrak{S}(t) dt. \quad (5)$$

Using the equation (3) in the equation (5), we get

$$\mathfrak{I}_{b-}^l {}_{RL} \mathfrak{D}_{b-}^l \mathfrak{S}(u) = (-1)^{q+1} \frac{d}{du} \left\{ - \int_u^b \mathfrak{S}(t) dt \right. \\ \left. + \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+2)} (b-u)^{(l-j+1)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \right\} \\ = (-1)^{q+1} \left[\mathfrak{S}(u) - \sum_{j=1}^{j=q} \frac{1}{\Gamma(l-j+1)} (b-u)^{(l-j)} \left[\left(\frac{d}{dt} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(t) \right]_{t=b} \right] \\ = (-1)^{q+1} \left[\mathfrak{S}(u) - \sum_{j=1}^{j=q} \frac{(b-u)^{l-j}}{\Gamma(l-j+1)} \left[\left(\frac{d}{du} \right)^{q-j} \mathfrak{I}_{b-}^{q-l} \mathfrak{S}(u) \right]_{u=b} \right].$$

□

Lemma 2.10. Let $p \in \mathbb{R}$ with $p < 1$, $v \in [0, 1]$ and $\gamma = p + v - vp$.

Suppose $R : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ is a function such that $R(., \vartheta(.)) \in C_{1-\gamma}[a, b]$,

for any $\vartheta \in C_{1-\gamma}[a, b]$.

If $\vartheta \in C_{1-\gamma}^\gamma[a, b]$ then ϑ satisfies the problem (IP)

$$(IP) \begin{cases} {}_H \mathfrak{D}_{b-}^{p,\gamma} \vartheta(u) = R(u, \vartheta(u)), & u \in [a, b], \\ \mathfrak{I}_{b-}^{1-\gamma} \vartheta(b) = \vartheta_b, \end{cases}$$

if and only if ϑ satisfies the following fractional integral equation

$$\vartheta(u) = \frac{(b-u)^{\gamma-1}}{\Gamma(\gamma)} \vartheta_b + \frac{1}{\Gamma(p)} \int_u^b (t-u)^{p-1} R(t, \vartheta(t)) dt, \quad u \in [a, b]. \quad (6)$$

Theorem 2.11. Let $l, \sigma \in \mathbb{R}_+$ with $\sigma < 1$. Then, the right Riemann-Liouville fractional integral $\mathfrak{I}_{b-}^l(\cdot)$ is bounded from $C_{1-\gamma}[a, b]$ into $C_{1-\gamma}[a, b]$.

Theorem 2.12. Let $l > 0, \sigma > 0$, with $\sigma \leq l < 1$. Then, the right Riemann-Liouville fractional integral \mathfrak{I}_{b-}^l is bounded from $C_\sigma[a, b]$ and to $C[a, b]$.

Theorem 2.13. Let $0 < l, 0 < \gamma \leq 1$ and $\vartheta \in C_{1-\gamma}[a, b]$. If $l > \gamma$, then $\mathfrak{I}_{b-}^l(\cdot) \in C[a, b]$ and

$$\mathfrak{I}_{b-}^l \vartheta(b) = \lim_{u \rightarrow b-} \mathfrak{I}_{b-}^l \vartheta(u) = 0.$$

Theorem 2.14. Let $p > 0, 0 \leq \nu \leq 1$ and $\vartheta \in L^1[a, b]$. Assume that ${}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} \vartheta(u)$ exists it lies in $L^1[a, b]$. Then,

$${}_H\mathfrak{D}_{b-}^{p,\nu} \mathfrak{I}_{b-}^p \vartheta(u) = \mathfrak{I}_{b-}^{\nu(1-p)} {}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} \vartheta(u), \quad u \in [a, b].$$

Moreover, if $\vartheta \in C_{1-\gamma}[a, b]$, $\mathfrak{I}_{b-}^{\nu(1-p)} \vartheta \in C_{1-\gamma}^1[a, b]$, then ${}_H\mathfrak{D}_{b-}^{p,\nu} \mathfrak{I}_{b-}^p \vartheta(\cdot)$ exists on $[a, b]$ and

$${}_H\mathfrak{D}_{b-}^{p,\nu} \mathfrak{I}_{b-}^p \vartheta(u) = \vartheta(u), \quad u \in [a, b].$$

Theorem 2.15. Let $0 < p < 1, 0 \leq \nu \leq 1$ and $\gamma = p + \nu - \nu p$. If $\vartheta \in C_{1-\gamma}^\gamma[a, b]$, then

$$\mathfrak{I}_{b-}^\gamma {}_{RL}\mathfrak{D}_{b-}^\gamma \vartheta(u) = \mathfrak{I}_{b-}^p {}_H\mathfrak{D}_{b-}^{p,\nu} \vartheta(u)$$

Theorem 2.16. (Krasnoselskii's fixed point theorem) Let Ω be a closed convex and nonempty subset of a Banach space X , let T_1, T_2 be the operators such that

a) $T_1 x + T_2 \vartheta \in \Omega$ for every pair $x, \vartheta \in \Omega$.

b) T_1 is compact and continuous.

c) T_2 is a contraction mapping.

Then there exists $z \in \Omega$ such that $z = T_1 z + T_2 z$.

Theorem 2.17. (Banach fixed point theorem) Let $(X; d)$ be a nonempty complete metric space with $T : X \rightarrow X$ is a contraction mapping. Then map T has a fixed point.

Lemma 2.18. Let $\gamma = p + \nu - \nu p$ where $0 < p < 1, \nu \in [0, 1]$. Assume that

$R : [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be a function such that $R(\cdot, \vartheta(\cdot), \vartheta(\tau)) \in C_{1-\gamma}[a, b]$, for any $\vartheta \in C_{1-\gamma}[a, b]$. If $\vartheta \in C_{1-\gamma}^\gamma[a, b]$ then ϑ satisfies the problem $(\mathbb{P}\tau)$ if and only if ϑ satisfies the following fractional integral equation

$$\begin{aligned} \vartheta(u) = & \frac{(b-u)^{\gamma-1}}{\Gamma(\gamma) - \sum_{i=1}^m \lambda_i [(b-\mu_i)]^{\gamma-1}} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b (t-\mu_i)^{p-1} \right. \\ & \left. \times R(t, \vartheta(t), \vartheta(\tau t)) dt + \vartheta_b \right] + \frac{1}{\Gamma(p)} \int_u^b (t-u)^{p-1} R(t, \vartheta(t), \vartheta(\tau t)) dt, \quad u \in [a, b]. \end{aligned}$$

For the sake of convenience, we use the following notations :

$$\Theta_-^\gamma(b, \cdot) = (b - \cdot)^{\gamma-1}, \quad R(t, \vartheta(t), \vartheta(\tau t)) = \vartheta(t),$$

and

$$\Theta_-^{-\gamma}(b, \cdot) = (b - \cdot)^{-\gamma+1}, \quad \mathcal{L} = \Gamma(\gamma) - \sum_{i=1}^m \lambda_i \Theta_-^\gamma(b, \mu_i) \neq 0.$$

Now, we can write

$$\vartheta(u) = \frac{\Theta_-^\gamma(b, u)}{\mathcal{E}} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \varpi(t) dt + \vartheta_b \right] + \frac{1}{\Gamma(p)} \int_u^b \Theta_-^p(t, u) \varpi(t) dt. \quad (7)$$

Proof. Assume that $\vartheta \in C_{1-\gamma}^\gamma[a, b]$ is a solution to the problem $(\mathbb{P}\tau)$. We show that ϑ is also a solution of fractional integrale Equation (7).

Since $\vartheta \in C_{1-\gamma}^\gamma[a, b]$, we have $\vartheta \in C_{1-\gamma}[a, b]$ and

$$\left[-\frac{d}{u} \right] \mathfrak{I}_{b-}^{1-\gamma} \vartheta = {}_{RL}\mathfrak{D}_{b-}^\gamma \vartheta \in C_{1-\gamma}[a, b]. \quad (8)$$

Further, by applying Theorem 2.12 with $l = 1 - \gamma$, we get

$$\mathfrak{I}_{b-}^{1-\gamma} \vartheta \in C[a, b]. \quad (9)$$

According to Equation (8) and (9) and using the definition of the space $C_{1-\gamma}^q[a, b]$, we obtain

$$\mathfrak{I}_{b-}^{1-\gamma} \vartheta \in C_{1-\gamma}^1[a, b].$$

Sinc $\vartheta \in C_{1-\gamma}[a, b]$ and $\mathfrak{I}_{b-}^{1-\gamma} \vartheta \in C_{1-\gamma}^1[a, b]$, by applying the lemma 2.9 with $\sigma = 1 - \gamma$, $l = \gamma$ and $q = [\gamma] = 1$, we get

$$\mathfrak{I}_{b-}^\gamma {}_{RL}\mathfrak{D}_{b-}^\gamma \vartheta(u) = \vartheta(u) - \frac{\Theta_-^\gamma(b, u)}{\Gamma(\gamma)} [\mathfrak{I}_{b-}^{1-\gamma} \vartheta(u)]_{u=b}. \quad (10)$$

By hypothesis ${}_{RL}\mathfrak{D}_{b-}^\gamma \vartheta \in C_{1-\gamma}[a, b]$, using Lemma 2.7 and Equation (1), we have

$$\mathfrak{I}_{b-}^\gamma {}_{RL}\mathfrak{D}_{b-}^\gamma \vartheta(u) = \mathfrak{I}_{b-}^p {}_H\mathfrak{D}_{b-}^{p,\gamma} \vartheta(u) = \mathfrak{I}_{b-}^p \varpi(u). \quad (11)$$

Comparing Equation (10) and (11), we see that

$$\vartheta(u) = \frac{\Theta_-^\gamma(b, u)}{\Gamma(\gamma)} [\mathfrak{I}_{b-}^{1-\gamma} \vartheta(u)]_{u=b} + \mathfrak{I}_{b-}^p \varpi(u) \quad (12)$$

Now, we substitute $u = \mu_i$ in (12) and multiply by λ_i we can write

$$\lambda_i \vartheta(\mu_i) = \lambda_i \frac{\Theta_-^\gamma(b, \mu_i)}{\Gamma(\gamma)} [\mathfrak{I}_{b-}^{1-\gamma} \vartheta(u)]_{u=b} + \lambda_i \mathfrak{I}_{b-}^p \varpi(\mu_i).$$

The last equality with the nonlocal condition (1), gives us

$$\mathfrak{I}_{a+}^{1-\gamma} \vartheta(b) = \sum_{i=1}^m \lambda_i \vartheta(\mu_i) + \vartheta_b = \sum_{i=1}^m \lambda_i \frac{\Theta_-^\gamma(b, \mu_i)}{\Gamma(\gamma)} [\mathfrak{I}_{b-}^{1-\gamma} \vartheta(u)]_{u=b} + \sum_{i=1}^m \lambda_i \mathfrak{I}_{b-}^p \varpi(\mu_i).$$

We find

$$\mathfrak{I}_{b-}^{1-\gamma} \vartheta(b) = \frac{\Gamma(\gamma) \left(\sum_{i=1}^m \lambda_i \mathfrak{I}_{b-}^p \varpi(\mu_i) + \vartheta_b \right)}{\mathcal{E}}. \quad (13)$$

Substituting (13) into (12), we conclude that $\vartheta(u)$ satisfies (7).

Conversely, suppose that $\vartheta \in C_{1-\gamma}^\gamma[a, b]$ satisfying equation (7). Then,

$$\vartheta(u) = \frac{\Theta_-^\gamma(b, u)}{\mathcal{E}} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \varpi(t) dt + \vartheta_b \right] + \frac{1}{\Gamma(p)} \int_u^b \Theta_-^p(t, u) \varpi(t) dt.$$

Inserting ${}_{RL}\mathfrak{D}_{b-}^{\gamma}$ on both sides of above equation, we get

$${}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta(u) = \frac{{}_{RL}\mathfrak{D}_{b-}^{\gamma} \Theta_{-}^{\gamma}(b, u)}{\mathcal{E}} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_{-}^p(t, \mu_i) \mathfrak{S}(t) dt + \vartheta_b \right] + {}_{RL}\mathfrak{D}_{b-}^{\gamma} \mathfrak{I}_{b-}^p \mathfrak{S}(u).$$

By applying the Lemma 2.6 and Lemma 2.7 we obtain

$${}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta(u) = {}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} \mathfrak{S}(u). \quad (14)$$

Since $\vartheta \in C_{1-\gamma}^{\gamma}[a, b]$, and by Definition of $C_{1-\gamma}^{\gamma}[a, b]$, we have ${}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta \in C_{1-\gamma}[a, b]$. Therefore, from (14) it follows that

$${}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} R(u, \vartheta(u), \vartheta(\tau u)) \in C_{1-\gamma}[a, b]. \quad (15)$$

Since $p < 1$, $\nu \in [0, 1]$ and $0 < 1 - p < 1$, we obtain $\nu(1 - p) < 1$. Therefore

$$[\nu(1 - p)] = 1.$$

In this case the definition of Riemann-Liouville derivative reduce to

$${}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} R(u, \vartheta(u), \vartheta(\tau u)) = \left[-\frac{d}{du} \right] \mathfrak{I}_{b-}^{1-\nu(1-p)} R(u, \vartheta(u), \vartheta(\tau u)). \quad (16)$$

Clearly, by (15) and (16), we obtain

$$\left[-\frac{d}{du} \right] \mathfrak{I}_{b-}^{1-\nu(1-p)} R(u, \vartheta(u), \vartheta(\tau u)) \in C_{1-\gamma}[a, b]. \quad (17)$$

Since $\gamma = p + \nu - \nu p > \nu(1 - p)$, we have $1 - \gamma < 1 - \nu + \nu p$.

Since $\mathfrak{S}(\cdot) \in C_{1-\gamma}[a, b]$, by applying Theorem 2.12, we get

$$\mathfrak{I}_{b-}^{1-\nu(1-p)} \mathfrak{S}(\cdot) \in C[a, b]. \quad (18)$$

Using the definition of the space $C_{1-\gamma}^q[a, b]$, from equation (17) and (18), it follows that

$$\mathfrak{I}_{b-}^{1-\nu+\nu p} \mathfrak{S}(\cdot) \in C_{1-\gamma}^1[a, b].$$

By applying $\mathfrak{I}_{b-}^{\nu(1-p)}$ on both sides of equation (14) and using Lemma 2.9 with $l = \nu - \nu p$ and $q = 1$, we have

$$\begin{aligned} \mathfrak{I}_{b-}^{\nu(1-p)} {}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta(u) &= \mathfrak{I}_{b-}^{\nu(1-p)} {}_{RL}\mathfrak{D}_{b-}^{\nu(1-p)} \mathfrak{S}(t) \\ &= \mathfrak{S}(u) - \frac{\Theta_{-}^{\nu(1-p)}(b, u)}{\Gamma(\nu(1 - p))} \left[\mathfrak{I}_{b-}^{1-\nu(1-p)} \mathfrak{S}(b) \right]. \end{aligned} \quad (19)$$

Using the theorem 2.13 with $l = 1 - \nu(1 - p)$, we obtain

$$\left[\mathfrak{I}_{b-}^{1-\nu(1-p)} \mathfrak{S}(b) \right] = 0. \quad (20)$$

Comparing the last equality with (1), we get

$${}_H\mathfrak{D}_{b-}^{p,\nu} \vartheta(u) = \mathfrak{S}(u), \quad u \in [a, b].$$

which means that (1) holds. Next, we show that if $\vartheta \in C_{1-\gamma}^\gamma[a, b]$ satisfies (7), it also satisfies the condition (1).

To this end, we multiply both sides of (7) by $\mathfrak{T}_{b-}^{1-\gamma}$ and use Proposition 2.8 and Lemma 2.5, we have

$$\begin{aligned} \mathfrak{T}_{b-}^{1-\gamma} \vartheta(u) &= \frac{\Gamma(\gamma)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt + \vartheta_b \right] \\ &\quad + \frac{1}{\Gamma(p-\gamma+1)} \int_u^b \Theta_-^{p-\gamma+1}(u, t) \vartheta(t) dt. \end{aligned}$$

Since $1-\gamma < p-\gamma+1$, Theorem 2.13 can be used when taking the limit $u \rightarrow b$,

$$\mathfrak{T}_{a+}^{1-\gamma} \vartheta(b) = \frac{\Gamma(\gamma)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt + \vartheta_b \right]. \quad (21)$$

Substituting $u = \mu_i$ into (7), we have

$$\begin{aligned} \vartheta(\mu_i) &= \frac{\Theta_-^\gamma(b, \mu_i)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt + \vartheta_b \right] \\ &\quad + \frac{1}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt. \end{aligned}$$

Then, we drive

$$\begin{aligned} \sum_{i=1}^m \lambda_i \vartheta(\mu_i) &= \sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt \left[1 + \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^\gamma(b, \mu_i) \right] \\ &\quad + \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^\gamma(b, \mu_i) \vartheta_b \\ &= \frac{\Gamma(\gamma)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt \right] + \left[\frac{\Gamma(\gamma)}{\varepsilon} - 1 \right] \vartheta_b. \end{aligned}$$

which gives,

$$\sum_{i=1}^m \lambda_i \vartheta(\mu_i) + \vartheta_b = \frac{\Gamma(\gamma)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) \vartheta(t) dt + \vartheta_b \right]. \quad (22)$$

It follows (21) and (22) that

$$\mathfrak{T}_{b-}^{1-\gamma} \vartheta(b) = \sum_{i=1}^m \lambda_i \vartheta(\mu_i) + \vartheta_b.$$

This proves the initial condition 1 is verified. \square

3. Existence and uniqueness results for problem $(\mathbb{P}\tau)$

In this section, we present existence and uniqueness results for the considered problem $(\mathbb{P}\tau)$.

Theorem 3.1. Assume that the hypotheses following two (A_1) and (A_2) are fulfilled
 (A_1) Let $R : [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be a function such that $R(\cdot, \vartheta(\cdot), \vartheta(\tau)) \in C_{1-\gamma}^{\gamma(1-p)}[a, b]$,
 for any $\vartheta \in C_{1-\gamma}[a, b]$, and there exists $L > 0$ such that

$$|R(u, \vartheta_1, x_1) - R(u, \vartheta_2, x_2)| \leq L[|\vartheta_1 - \vartheta_2| + |x_1 - x_2|], \quad (23)$$

for all $u \in [a, b]$ and $\vartheta_i, x_i \in \mathbb{R} (i = 1, 2)$.

(A₂) The constant

$$\sigma := \left[\sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^{p+\gamma}(b, \mu_i) + \Theta_-^{p+1}(a, b) \right] \frac{2LB(\gamma, p)}{\Gamma(p)} < 1. \quad (24)$$

where $B(., .)$ is defined as in Definition 2.1.

The first result is based on Theorem 2.16. And so there exists at least one solution for the Hilfer problem $(\mathbb{P}\tau)$ in the space $C_{1-\gamma}^\gamma[a, b] \subset C_{1-\gamma}^{p,\gamma}[a, b]$.

Proof. We use the Krasnoselskii's fixed point theorem to prove the existence of solution ϑ in the weighted space $C_{1-\gamma}^\gamma[a, b]$. Define the operator $T : C_{1-\gamma}[a, b] \rightarrow C_{1-\gamma}[a, b]$ by

$$\begin{aligned} (Ty)(u) &= \frac{\Theta_-^\gamma(b, u)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) F_\vartheta(t) dt + \vartheta_b \right] \\ &\quad + \frac{1}{\Gamma(p)} \int_u^b \Theta_-^p(t, u) F_\vartheta(t) dt. \end{aligned} \quad (25)$$

Where $F_\vartheta(t) := R(t, \vartheta(t), \vartheta(\tau t))$.

Setting $\tilde{R}(t) = F_0(t) := R(t, 0, 0)$, and suppose the ball $\mathcal{B}_r = \{\vartheta \in C_{1-\gamma}[a, b] : \|\vartheta\|_{C_{1-\gamma}} \leq r\}$, having $r \geq \frac{w}{1-\sigma}$, $\sigma < 1$ where

$$w := \frac{B(\gamma, p)}{\Gamma(p)} \left[\sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^{p+\gamma}(b, \mu_i) + \Theta_-^{p+1}(a, b) \right] \|\tilde{R}\|_{C_{1-\gamma}} + \frac{|\vartheta_b|}{\varepsilon}.$$

First, surmise the operator T into sum two operators $T_1 + T_2$ as follows

$$\begin{aligned} T_1\vartheta(u) &= \frac{\Theta_-^\gamma(b, u)}{\varepsilon} \left[\sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) F_\vartheta(t) dt + \vartheta_b \right], \\ T_2\vartheta(u) &= \frac{1}{\Gamma(p)} \int_u^b \Theta_-^p(t, u) F_\vartheta(t) dt. \end{aligned}$$

The proof will be demonstrated by the accompanying three steps.

Step 1 : we show that $T_1\vartheta + T_2x \in \mathcal{B}_r$ for every $\vartheta, x \in \mathcal{B}_r$.

For operator T_1 , by our hypotheses, we have

$$\begin{aligned} &|\Theta_-^\gamma(b, u) T_1\vartheta(u)| \\ &\leq \frac{1}{\varepsilon} \sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) [|F_\vartheta(t) - F_0(t)| + |F_0(t)|] dt + \frac{|\vartheta_b|}{\varepsilon} \\ &\leq \frac{1}{\varepsilon} \sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) (L(|\vartheta(t)| + |\vartheta(\tau t)|) + |\tilde{R}(t)|) dt + \frac{|\vartheta_b|}{\varepsilon} \\ &\leq \frac{B(\gamma, p)}{\varepsilon} \sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \Theta_-^{p+\gamma}(b, \mu_i) (2L\|\vartheta\|_{C_{1-\gamma}} + \|\tilde{R}\|_{C_{1-\gamma}}) + \frac{|\vartheta_b|}{\varepsilon} \end{aligned}$$

hence, for every $\vartheta \in \mathcal{B}_r$, we find that

$$\|T_1\vartheta\|_{C_{1-\gamma}} \leq \frac{B(\gamma, p)}{\varepsilon} \sum_{i=1}^m \frac{\lambda_i}{\Gamma(p)} \Theta_-^{p+\gamma}(b, \mu_i) (2L\|\vartheta\|_{C_{1-\gamma}} + \|\tilde{R}\|_{C_{1-\gamma}}) + \frac{|\vartheta_b|}{\varepsilon}. \quad (26)$$

For operator T_2 , we have

$$\begin{aligned} |\Theta_-^{-\gamma}(b, u)T_2x(u)| &\leq \frac{\Theta_-^{-\gamma}(b, u)}{\Gamma(p)} \int_u^b \Theta_-^p(t, u) [|F_x(t) - F_0(t)| + |F_0(t)|] dt \\ &\leq \frac{\Theta_-^{-\gamma}(b, u)}{\Gamma(p)} \Theta_-^{p+\gamma}(b, u) B(\gamma, p) (2L \|\vartheta\|_{C_{1-\gamma}} + \|\tilde{R}\|_{C_{1-\gamma}}). \end{aligned}$$

Thus we get :

$$\|T_2x\|_{C_{1-\gamma}} \leq \frac{B(\gamma, p)}{\Gamma(p)} (2L\|\vartheta\|_{C_{1-\gamma}} + \|\tilde{R}\|_{C_{1-\gamma}}) [\Theta_-^{p+1}(b, u)]. \quad (27)$$

By Definitions of σ and r with (27) and (26), we get

$$\|T_1x + T_2\vartheta\|_{C_{1-\gamma}} \leq \|T_1\vartheta\|_{C_{1-\gamma}} + \|T_2x\|_{C_{1-\gamma}} \leq \sigma r + w \leq r.$$

This proves that $T_1\vartheta + T_2x \in \mathcal{B}_r$ for every $\vartheta, x \in \mathcal{B}_r$.

Step 2 : The operator T_1 is a contraction mapping on \mathcal{B}_r .

For any $\vartheta, x \in \mathcal{B}_r$, and for any $u \in [a, b]$, we have

$$\begin{aligned} &|\Theta_-^{-\gamma}(b, u)T_1\vartheta(u) - \Theta_-^{-\gamma}(b, u)T_1x(u)| \\ &\leq \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \frac{1}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) |F_\vartheta(t) - F_x(t)| dt \\ &\leq \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \frac{1}{\Gamma(p)} \int_{\mu_i}^b \Theta_-^p(t, \mu_i) 2L |\vartheta(t) - x(t)| dt \\ &\leq \frac{B(\gamma, p)}{\Gamma(p)} 2L \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^{p+\gamma}(b, \mu_i) \|\vartheta - x\|_{C_{1-\gamma}}. \end{aligned}$$

This yields

$$\|T_1\vartheta - T_1x\|_{C_{1-\gamma}} \leq \frac{B(\gamma, p)}{\Gamma(p)} 2L \sum_{i=1}^m \frac{\lambda_i}{\varepsilon} \Theta_-^{p+\gamma}(b, \mu_i) \|\vartheta - x\|_{C_{1-\gamma}}.$$

The operator T_1 is contraction mapping. Thus, condition (A_2) of Theorem 3.1 is satisfied.

Step 3 : The operator T_2 is completely continuous on \mathcal{B}_r .

Now, we will prove that the operator T_2 is continuous.

Now, we prove that $(T_2\mathcal{B}_r)$ is uniformly bounded. Indeed, it is enough to show that for some $r > 0$, there exists a positive constant l such that $\|T_2\vartheta\|_{C_{1-\gamma}} \leq l$.

According to step 1, for $\vartheta \in \mathcal{B}_r$, we know that

$$\|T_2\vartheta\|_{C_{1-\gamma}} \leq \left[\frac{B(\gamma, p)}{\Gamma(p)} (2L\|\vartheta\|_{C_{1-\gamma}} + \|\tilde{R}\|_{C_{1-\gamma}}) \right] [\Theta_-^{p+1}(a, b)] := l.$$

Hence, $\|T_2\vartheta\|_{C_{1-\gamma}} \leq l$. Which shows that the operator T_2 is uniformly bounded on \mathcal{B}_r . Finally, we show that $(T_2\mathcal{B}_r)$ is equicontinuous in \mathcal{B}_r .

Let $\vartheta \in \mathcal{B}_r$ and $u_1, u_2 \in [a, b]$ with $u_1 < u_2$, we have

$$\begin{aligned} & \left| \Theta_{-}^{-\gamma}(b, u_2) T_2 \vartheta(u_2) - \Theta_{-}^{-\gamma}(b, u_1) T_2 \vartheta(u_1) \right| \\ & \leq \left| \frac{\Theta_{-}^{-\gamma}(b, u_2)}{\Gamma(p)} \int_{u_2}^b \Theta_{-}^p(t, u_2) \left[\Theta_{-}^{\gamma}(b, t) \right] \max_{t \in [a, b]} \left| \Theta_{-}^{-\gamma}(b, t) F_{\vartheta}(t) \right| dt \right. \\ & \quad \left. - \frac{\Theta_{-}^{-\gamma}(b, u_1)}{\Gamma(p)} \int_{u_1}^b \Theta_{-}^p(t, u_1) \left[\Theta_{-}^{\gamma}(b, t) \right] \max_{t \in [a, b]} \left| \Theta_{-}^{-\gamma}(b, t) F_{\vartheta}(t) \right| dt \right| \\ & \leq \|F_{\vartheta}\|_{C_{1-\gamma}[a, b]} \frac{B(\gamma, p)}{\Gamma(p)} \left| \left[\Theta_{-}^{p+\gamma}(b, u_2) \right] - \left[\Theta_{-}^{p+\gamma}(b, u_1) \right] \right|. \end{aligned}$$

As $|u_2 - u_1| \rightarrow 0$, the right-hand side of the above inequality tends to zero, independent of ϑ . Thus, (T_2) is equicontinuous. Therefore, it follows by Arzela-Ascoli Theorem, that T_2 is a completely continuous operator on \mathcal{B}_r . As a consequence of Theorem 2.16, we conclude that the problem $(\mathbb{P}\tau)$ has at least one solution in $C_{1-\gamma}[a, b]$.

Finally, we show that such a solution is indeed in $C_{1-\gamma}^{\gamma}[a, b]$. By applying ${}_{RL}\mathfrak{D}_{b-}^{\gamma}$ on both sides of (7), we get

$$\begin{aligned} {}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta(u) &= {}_{RL}\mathfrak{D}_{b-}^{\gamma} \mathfrak{T}_{b-}^p \mathfrak{S}(u) = {}_{RL}\mathfrak{D}_{b-}^{\gamma-p} R(u, \vartheta(u), \vartheta(\tau u)) \\ &= {}_{RL}\mathfrak{D}_{b-}^{v(1-p), \psi} R(u, \vartheta(u), \vartheta(\tau u)). \end{aligned}$$

Since $R(\cdot, \vartheta(\cdot), \vartheta(\tau \cdot)) \in C_{1-\gamma}^{v(1-p)}[a, b]$, it follows by definition of the space $C_{1-\gamma}^{v(1-p)}[a, b]$ that ${}_{RL}\mathfrak{D}_{b-}^{\gamma} \vartheta(u) \in C_{1-\gamma}[a, b]$ which implies that $\vartheta(u) \in C_{1-\gamma}^{\gamma}[a, b]$. \square

Theorem 3.2. Assume that hypotheses (A_1) and (A_2) are fulfilled.

If $\sigma < 1$. Then, the problem $(\mathbb{P}\tau)$ has a unique solution where σ is defined as in Theorem 3.1.

Proof. For the proof of Theorem 3.2, one can adopt the same technique as we did Theorem 3.1 and easily prove that the operator $T : C_{1-\gamma}[a, b] \rightarrow C_{1-\gamma}[a, b]$ stated in equation (25) is completely continuous. In view of Theorem 3.1, we know that the fixed point of T are solutions of problem $(\mathbb{P}\tau)$. Now, we prove that T has a unique fixed point, which is a solution of problem $(\mathbb{P}\tau)$. Indeed, by hypotheses $(A_1) - (A_2)$, Proposition 2.8, then for $\vartheta, x \in C_{1-\gamma}[a, b]$, $u \in [a, b]$, we have

$$\begin{aligned} & \left| \Theta_{-}^{-\gamma}(b, u) T \vartheta(u) - \Theta_{-}^{-\gamma}(b, u) T x(u) \right| \\ & \leq \sum_{i=1}^m \frac{\lambda_i}{\mathcal{E}} \frac{1}{\Gamma(p)} \int_{\mu_i}^b \Theta_{-}^p(t, \mu_i) |F_{\vartheta}(t) - F_x(t)| dt \\ & \quad + \frac{\Theta_{-}^{-\gamma}(b, u)}{\Gamma(p)} \int_u^b \Theta_{-}^p(t, u) |F_{\vartheta}(t) - F_x(t)| dt \\ & \leq \sum_{i=1}^m \frac{\lambda_i}{\mathcal{E}} \frac{2L}{\Gamma(p)} \int_{\mu_i}^b \Theta_{-}^p(t, \mu_i) \left[\Theta_{-}^{\gamma}(b, t) \right] \left[\|\vartheta - x\|_{C_{1-\gamma}} dt \right. \\ & \quad \left. + \frac{2L \Theta_{-}^{-\gamma}(b, u)}{\Gamma(p)} \int_u^b \Theta_{-}^p(t, u) \Theta_{-}^{\gamma}(b, t) \|\vartheta - x\|_{C_{1-\gamma}} dt \right] \\ & \leq \left[\sum_{i=1}^m \frac{\lambda_i}{\mathcal{E}} \Theta_{-}^{p+\gamma}(b, \mu_i) + \left[\Theta_{-}^{p+1}(a, b) \right] \right] \frac{2LB(\gamma, p)}{\Gamma(p)} \|\vartheta - x\|_{C_{1-\gamma}}. \end{aligned}$$

This gives, $\|T\vartheta - Tx\|_{C_{1-\gamma}} \leq \sigma \|\vartheta - x\|_{C_{1-\gamma}}$.

Since $\sigma < 1$, the operator $T : C_{1-\gamma}[a, b] \rightarrow C_{1-\gamma}[a, b]$ is a contraction mapping. Hence by Banach fixed point theorem, it follows that T has a unique fixed point. which is a solution of problem $(\mathbb{P}\tau)$. This completed the proof. \square

4. An example

This section provide illustrative example of the justness and applicability of the main results. We consider the following problem of the left Hilfer fractional differential equations of the following form:

$$(\varphi) \begin{cases} {}_H\mathfrak{D}_{2-}^{\frac{3}{6}, \frac{3}{9}} \vartheta(u) = \frac{30^{-8}}{e^u} \left(\frac{|\vartheta(\tau u)|}{(30^8 + |\vartheta(u)|)} \right) + \sqrt{1989}u, & 0 < \tau < 1, u \in [1, 2], \\ \mathfrak{I}_{2-}^{1-\frac{6}{9}} \vartheta(2) = \frac{6}{15} \vartheta(\frac{6}{9}) + \vartheta_2, & \gamma = \frac{3}{6} + (\frac{3}{9} \times 1) - (\frac{3}{9} \times \frac{3}{6}) = \frac{6}{9}. \end{cases}$$

From Example, we have $a = 1$, $b = 2$, $p = 3/6$, $\nu = 3/9$, $\gamma = 6/9$, $1 - \gamma = 3/9$, $\lambda_1 = \frac{6}{15}$, $\mu_1 = \frac{6}{9}$ and ϑ_2 is a constant. Thanks to (24) under the given data, this takes the value

$$\mathcal{E} = \Gamma(\gamma) - \lambda_1 \Theta_-^\gamma(b, \mu_1) = \Gamma(\frac{6}{9}) - \frac{6}{15} (\frac{6}{9})^{\frac{-1}{3}} \approx 0.9.$$

Given the continuous function:

$$R(u, \vartheta(u), \vartheta(\tau u)) = \frac{30^{-8}}{e^u} \left(\frac{|\vartheta(\tau u)|}{(30^8 + |\vartheta(u)|)} \right) + \sqrt{1989}u.$$

For each $\vartheta, x \in \mathbb{R}^+$ and $u \in [1, 2)$, we obtain

$$|R(u, \vartheta(u), \vartheta(\tau u)) - R(u, x(u), x(\tau u))| \leq \frac{1}{30^8} [|\vartheta - x| + |\vartheta(\tau u) - x(\tau u)|]$$

The assumptions (A_1) and (A_2) in Theorem 3.1 are verified, we obtain

$$L = \frac{1}{30^8}.$$

Furthermore, by simple computations we get

$$\begin{aligned} \sigma &:= \left(\frac{\lambda_1}{\mathcal{E}} \Theta_-^{p+\gamma}(b, \mu_1) + \Theta_-^{p+1}(a, b) \right) \frac{B(\gamma, p)}{\Gamma(p)} 2L \\ &\approx \left(\frac{0.4}{0.9} \Theta_-^{\frac{3}{6} + \frac{6}{9}}(2, \frac{6}{9}) + \Theta_-^{\frac{3}{6} + 1}(1, 2) \right) \frac{B(\frac{6}{9}, \frac{3}{6})}{\Gamma(\frac{3}{6})} \times 1.5 \times 10^{-12} < 1, \end{aligned}$$

since all conditions of Theorem 3.2 are satisfied. Then the problem (φ) has a unique solution on $[1, 2)$.

Credit authorship contribution statement

Belqassim Azzouz: Conceptualization, Investigation, Methodology, Resources, Supervision, Validation, Visualization, Writing–original draft, Writing–review and editing.

The funding declaration

There are no funders to report for this submission.

Competing interests

This work does not have any conflicts of interest.

Data Availability Statement

Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

References

- [1] M. I. Abbas and M. A. Ragusa, *On the Hybrid Fractional Differential Equations with Fractional Proportional Derivatives of a Function with Respect to a Certain Function*, *Symmetry*, **13** (2) (2021).
- [2] M. G. A. Alshehri, A. Hyder, H. Budak, M. A. Barakat, *Some new improvements for fractional Hermite-Hadamard inequalities by Jensen-Mercer inequalities*, *Journal of Function Spaces*. **2024** (2024), pages 13.
- [3] R. Almeida, *A Caputo fractional derivative of a function with respect to another function*, *Commun. Nonlinear Sci. Numer. Simulat.* **44** (2017), 460–481.
- [4] M. Beddani, H. Beddani, *Compactness of boundary value problems for impulsive integro-differential equation*, *Filomat*. **37** (20) (2023), 6855–6866.
- [5] M. Beddani and B. Hedia, *Existence result for fractional differential equations on unbounded domain*, *Kragujevac J. Math.* **48** (5) (2024), 755–766.
- [6] M. Beddani and B. Hedia, *Existence result for a fractional differential equation involving a sequential derivative*, *Moroccan J. of Pure and Appl. Anal.* **8** (1) (2022), 67–77.
- [7] N. Chems Eddine, P. D. Nguyen, M. A. Ragusa, *Existence and multiplicity of solutions for a class of critical anisotropic elliptic equations of Schrodinger-Kirchhoff-type*, *Mathematical Methods in the Applied Sciences*. **46** (16) (2023), 16782–16801.
- [8] K. M. Furati, M. D. Kassim and N.e-. Tata, *Existence and uniqueness for a problem involving Hilfer fractional derivative*, *Comput. Math. Appl.* **64** (2012), 1616–1626.
- [9] H. Gu, J. J. Trujillo, *Existence of mild solution for evolution equation with Hilfer fractional derivative*, *Appl. Math. Comput.* **257** (2015), 344–354.
- [10] E. Guariglia, *Riemann zeta fractional derivative-functional equation and link with primes*, *Adv. Differ. Equ.* **2019** (1) (2019).
- [11] E. Guariglia, *Fractional Calculus of the Lerch Zeta Function*, *Adv. Differ. Equ.* **19**(1) (2022).
- [12] S. Harikrishnan, K. Kanagarajan, E. M. Elsayed *Existence and stability results for Langevin equation with Hilfer fractional derivative*, *Results Fixed Point Theory and Applications*. **2018** (20183) (2018), 10.
- [13] R. Hilfer, Y. Luchko, Z. Tomovski, *Operational method for solution of the fractional differential equations with the generalized Riemann-Liouville fractional derivatives*, *Fract. Cal. Appl. Anal.* **12** (2009), 299–318.
- [14] A. A. Kilbas, H. M. Srivastava, J. J. Trujillo, *Theory and Applications of Fractional Differential Equations*, Elsevier B. V. Amsterdam, 2006.
- [15] C. Li, X. Dao and P. Guo, *Fractional derivatives in complex planes*, *Nonlinear. Anal.* **71** (5-6) (2009), 1857–1869.
- [16] H. Lmou, K. Hilal, A. Kajouni, *Existence and uniqueness results for Hilfer Langevin fractional pantograph differential equations and inclusions*, *International Journal of Difference Equations*. **18** (1) (2023), 145–162.
- [17] S. Longhi, *Fractional Schrödinger equation in optics*, *Opt. Lett.* **40** (2015), 1117–1120.
- [18] S. Mohamed, K. Satish, P. Sandeep, *Existence of solution for Hilfer fractional differential equations with boundary value conditions*, *math. GM.* **13680** (2019), 1–17.
- [19] M. I. Nouh, E. A. B. Abed El Salam, *Analytical solution to the fractional polytropic gas spheres*, *Eur. Phys. J. Plus.* **149** (2018), 133–149.
- [20] A. Suphawat, K. Atthapol, K. Sotiries Ntouyas and J. Tariboon, *Nonlocal boundary value problems for Hilfer fractional differential equations*, *Bull. Korean. Math. Soc.* **55** (6)(2018), 1639–1657.
- [21] T. Srivastava, A. P. Singh, H. Agarwal, *Modeling the under-Aactuated mechanical system with fractional order derivative*, *Progr. Fract. Differ. Appl.* **1** (2015), 57–64.
- [22] S. G. Samako, A. A. Kilbas, Marichev, *Fractional and Derivatives, Theory and Applications*, Goden and Breach, Yverdon, 1993.
- [23] D. Vivek, K. Kanagarajan and E. Elsayed, *Some existence and stability results for Hilfer fractional implicit differential equations with nonlocal conditions*, *Mediterr. J. Math.* **15** (15) (2018).
- [24] J. Wnag and Y. Zhang, *Nonlocal initial value problems for differential equations with Hilfer fractional derivative*, *Appl. Math. Comput.* **266** (2015), 850–859.